

Psych269 Cognitive Robotics – Laboratory 6

NXT Inputs using NXC

Work through the following examples in chapter 11 and 12 of Hansen's "NXT Power Programming".

Chapter 11, page 268 – Touch sensor collision avoidance robot.

Chapter 11, page 276 – Line following robot.

Chapter 11, page 279 – Clapper robot.

Chapter 12, page 306 – Ultrasonic collision avoidance robot.