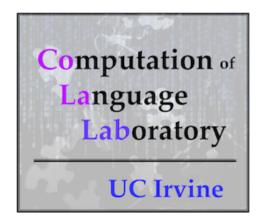
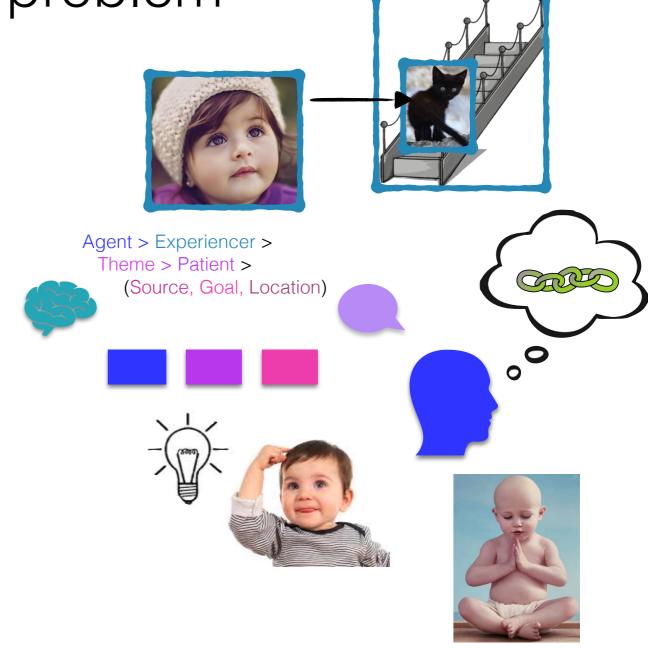
Arguments from acquisition for how to solve the linking problem

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Linguistics Colloquium
University of Maryland, College Park



The little girl blicked the kitten on the stairs.

What is this likely to mean?

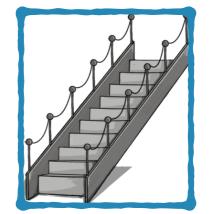
The little girl blicked the kitten on the stairs.

What is this likely to mean?

The little girl blicked the kitten on the stairs.







What is this likely to mean?

Syntactic positions

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.

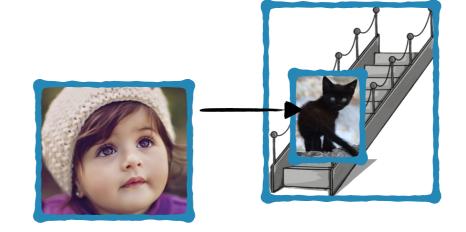








This event is much more likely...



Syntactic positions

Subject

Object

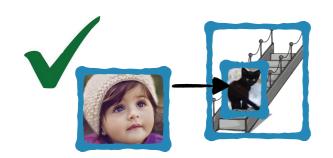
Oblique Object

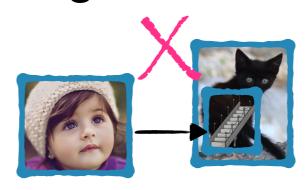
The little girl blicked the kitten on the stairs.

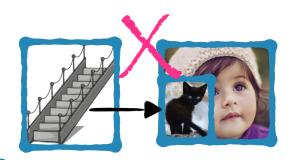




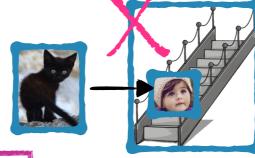








...compared to these.



Syntactic positions

Subject

Object

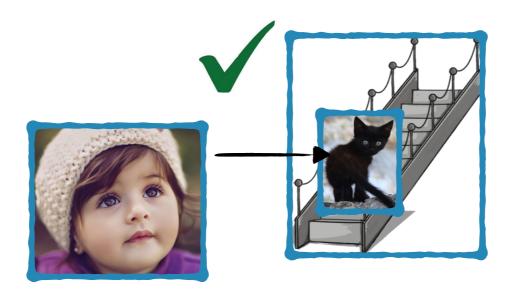
Oblique Object

The little girl blicked the kitten on the stairs.









Syntactic positions

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.



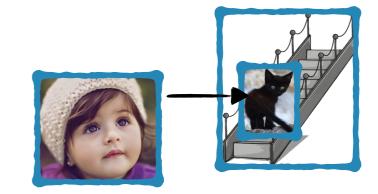
Why?







We as adults have linking theories that help us interpret verbs in combination with their arguments.



Syntactic positions

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.



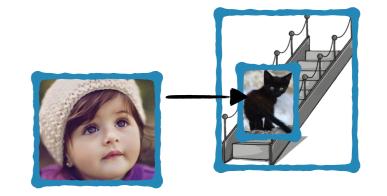






We as adults have linking theories that help us interpret verbs in combination with their arguments.

We can also use these linking theories to produce verbs in combination with their arguments when we want to express a particular meaning.



Syntactic positions

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.







These linking theories are mental representations that we as adults have developed. They let us link event participants and syntactic positions, so we know how to interpret an utterance — even when we don't know what the verb means.

Syntactic positions

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.









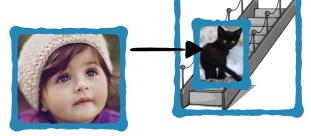
Subject

Object

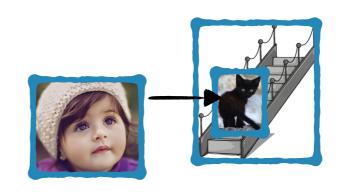
Oblique Object

The little girl blicked the kitten on the stairs.





What does a linking theory look like?



Subject

Object

Oblique Object

Syntax

The little girl blicked the kitten on the stairs.

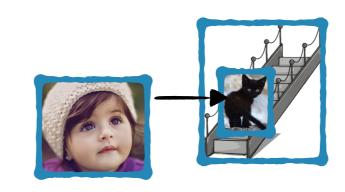


Current proposals involve prior (innate) knowledge

Event participant roles

Agent, Experiencer, Patient, Theme, Goal, Source, Location...

What does a linking theory look like?



Syntax

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.

Mapping to syntax

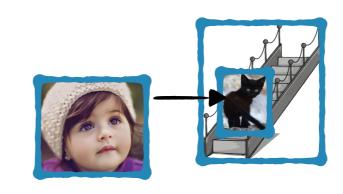


Intermediate representations

Event participant roles

Agent, Experiencer, Patient, Theme, Goal, Source, Location...

What does a linking theory look like?



Syntax

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.

Mapping to syntax



Intermediate representations

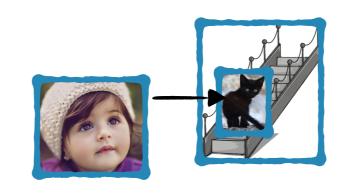
The Uniformity of Theta Assignment Hypothesis

Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990

Event participant roles

Agent, Experiencer, Patient, Theme, Goal, Source, Location...

What does a linking theory look like?



Syntax

Mapping to syntax

Intermediate representations

Subject

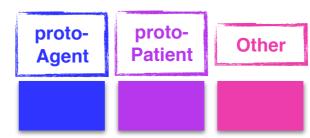
Object

The little girl blicked the kitten on the stairs.

Oblique Object

UTAH

Thematic roles map to one of three **fixed macro-roles**.

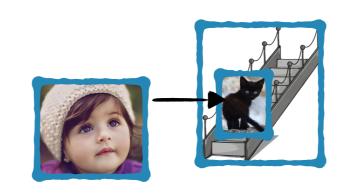


Event participant roles

Agent, Experiencer, Patient, Theme, Goal, Source, Location...

What does a linking theory look like?

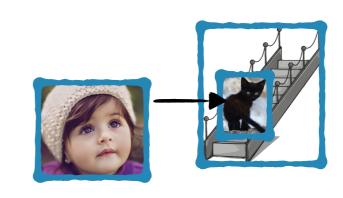
representations

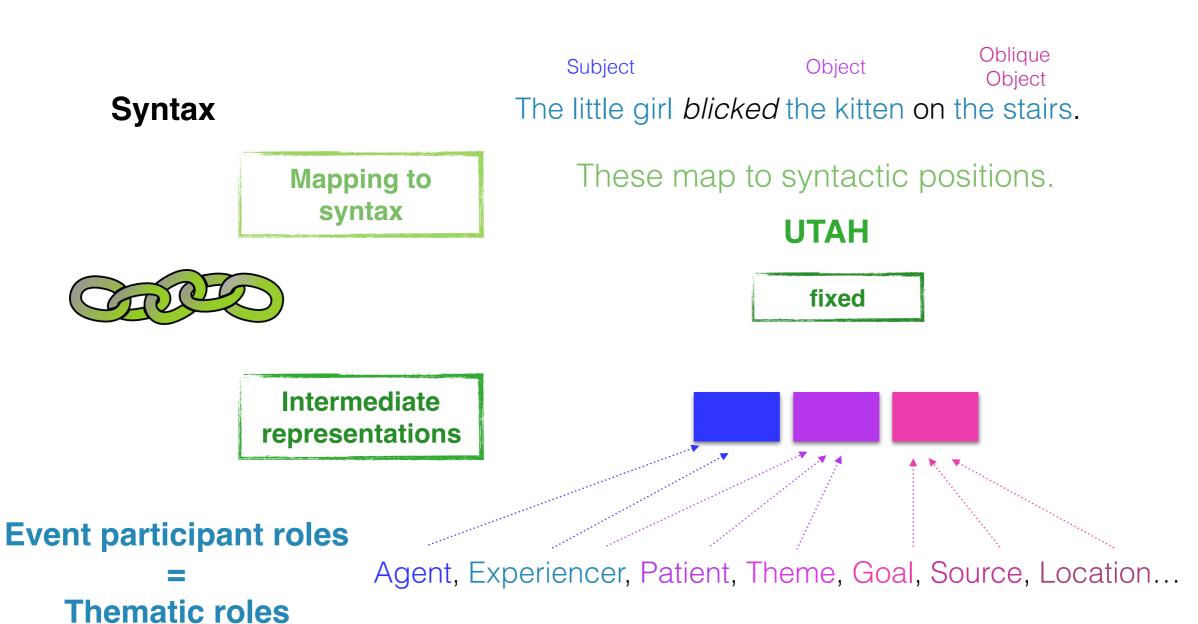


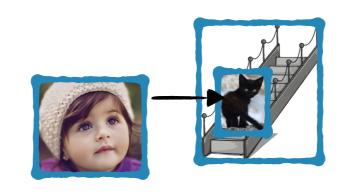
Oblique Subject Object Object **Syntax** The little girl blicked the kitten on the stairs. **Mapping to syntax UTAH** Thematic roles map to one of three fixed macro-roles. protoproto-**Other Patient Agent** Intermediate

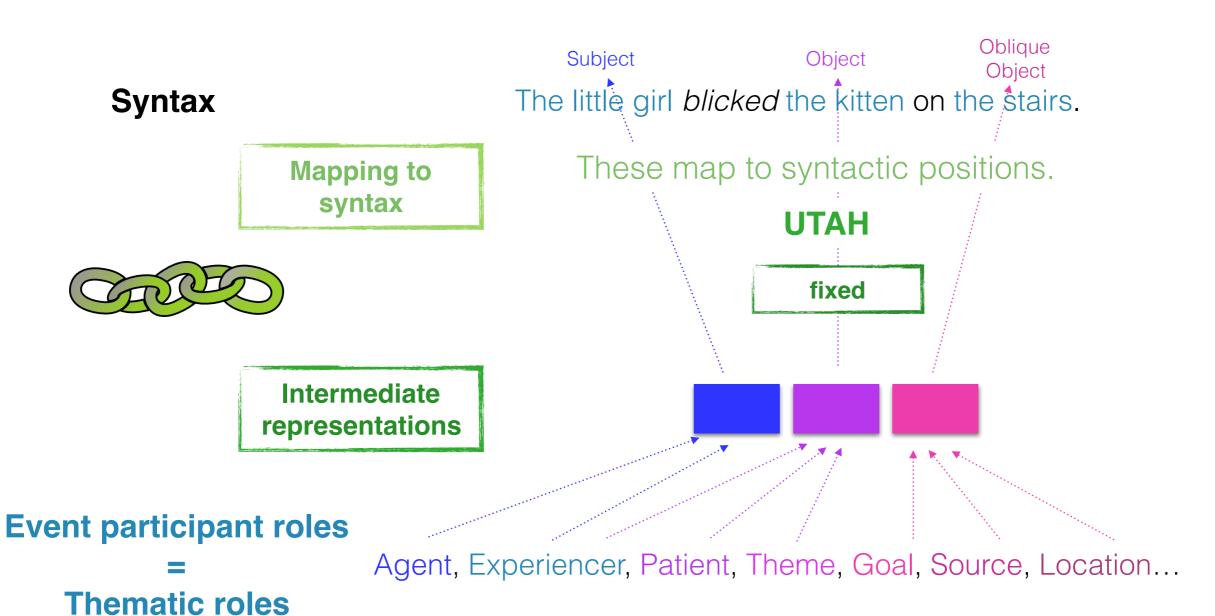
Event participant roles

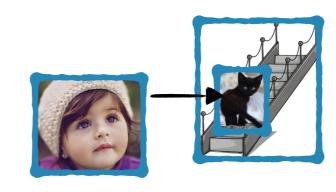
Agent, Experiencer, Patient, Theme, Goal, Source, Location...

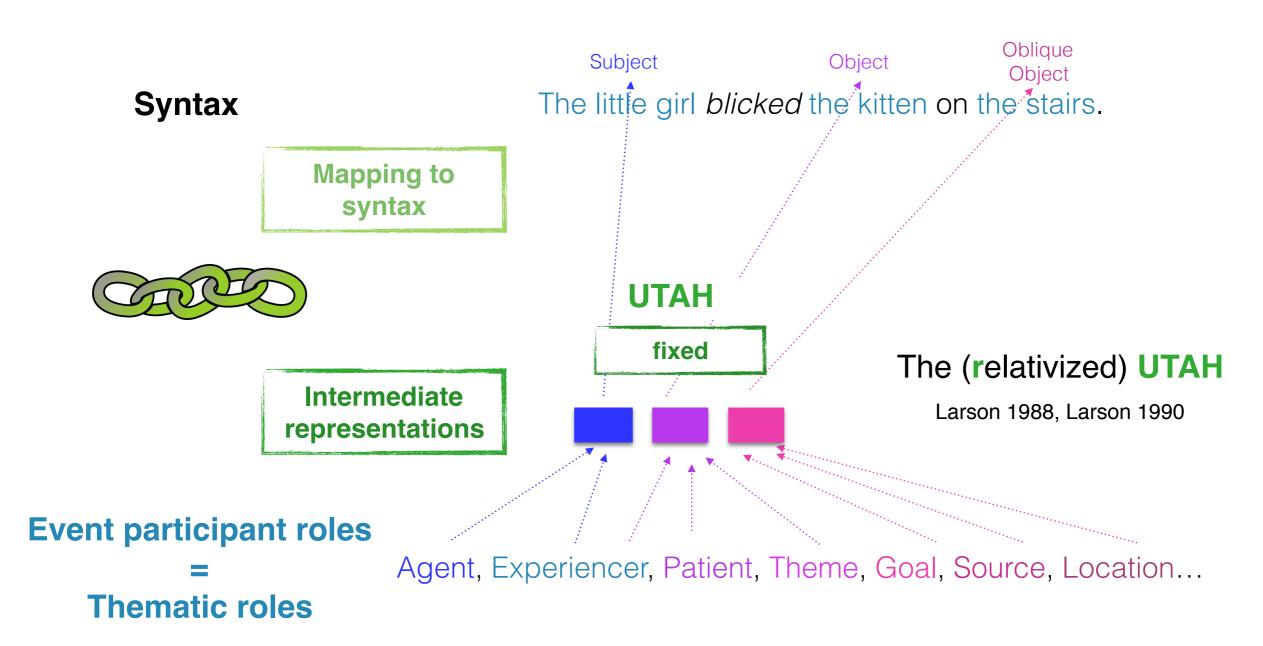


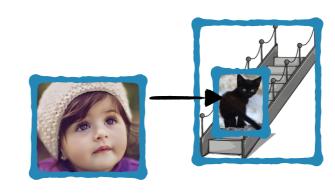


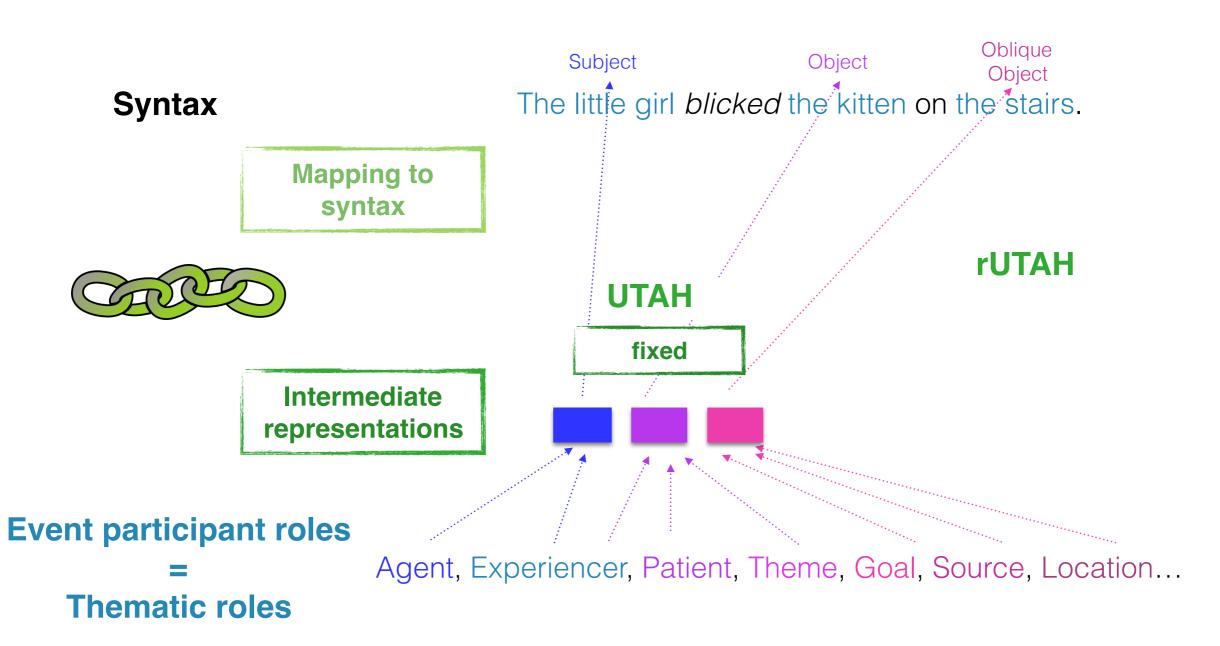


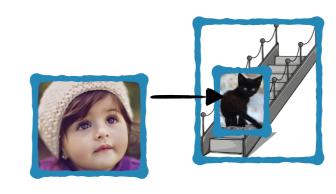


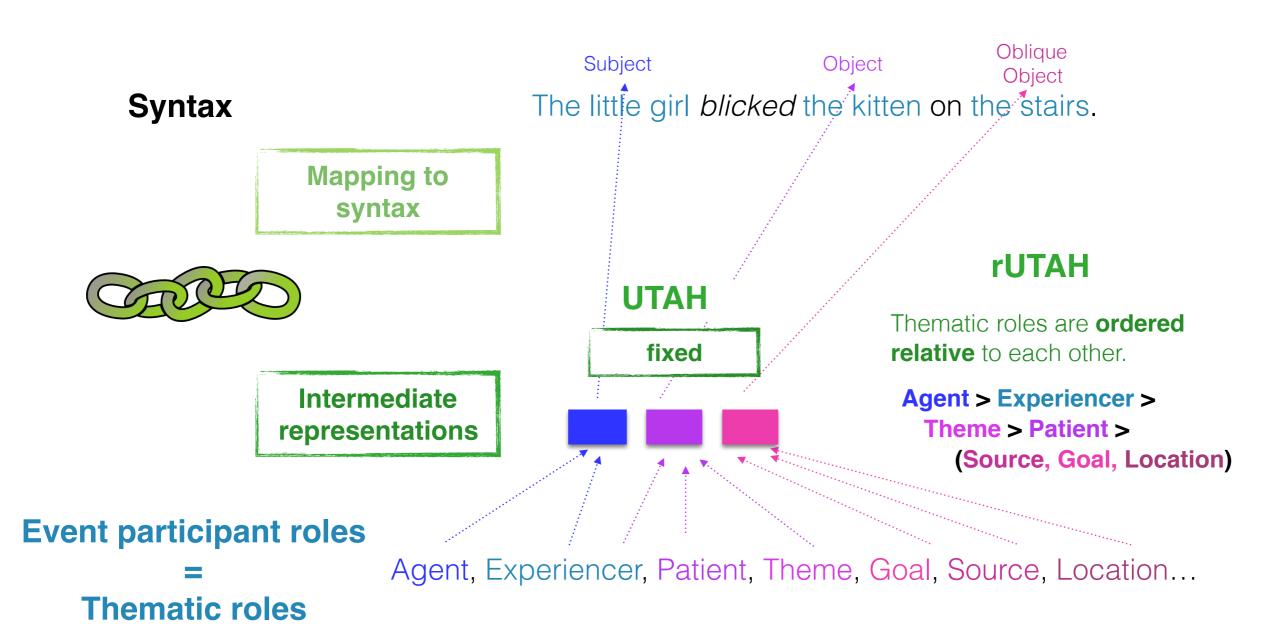


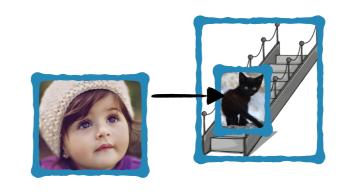


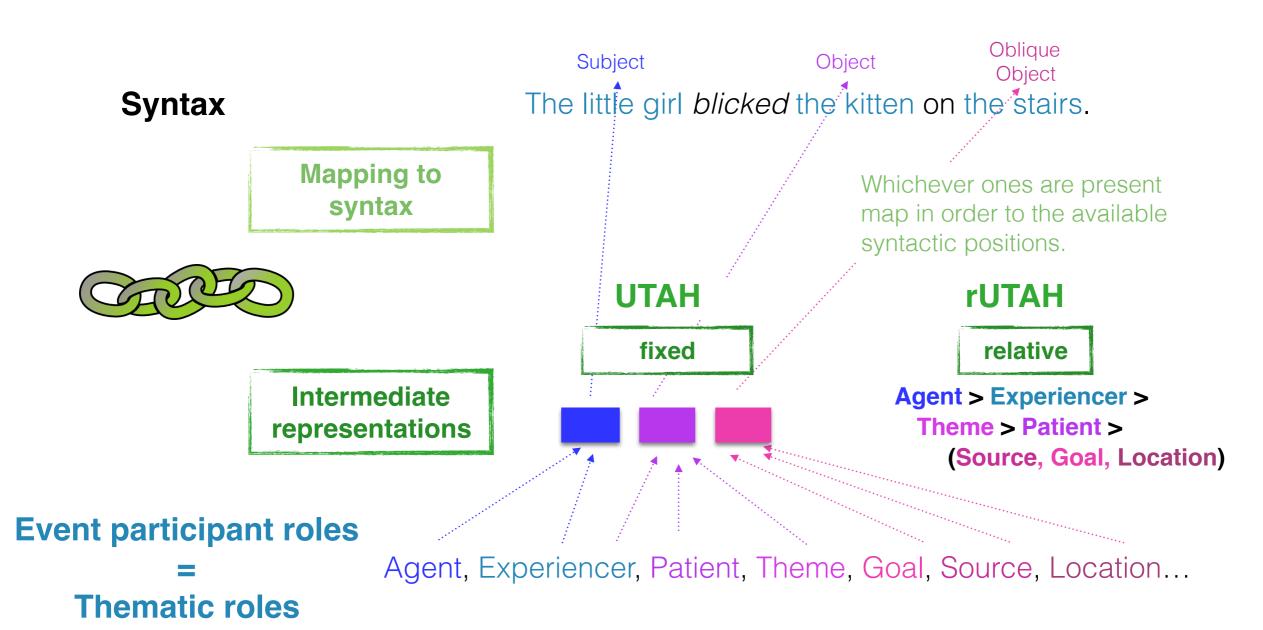


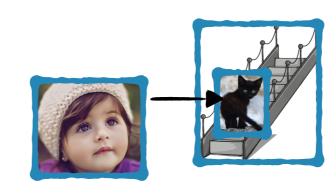


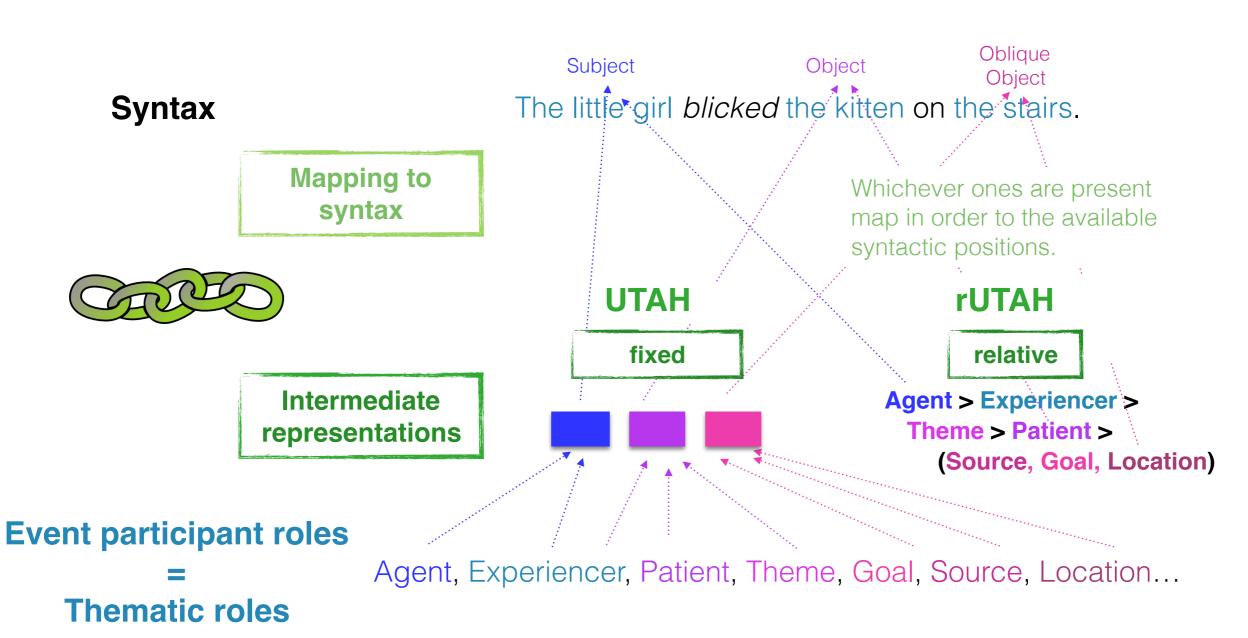






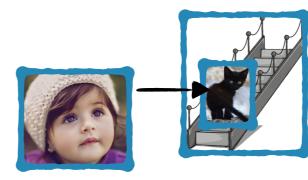


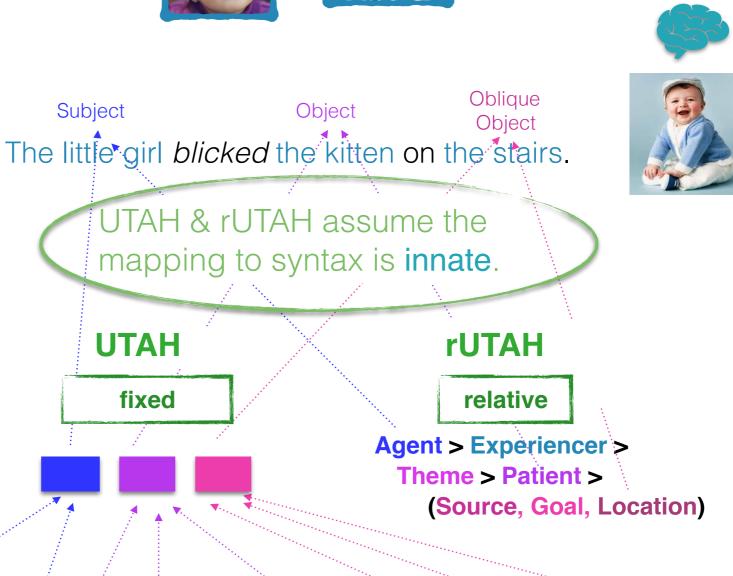




Subject

What does a linking theory look like?





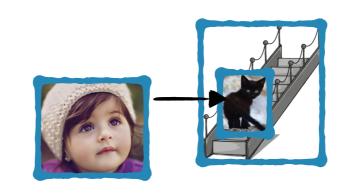
Mapping to syntax Intermediate representations

Event participant roles

Syntax

Agent, Experiencer, Patient, Theme, Goal, Source, Location...

What does a linking theory look like?



Syntax

rUTAH

UTAH

Mapping to syntax

Subject

Object

Oblique Object

The little girl blicked the kitten on the stairs.



But it could be that this mapping is derived from language experience.

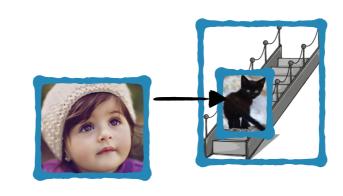
Intermediate representations fixed

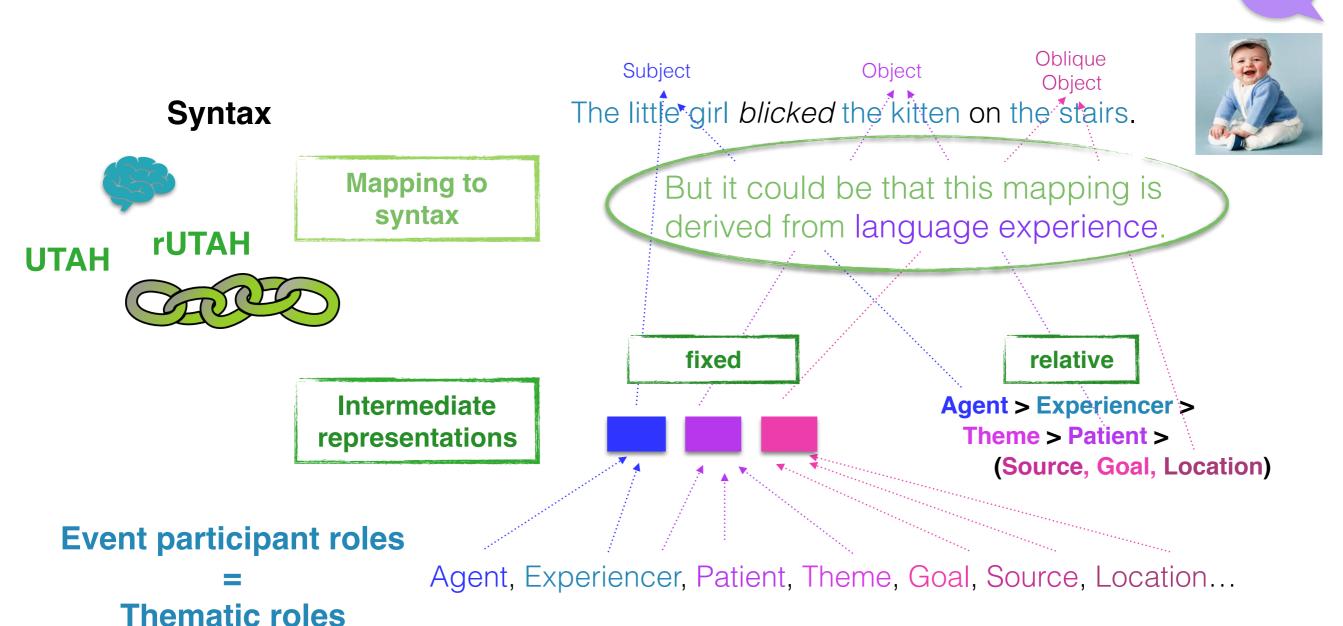
relative

Agent > Experiencer > Theme > Patient > (Source, Goal, Location)

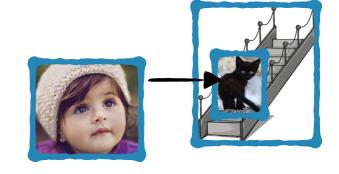
Event participant roles

Agent, Experiencer, Patient, Theme, Goal, Source, Location...



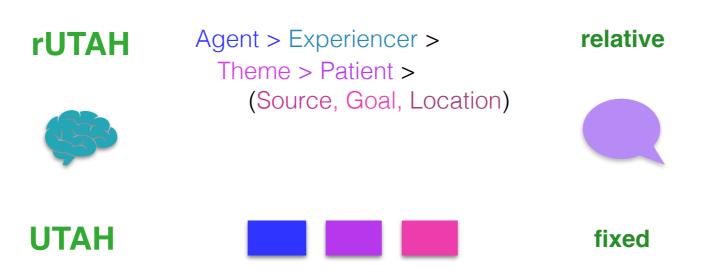


The little girl blicked the kitten on the stairs.

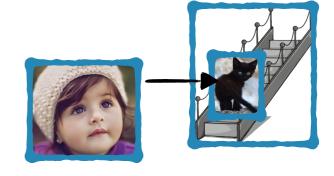


How do we tell which linking theory proposal is likely to be correct?





The little girl blicked the kitten on the stairs.



Argument from acquisition:

Which linking theory proposals are compatible with the observed development of this knowledge in children?

Pearl 2017, Pearl et al. 2017





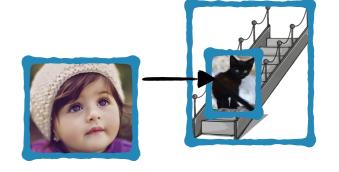
Agent > Experiencer > Theme > Patient > (Source, Goal, Location)

UTAH

Agent > Experiencer > relative

Theme > Patient > (fixed)

The little girl blicked the kitten on the stairs.



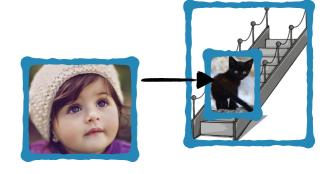
Good news: These proposals make developmental predictions.



fixed

UTAH

The little girl blicked the kitten on the stairs.





Proposals relying on innate knowledge typically assume early maturation: the knowledge is **present as early as we can test for it**.





rUTAH

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



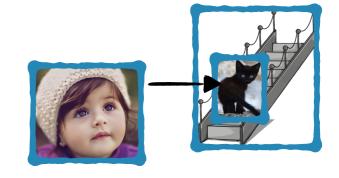






fixed

The little girl blicked the kitten on the stairs.





Implication: A modeled learner who has knowledge of the mapping to syntax should always match real children's behavior best.





rUTAH

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



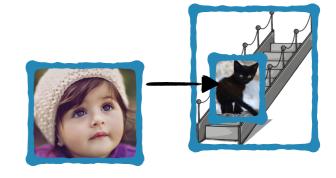






fixed

The little girl blicked the kitten on the stairs.



Proposals relying on derived knowledge typically assume it **takes some time** for children to derive the knowledge from their input.





Theme > Patient > (Source, Goal, Location)

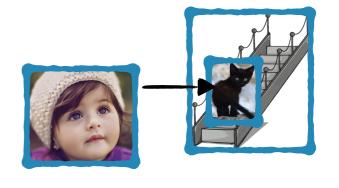
UTAH

Agent > Experiencer > relative

Theme > Patient > (Source, Goal, Location)

The little girl blicked the kitten on the stairs.

Implication: A modeled learner who has knowledge of the mapping to syntax should *not* always match real children's behavior best.



A modeled learner *without* this knowledge should match younger children best.



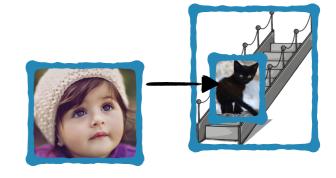


Theme > Patient >
(Source, Goal, Location)

UTAH

Agent > Experiencer >
relative
relative

The little girl blicked the kitten on the stairs.



The same evaluation can be done for modeled learners who use a fixed thematic system vs. a relative thematic system. Which ones match real children's behavior best?





rUTAH

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)





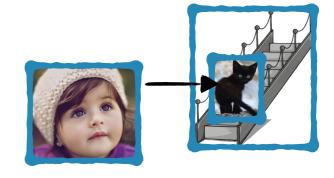


UTAH



fixed

The little girl blicked the kitten on the stairs.



So what behavior should we look at that would leverage linking theory knowledge?







Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



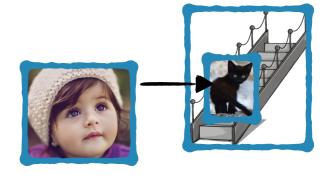






fixed

The little girl blicked the kitten on the stairs.



One answer: The development of **verb classes** — how children cluster verbs together in order to generalize about verb linguistic behavior.





rUTAH

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)





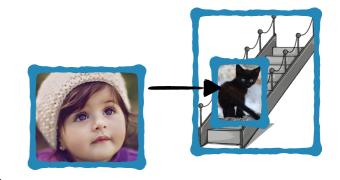






fixed

The little girl blicked the kitten on the stairs.

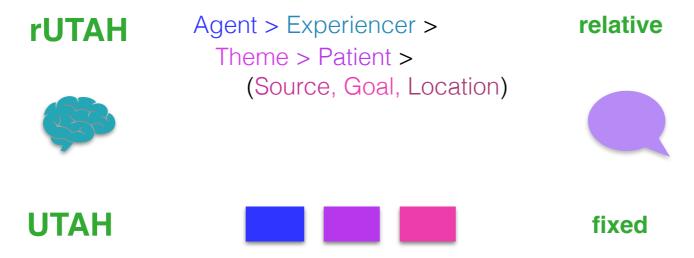


Why **verb classes**? Linking theories are precisely about one key aspect of verb behavior: how verb arguments are interpreted.

So, linking theory knowledge could affect how children cluster verbs together into verb classes.











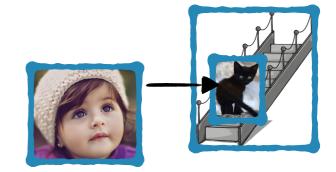




fixed

Linking theories

How does linking knowledge affect verb clustering in children?



Subject

Oblique Object

The kitten was blicked by the little girl.



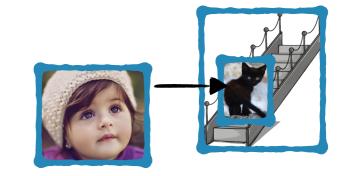


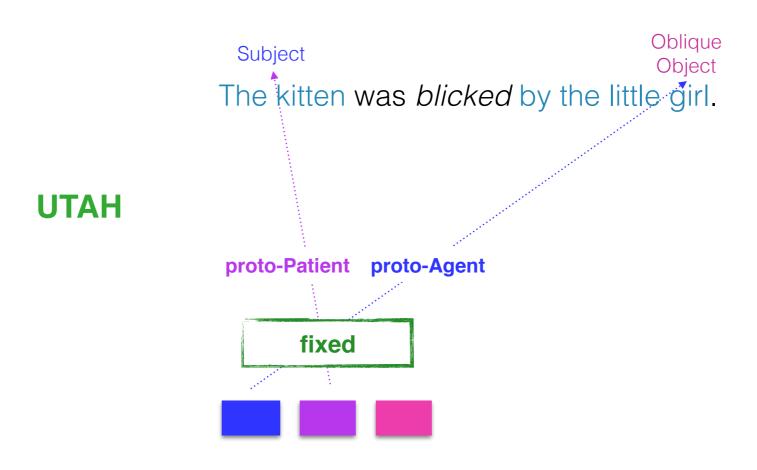


fixed

Linking theories

How does linking knowledge affect verb clustering in children?



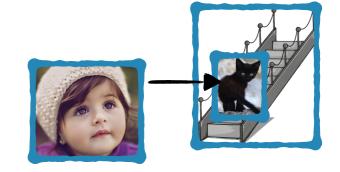






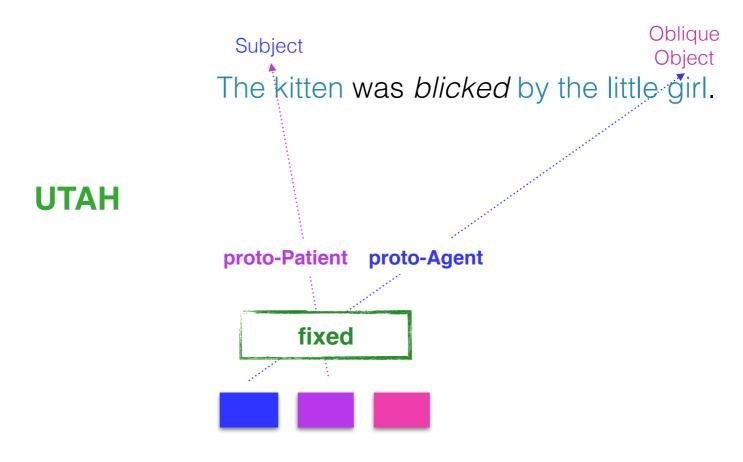


How does linking knowledge affect verb clustering in children?



If children expect a mapping already, it's salient when the mapping doesn't hold.

Interpretation: movement, which is used to cluster verbs.







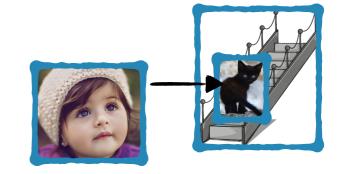




fixed

Linking theories

How does linking knowledge affect verb clustering in children?



Oblique

Object

blick: 2 movement

If children expect a mapping already, it's salient when the mapping doesn't hold.

Interpretation: movement, which is used to cluster verbs.



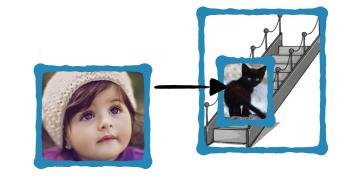








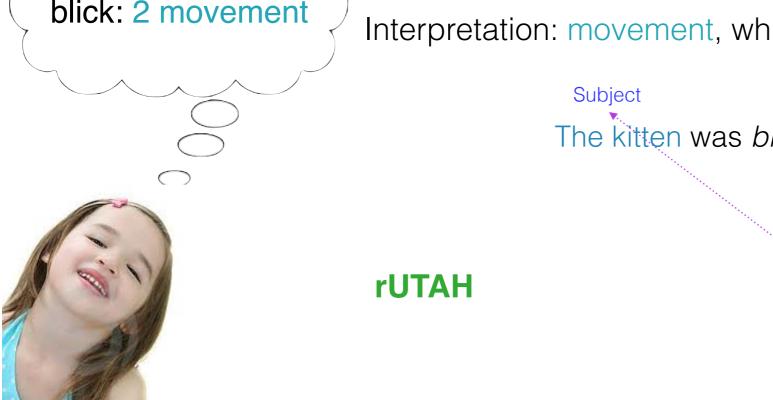
How does linking knowledge affect verb clustering in children?



blick: 2 movement

If children expect a mapping already, it's salient when the mapping doesn't hold.

Interpretation: movement, which is used to cluster verbs.



The kitten was blicked by the little girl. **2nd-Highest Highest** relative **Agent > Experiencer >** Theme > Patient > (Source, Goal, Location)

Oblique

Object

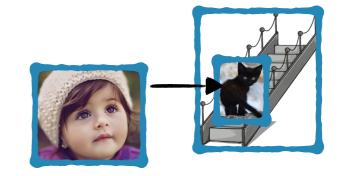


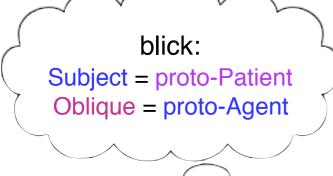






How does linking knowledge affect verb clustering in children?

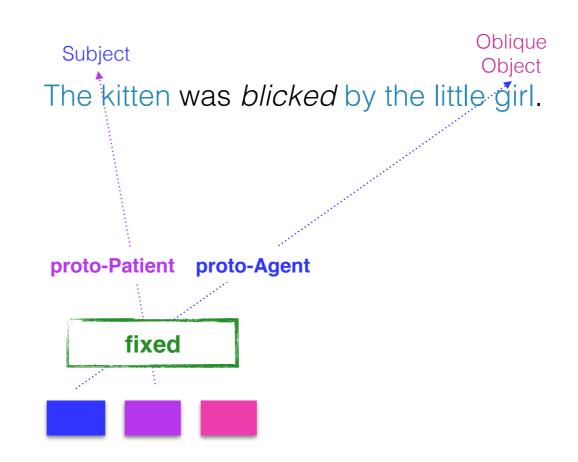




If children don't expect a mapping already, they may track the details of where certain thematic representations appear and use that to cluster verbs.



fixed

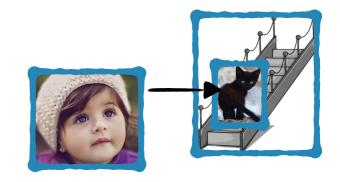








How does linking knowledge affect verb clustering in children?



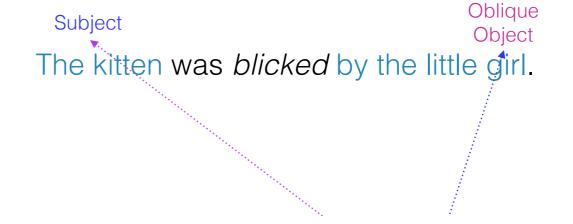


Subject/Highest-Syn = 2nd-Highest Oblique/2nd-Highest-Syn = Highest



relative

If children don't expect a mapping already, they may track the details of where certain thematic representations appear and use that to cluster verbs.



2nd-Highest

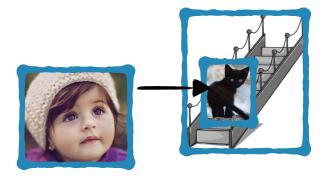
Agent > Experiencer > Theme > Patient >

relative

Highest

(Source, Goal, Location)

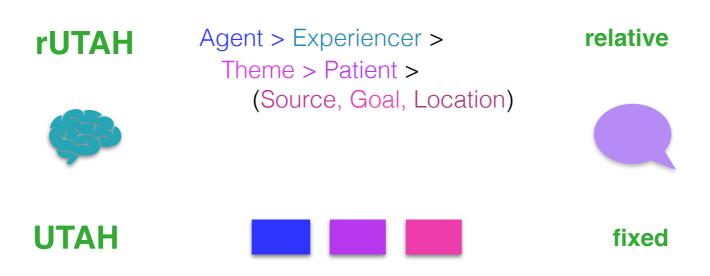
The little girl blicked the kitten on the stairs.



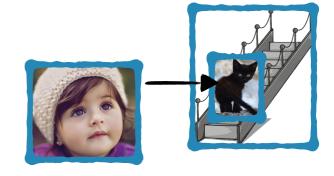
Strong empirical foundation:

We have a lot of empirical data about the development of **verb classes**: experimental studies of children's behavior (output of acquisition) and corpus studies of their input.





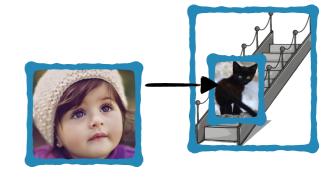
The little girl blicked the kitten on the stairs.



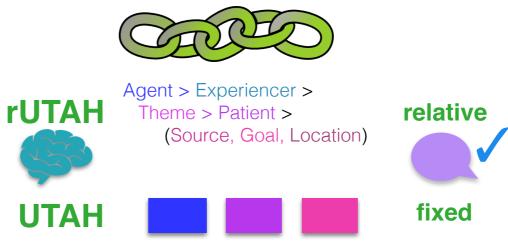
1. Evaluating different linking theory proposals using acquisition modeling



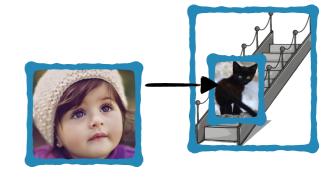
The little girl blicked the kitten on the stairs.



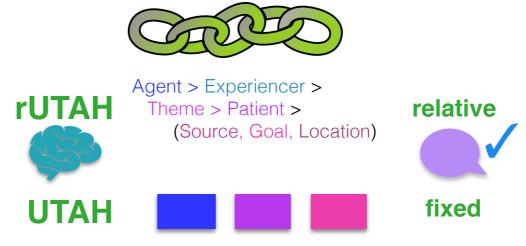
1. Evaluating different linking theory proposals using acquisition modeling



The little girl blicked the kitten on the stairs.



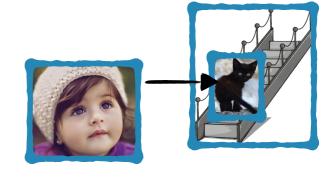
1. Evaluating different linking theory proposals using acquisition modeling



2. Exploring how a linking theory could be derived from children's input



The little girl blicked the kitten on the stairs.



1. Evaluating different linking theory proposals using acquisition modeling



2. Exploring how a linking theory could be derived from children's input





Goal:

Build a modeled learner who learns close enough to how real children learn to tell us something informative about these linking theory proposals



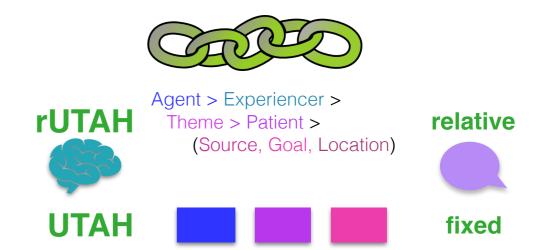


Goal:

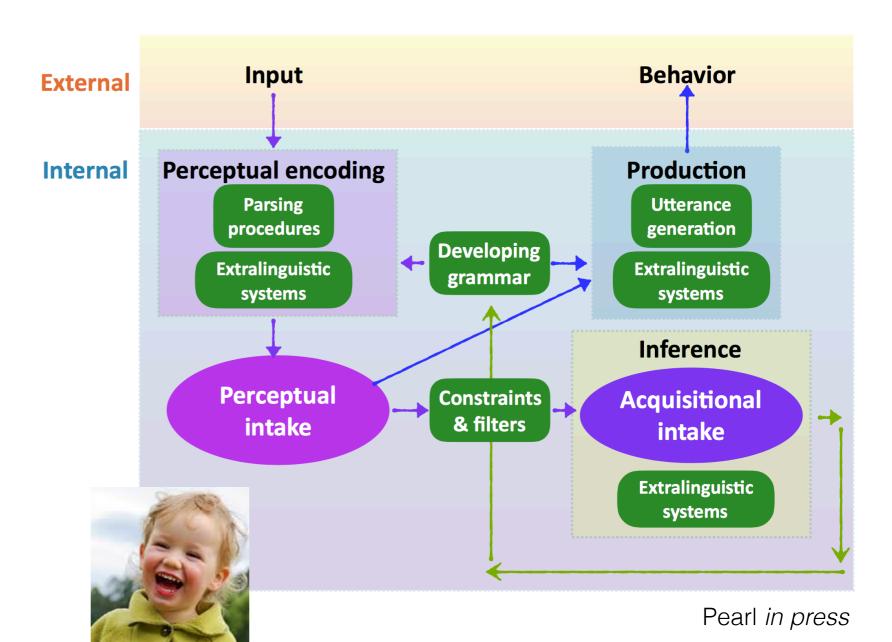
Build a modeled learner who learns close enough to how real children learn to tell us something informative about these linking theory proposals

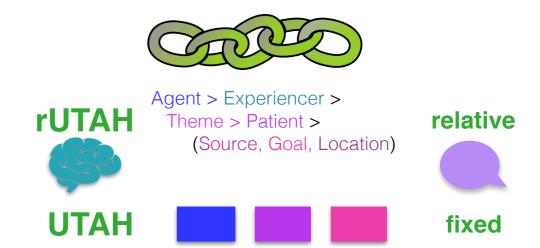


What's close enough?



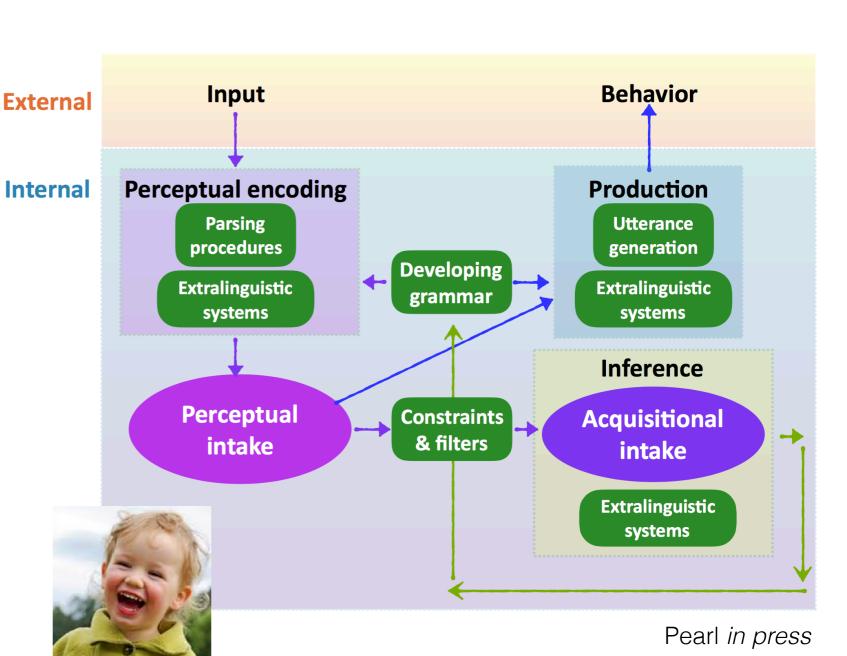
Close enough to this process





Close enough to this process

...which has a lot going on. It can be helpful when acquisition modeling to think about five main parts.





five main parts

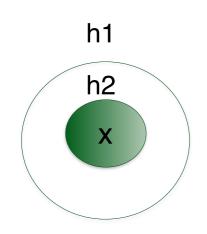
initial state

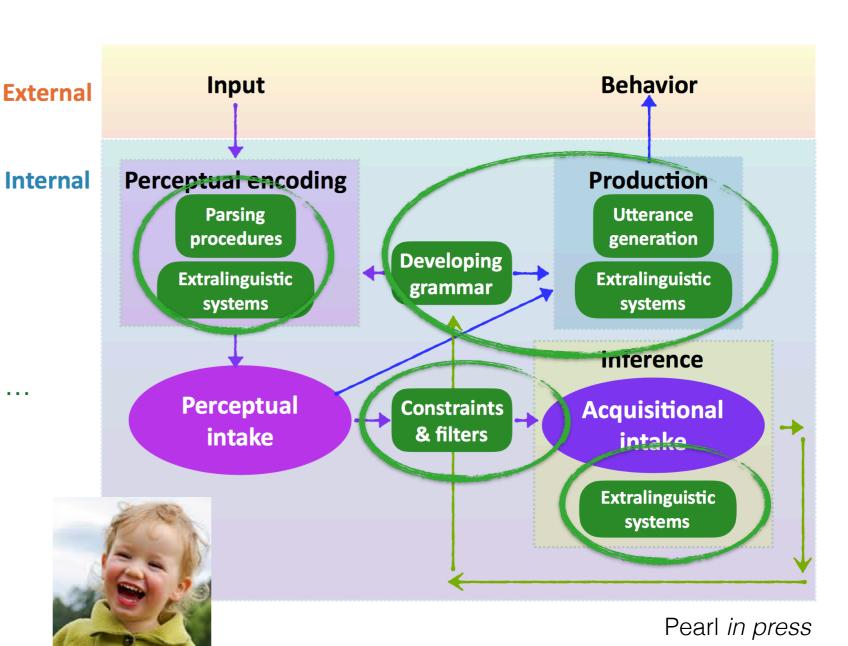
What does the child **start with**? What knowledge, abilities, and learning biases does the child already have?

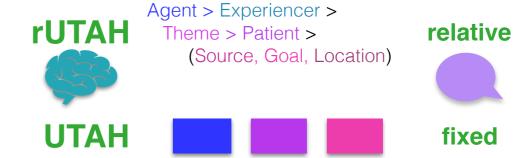


N, V, Adj, P, ...

Agent, Patient, Goal, ...







five main parts

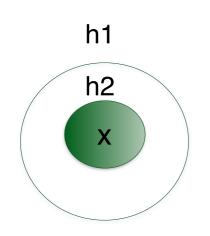
initial state

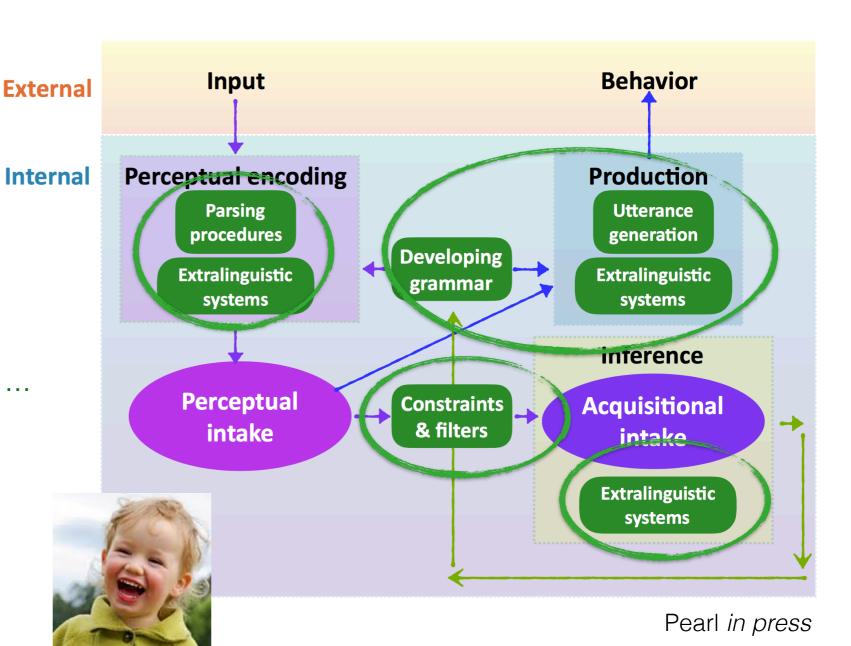
What does the child **start with**? What knowledge, abilities, and learning biases does the child already have?

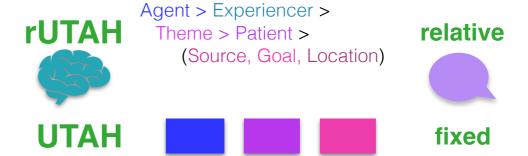


N, V, Adj, P, ...

Agent, Patient, Goal, ...







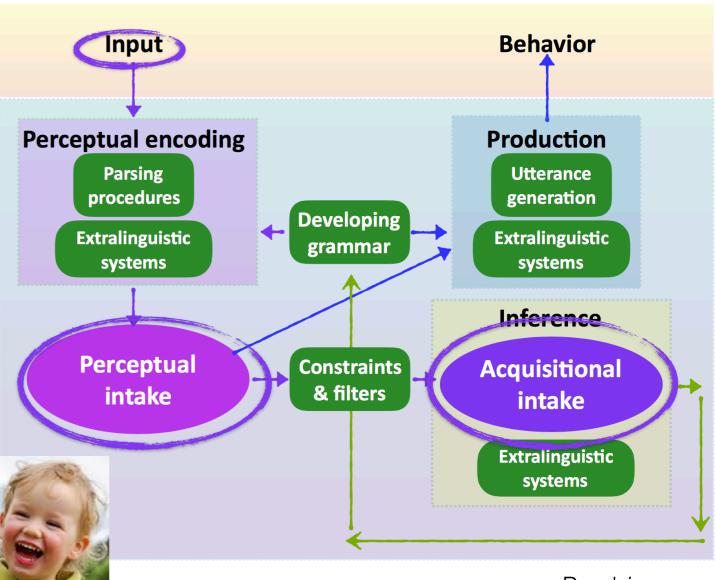
five main parts

initial state

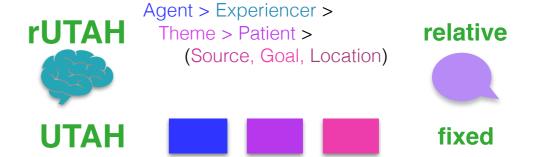
data intake

How does the modeled child perceive the input (= perceptual intake)? What part of the perceived data is used for acquisition (= acquisitional intake)? **External**

Internal



Pearl in press



Behavior

Production

Utterance

generation

Extralinguistic

systems

Inference

five main parts

initial state

data intake

How does the modeled child perceive the input (= perceptual intake)? What part of the perceived data is used for acquisition (= acquisitional intake)?



The kitten was blicked by the little girl.

External

Internal

Perceptual encoding Parsing

> procedures **Extralinguistic**

> > systems

Input

Perceptual

intake

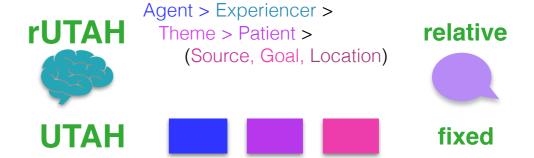
Constraints Acquisitional & filters intake **Extralinguistic**



Developing

grammar

Pearl in press



five main parts

initial state

data intake

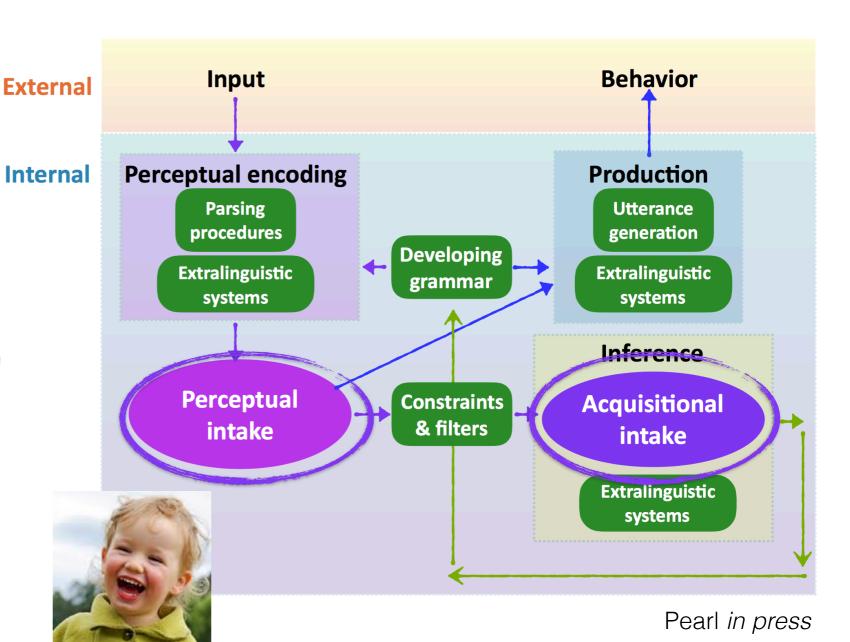
How does the modeled child perceive the input (= perceptual intake)? What part of the perceived data is used for acquisition (= acquisitional intake)?

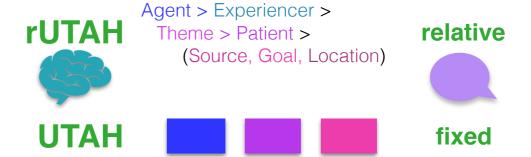


The kitten was *blicked* by the little girl.









five main parts

initial state

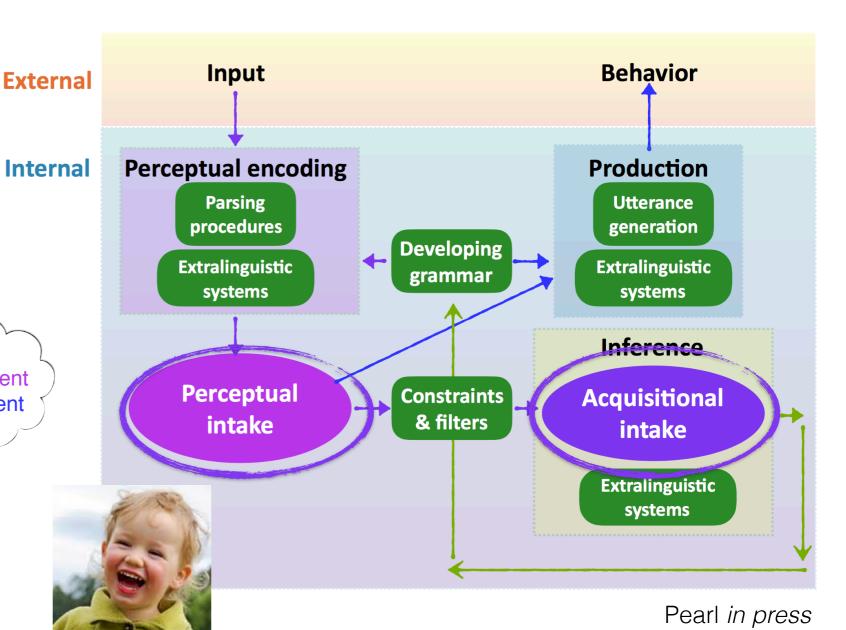
data intake How does the modeled child perceive the input (= perceptual intake)? What

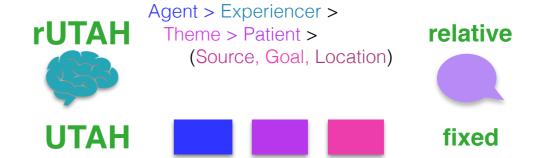
part of the perceptual intake)? What part of the perceived data is used for acquisition (= acquisitional intake)?



The kitten was *blicked* by the little girl.







five main parts

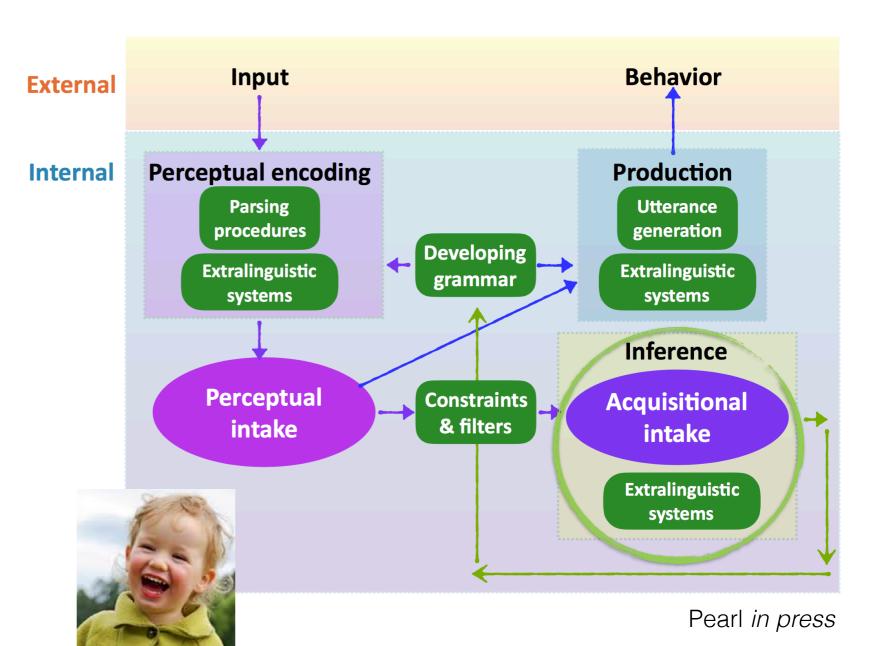




inference

How are updates made to the modeled child's internal representations?







five main parts



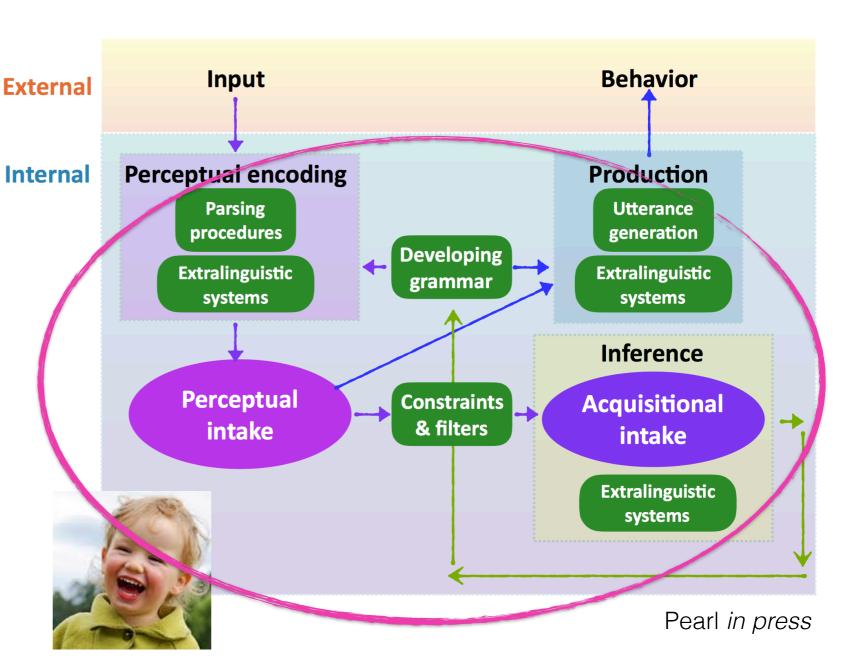
learning period

How long does the child have to learn?



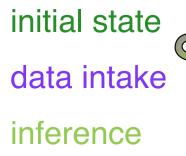
ex: 3 years, ~1,000,000 data points

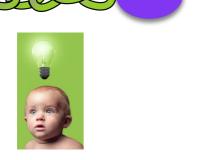
ex: 4 months, ~36,500 data points





five main parts







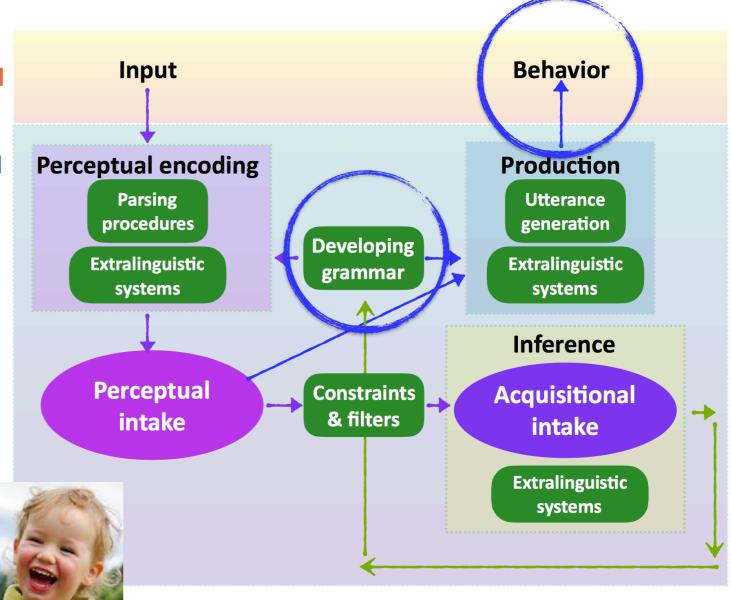
External

Internal

target state

learning period

What does successful acquisition look like? What knowledge is the child trying to attain (often assessed in terms of observable behavior)?



Pearl in press



five main parts

initial state

data intake

inference



learning period

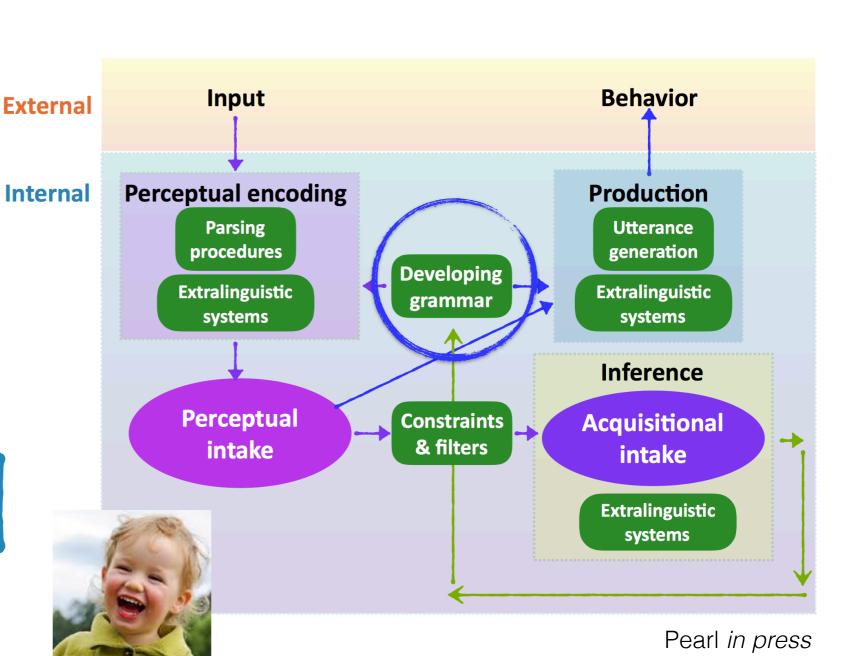


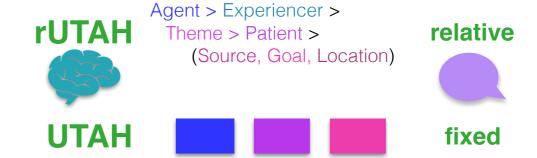
target state

What does successful acquisition look like? What **knowledge** is the child trying to attain (often assessed in terms of observable behavior)?

The little girl kissed the kitten on the stairs.







five main parts

initial state

data intake

inference



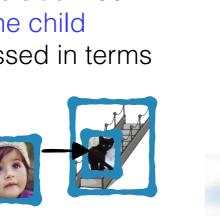


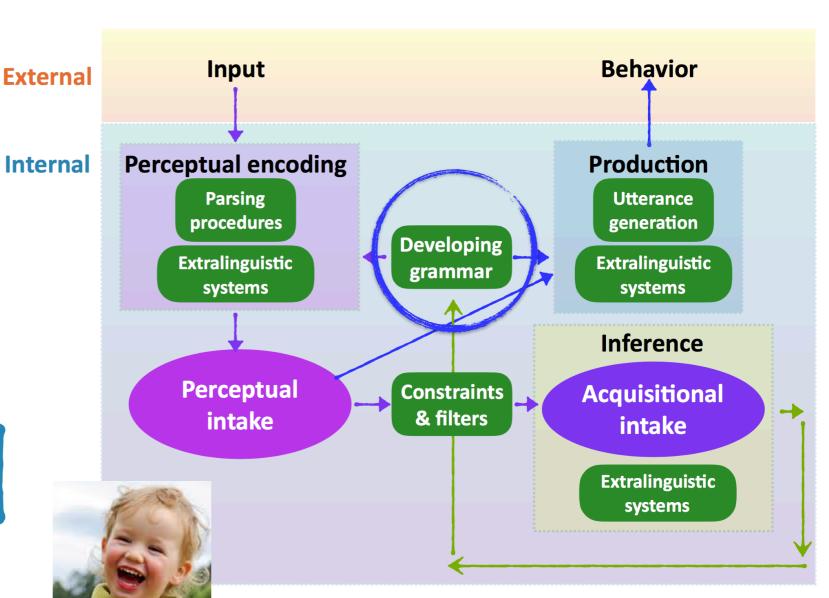


target state

What does successful acquisition look like? What **knowledge** is the child trying to attain (often assessed in terms of observable behavior)?

pet kiss hug





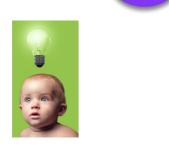
Pearl in press



five main parts

initial state data intake

inference







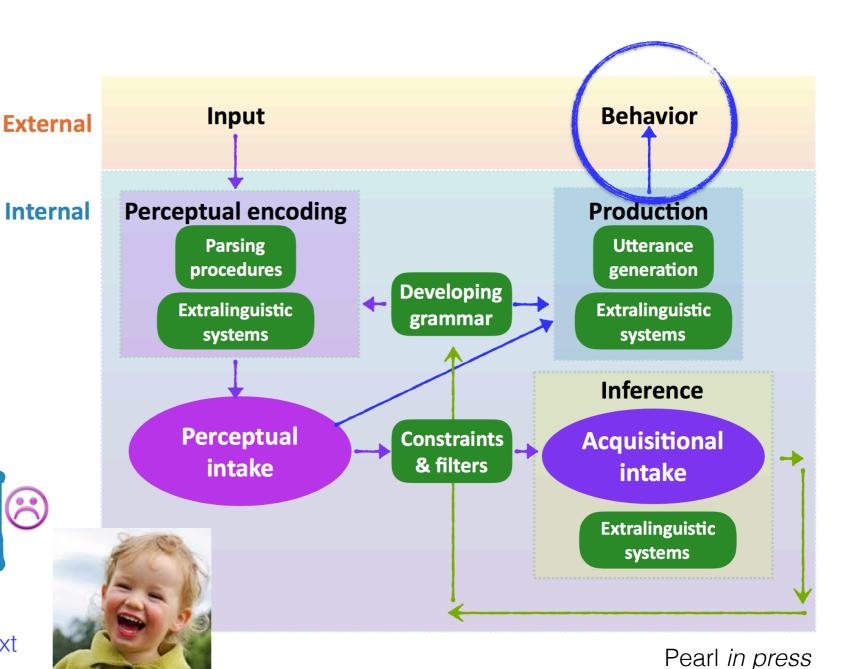
target state

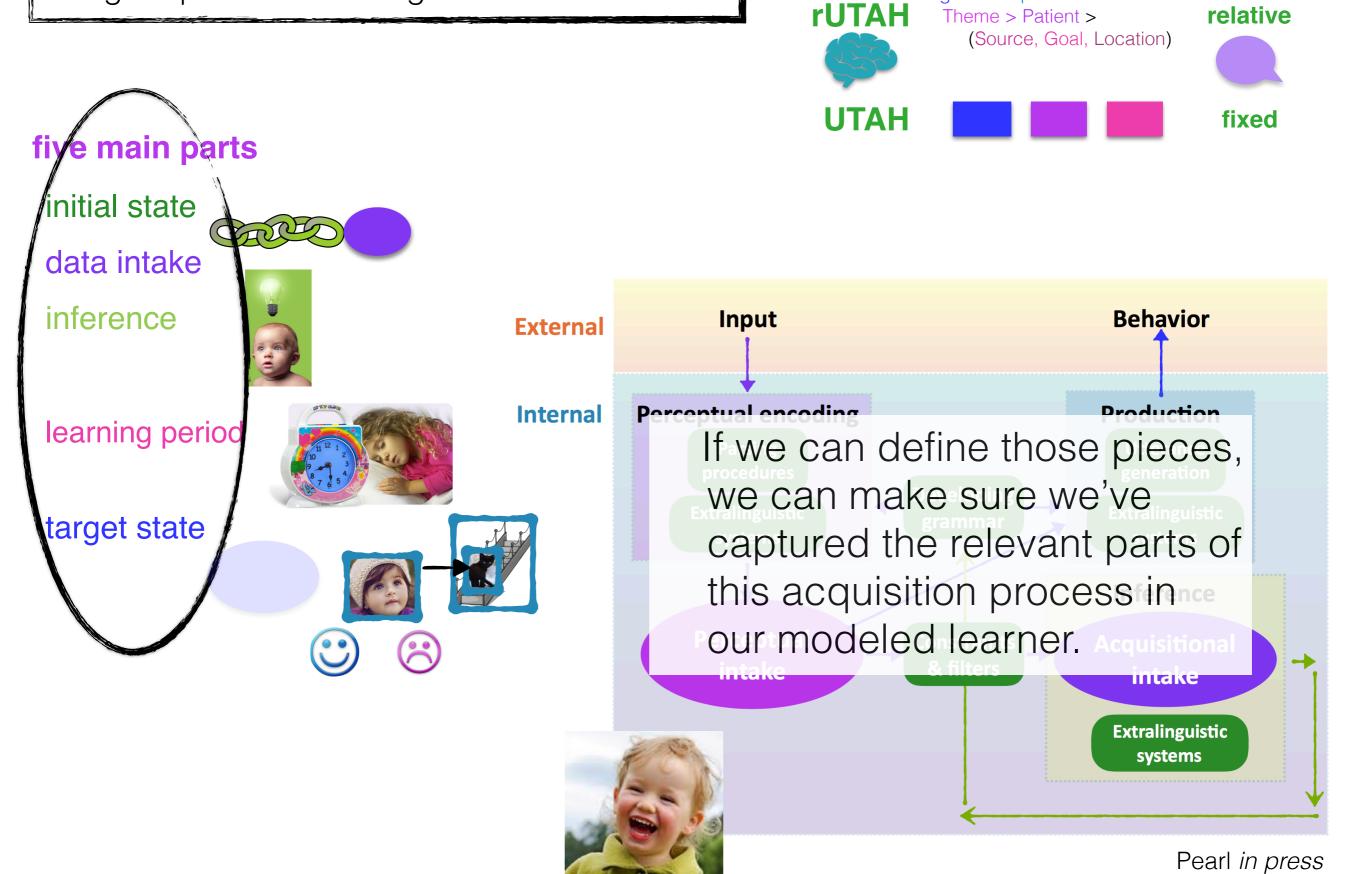
What does successful acquisition look like? What knowledge is the child trying to attain (often assessed in terms of observable behavior)?

pet kiss hug

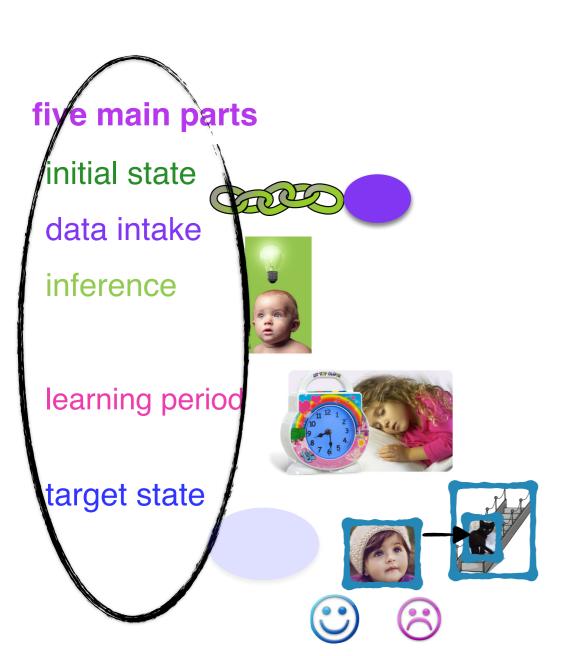


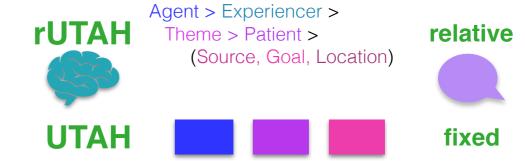
interpretations or productions in context





Agent > Experiencer >





So let's do this for modeled learners who implement different linking theory proposals.





Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



fixed



Goal: Model the developmental trajectory of verb class knowledge from 3 to 4 to 5 years old in English







data intake inference target state

learning period

initial state





Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)









data intake

inference learning period

target state

initial state





Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)









Thematic roles that indicate event participant roles are salient to very young children. (<10 months: Gordon 2003; 6 months: Hamlin, Wynn, & Bloom 2007, Hamlin, Wynn, Bloom, & Mahajan 2011)



data intake

inference learning period target state

initial state





Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



Thematic roles that indicate event participant roles are salient to very young children. (<10 months: Gordon 2003; 6 months: Hamlin, Wynn, & Bloom 2007, Hamlin, Wynn, Bloom, & Mahajan 2011)

Cognitively plausible



data intake

inference learning period target state

initial state



rUTAH

UTAH

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)





fixed

Children are also sensitive to the animacy of verb arguments.

Becker 2009, Kirby 2009, Kirby 2010, Becker 2014, Becker 2015, Hartshorne et al. 2015, among others

The little girl blicked the kitten on the stairs.







+animate



-animate



data intake

inference learning period target state

initial state





UTAH

Theme > Patient > (Source, Goal, Location)





fixed

Agent > Experiencer >









+animate

-animate

Children pay attention to the linguistic context of a verb (its syntactic frame) to figure out how it behaves (e.g., Fisher et al. 2010, Gutman et al. 2015, Harrigan et al. 2016).

The little girl blicked the kitten on the stairs.



data intake

inference learning period

target state

initial state





Agent > Experiencer > Theme > Patient > (Source, Goal, Location)





fixed



UTAH













+animate



-animate

Children pay attention to the linguistic context of a verb (its syntactic frame) to figure out how it behaves (e.g., Fisher et al. 2010, Gutman et al. 2015, Harrigan et al. 2016).

The little girl blicked the kitten on the stairs.

NP



NP

PP



data intake

inference learning period target state

initial state





UTAH

Agent > Experiencer > Theme > Patient > (Source, Goal, Location)













+ whatever statistical learning abilities are required to do inference (Saffran et al. 1996, Gerken 2006, Mintz 2006, Xu & Tenenbaum 2007, Smith & Yu 2008)





+animate

-animate



initial state

inference learning period target state

input that yields data intake







The little girl blicked the kitten on the stairs.

Samples of child-directed speech

CHILDES Treebank

Pearl & Sprouse 2013



<3yrs

18 and 32 months ~40,000 utterances 239 verbs



<4yrs

18 and 48 months ~51,000 utterances 267 verbs



<5yrs

18 and 58 months ~56,500 utterances 284 verbs

initial state inference target state learning period

data intake

The little girl blicked the kitten on the stairs.

NP ___ NP PP

syntactic frame



initial state inference target state learning period

data intake

The little girl blicked the kitten on the stairs.

NP ___ NP PP

NP ___ NP PP -surface morphology

NP ____+past NP PP +surface morphology

syntactic frame

Children may either ignore verb surface morphology (like the past tense marker -ed) or pay attention to it when encoding the syntactic frame information.



initial state inference target state learning period

data intake







+animate +animate -animate
The little girl *blicked* the kitten on the stairs.

NP ___ NP PP -surface morphology

NP _____+past NP PP +surface morphology



initial state inference target state learning period

data intake













+animate

+animate

-animate

The little girl blicked the kitten on the stairs.

NP ___ NP PP -surface morphology

NP ____+past NP PP

+surface morphology



+expect-mapping

initial state inference target state learning period

data intake







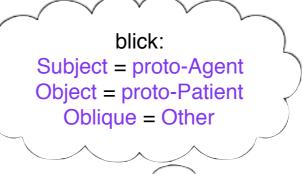






+animate +animate -animateThe little girl *blicked* the kitten on the stairs.

NP ____+past NP PP +surface morphology



-expect-mapping



initial state

inference learning period

target state

data intake













+animate

+animate

-animate

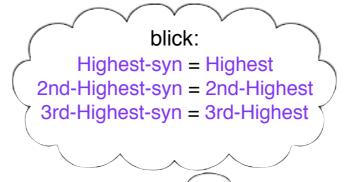
The little girl blicked the kitten on the stairs.

NP ___ NP PP

-surface morphology

NP ____+past NP PP

+surface morphology



-expect-mapping



initial state data intake target state

inference learning period

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?



initial state data intake target state

inference

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

learning period

Ideal learner model: not concerned with the cognitive limitations and incremental learning restrictions children have.

Concerned with what assumptions are useful for children to have.





initial state data intake target state

inference

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

learning period

Ideal learner model: not concerned with the cognitive limitations and incremental learning restrictions children have.

Concerned with what assumptions are useful for children to have.

It's good to do this before we start worrying if the assumptions are useable by children.





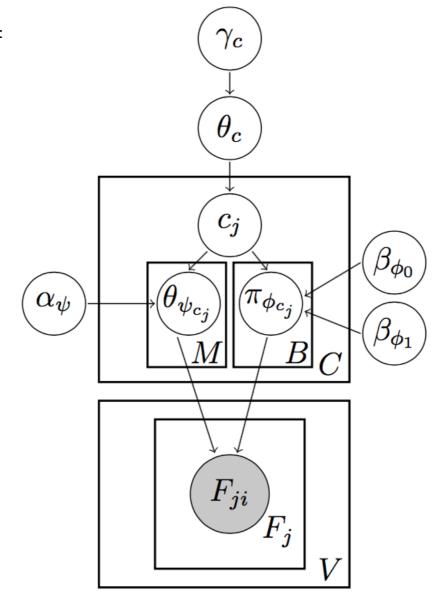
initial state data intake target state



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Learners use a **generative model** of how the observable data for each verb are created.





initial state data intake target state

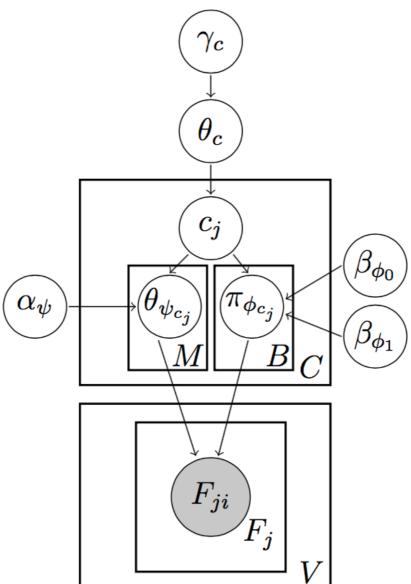


Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Learners use a **generative model** of how the observable data for each verb are created.

This represents how the different information is integrated into the process of determining a verb's class.





initial state data intake target state



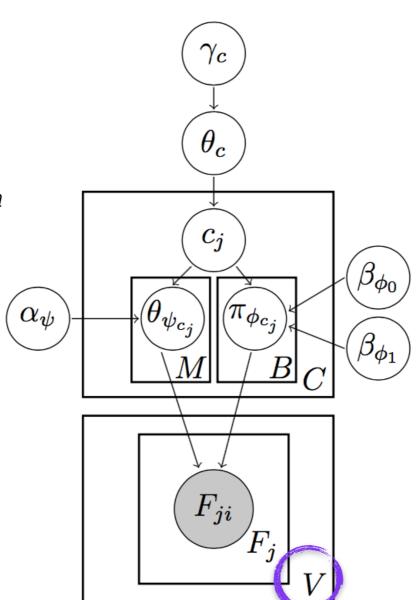
Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Learners use a **generative model** of how the observable data for each verb are created.

This represents how the different information is integrated into the process of determining a verb's class.

FALL





initial state data intake target state



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Learners use a **generative model** of how the observable data for each verb are created.

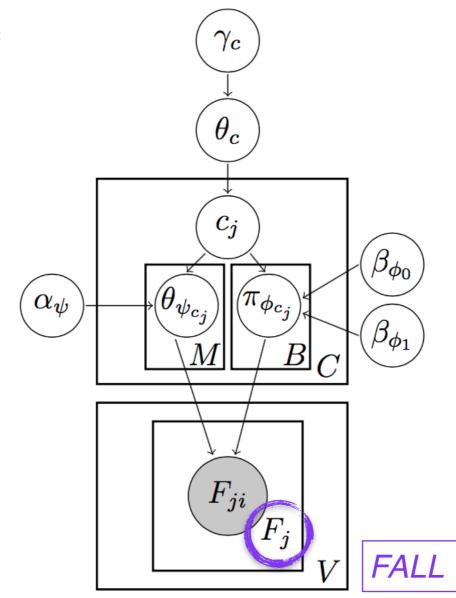
Each verb appears in a certain number of instances in the input.

"it's falling off"

"she fell down"

"don't fall!"

"is London Bridge
falling down?"





initial state data intake target state



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Learners use a **generative model** of how the observable data for each verb are created.

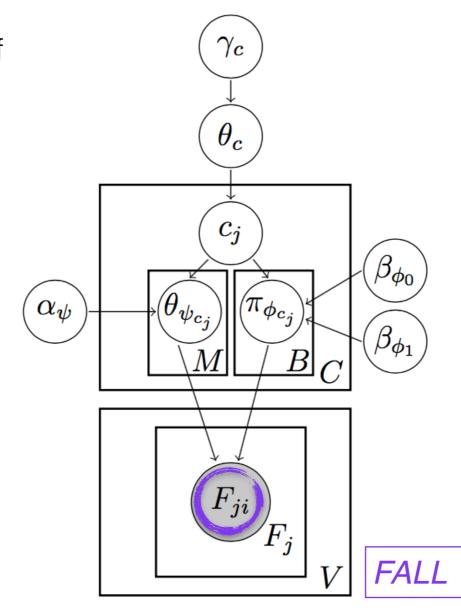
Each instance is observed some number of times.

(3x) "it's falling off"

"she fell down"

"don't fall!"

"is London Bridge
falling down?"





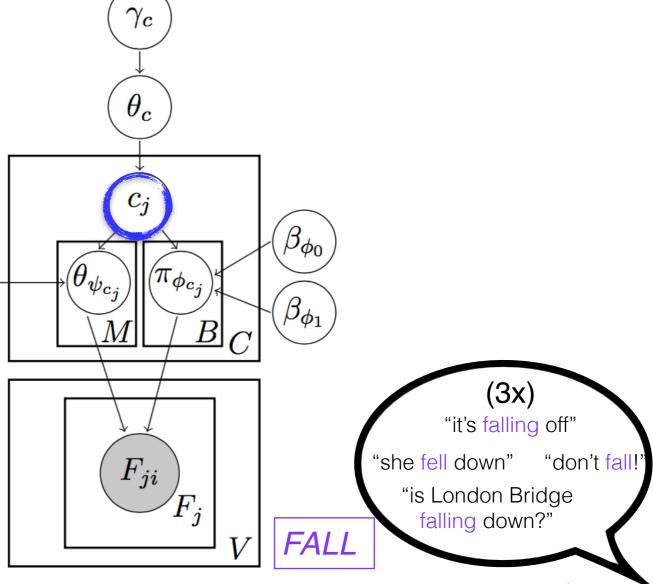
initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Each verb belongs to some class which determines its linguistic behavior. class7

 $lpha_\psi$



initial state data intake target state

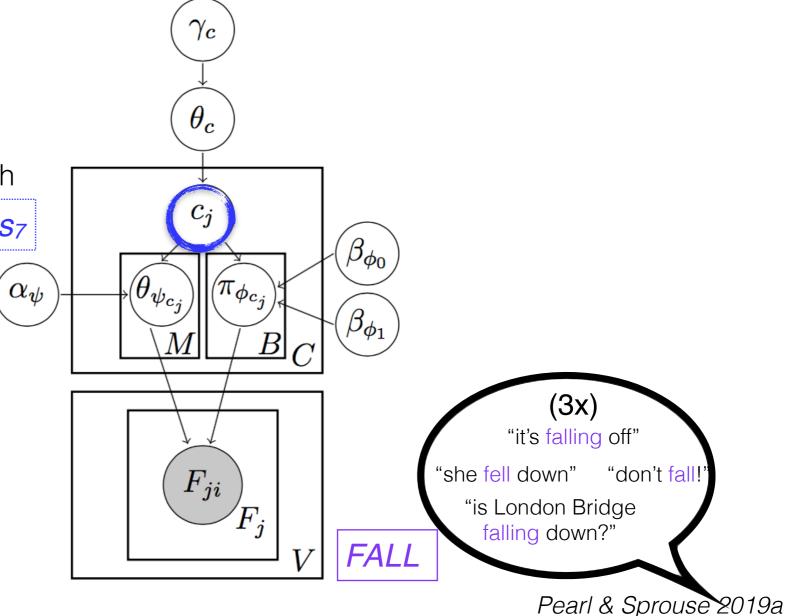
Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?





Each verb belongs to some class which determines its linguistic behavior. *class*7

Objective: Infer verb class



target state initial state data intake



 $heta_c$

 $lpha_{\psi}$

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Each verb belongs to some class which determines its linguistic behavior. class₇

Objective: Infer verb class

 $(\pi_{\phi_{c_j}})$ eta_{ϕ_1}

many classes there are or which verbs belong to which. There's a bias for classes in a power law distribution.

The learner doesn't know beforehand how

(3x)"it's falling off" "she fell down" "don't fall!" "is London Bridge falling down?"

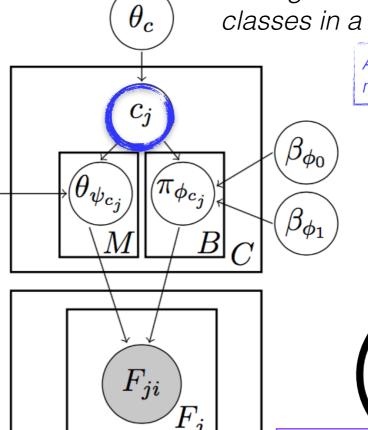
initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Each verb belongs to some class which determines its linguistic behavior. *class*7

Objective: Infer verb class



 $lpha_{m{\psi}}$

The learner doesn't know beforehand how many classes there are or which verbs belong to which. There's a bias for classes in a power law distribution.

A few classes with many members, and most classes with few members.

(3x)

"it's falling off"

"she fell down" "don't fall!

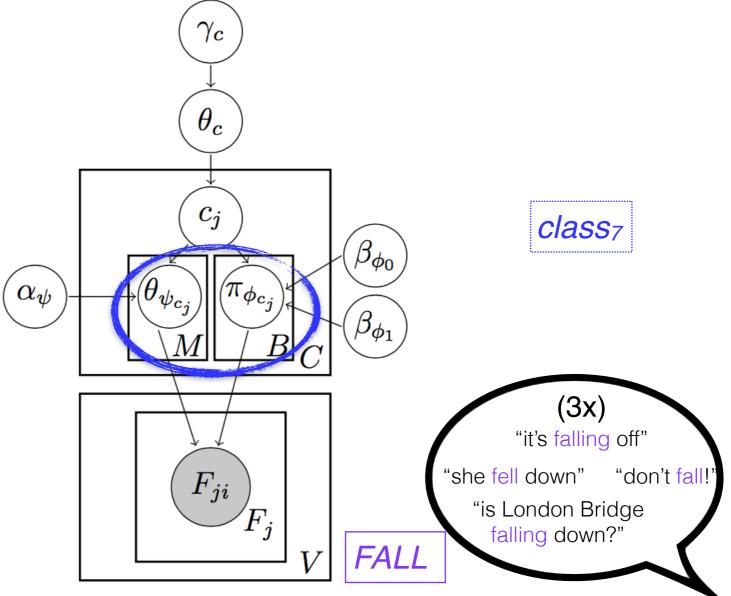
"is London Bridge
falling down?"

initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Depending on the verb class, the observed usage will have certain characteristics.

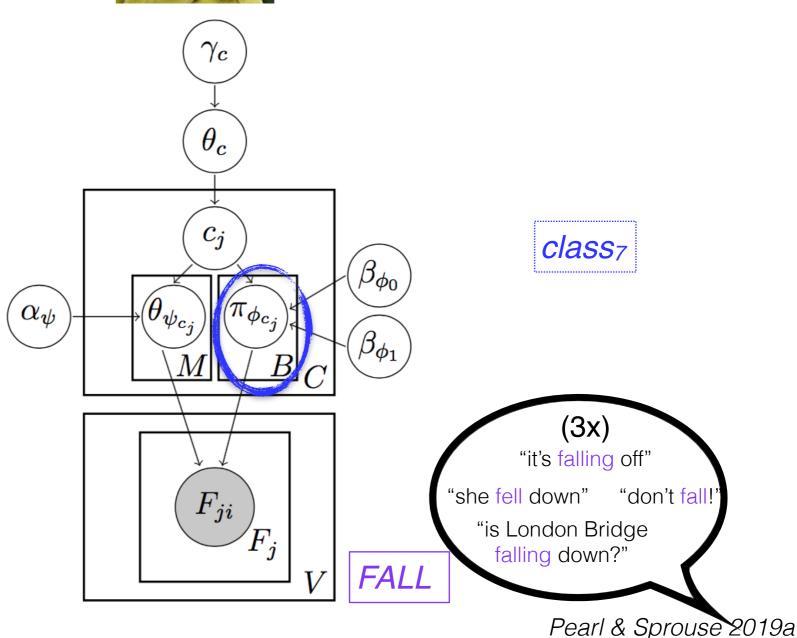


initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

These characteristics include binary choices such as whether the subject is animate or not.



initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

These characteristics include binary choices such as whether the subject is animate or not.

 γ_c Each class has a probability of preferring each option. $heta_c$ c_j class₇ $lpha_{m{\psi}}$ Subject -anim +anim eta_{ϕ_1} 0.3 0.7 (3x)-anim (SX)
"it's falling off" "she fell down" "don't fall!" "is London Bridge falling down?" **FALL**

initial state data intake target state

inference



 γ_c

 $heta_c$

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

Each class has a probability of preferring each option.

Binary choices:

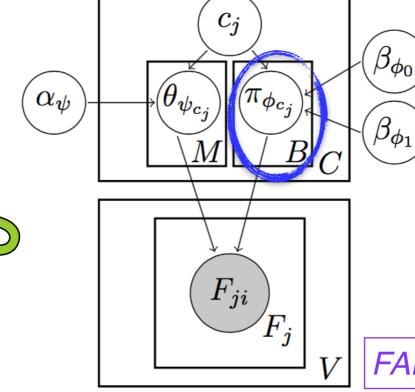
- +/-animate subject
- +/-animate object
- +/-animate oblique object
- +/-movement (when +exp-mapping)



+animate



-animate



class₇

+anim Subject -anim
0.3
0.7

-anim

"it's falling off"

"she fell down" "don't fall!"

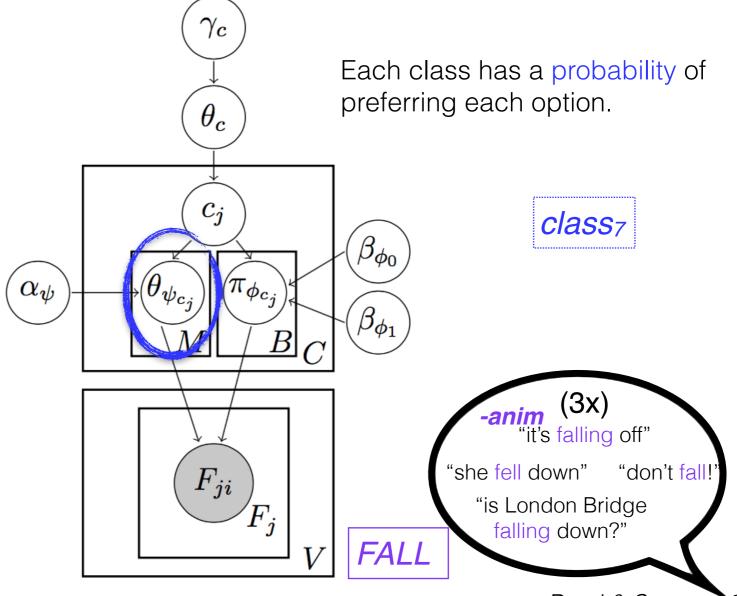
"is London Bridge
falling down?"

initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

These characteristics include multinomial choices such as which syntactic frame a verb appears in.



initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

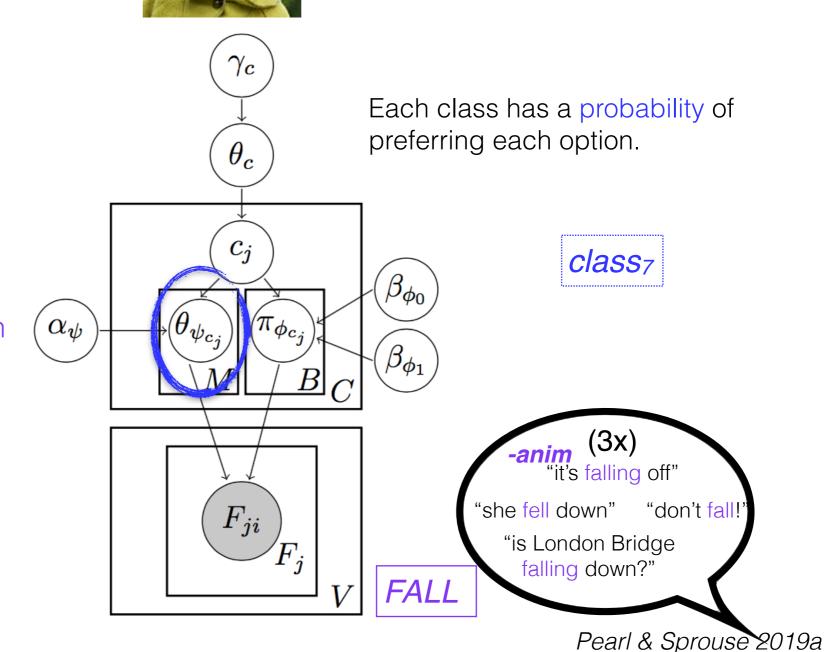
These characteristics include multinomial choices such as which syntactic frame a verb appears in.

NP V PRT

NP V

...

NP V S



initial state data intake target state



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

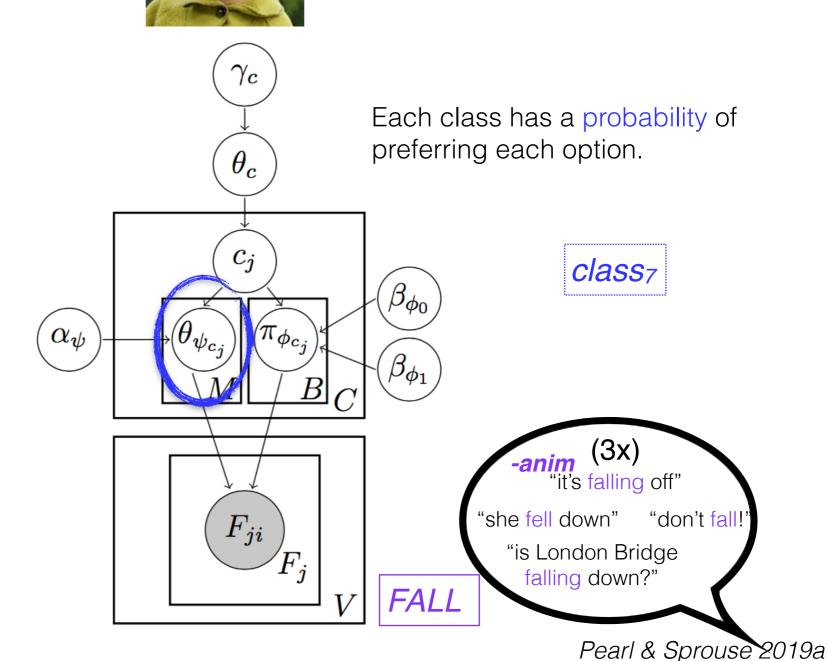
Each class has a probability of preferring each option.

NP V PRT 0.3

NP V 0.25

. . .

NP VS 0



initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?



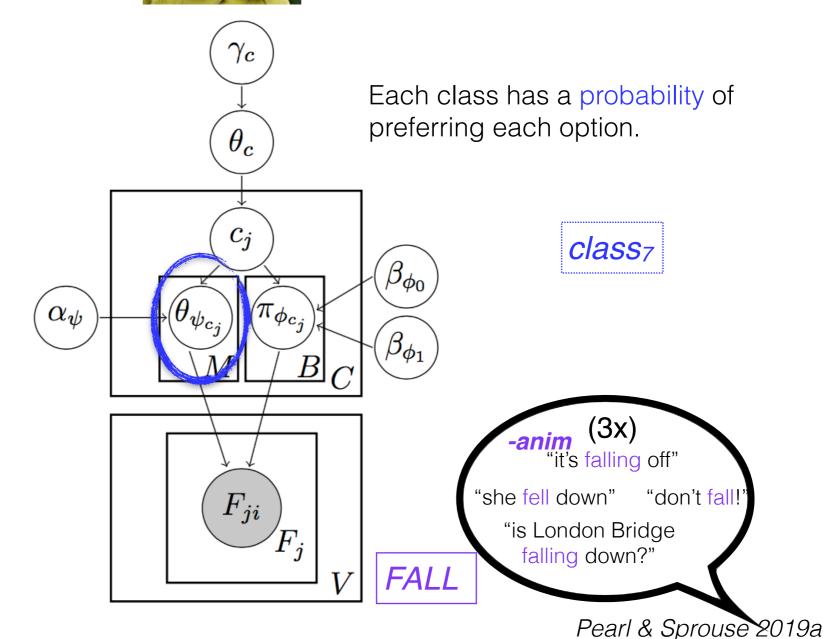
Multinomial choices: syntactic frame NP V PRT

(when -exp-mapping)
position of proto-Agent/Highest
position of proto-Patient/2nd-Highest
position of Other/3rd-Highest



Subject Highest-syn

Object 2nd-Highest-syn Oblique Object 3rd-Highest-syn



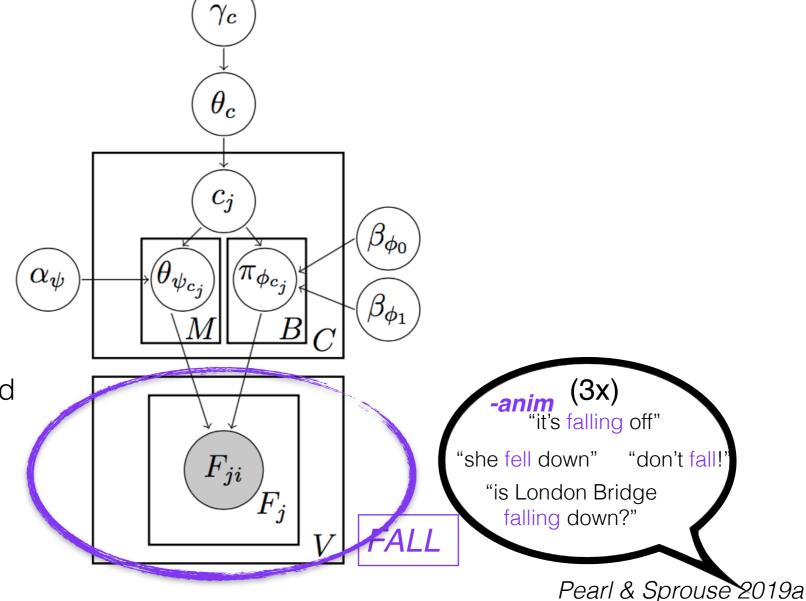
initial state data intake target state

uestion: Is it possible for th

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

Using the observed instances of verb usage, Bayesian inference can be used to determine ...



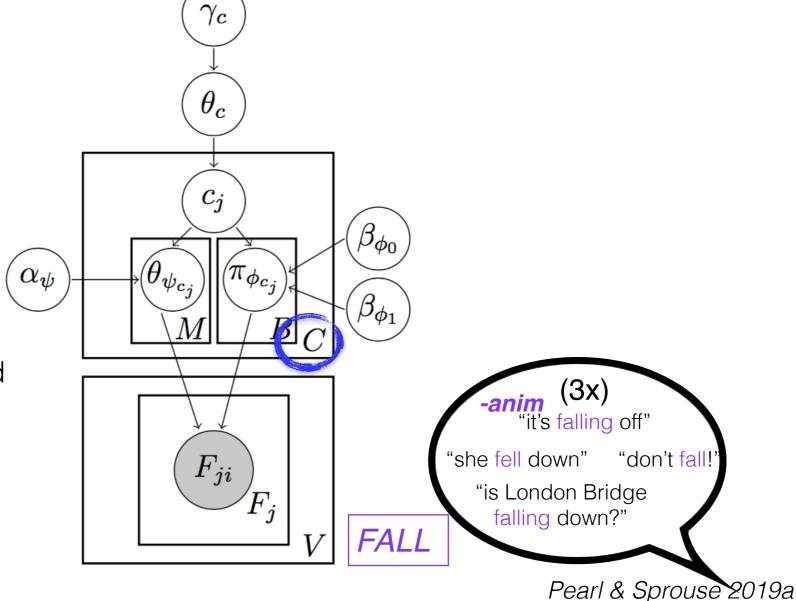
initial state data intake target state

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?



Using the observed instances of verb usage, Bayesian inference can be used to determine

how many classes there are



initial state data intake target state

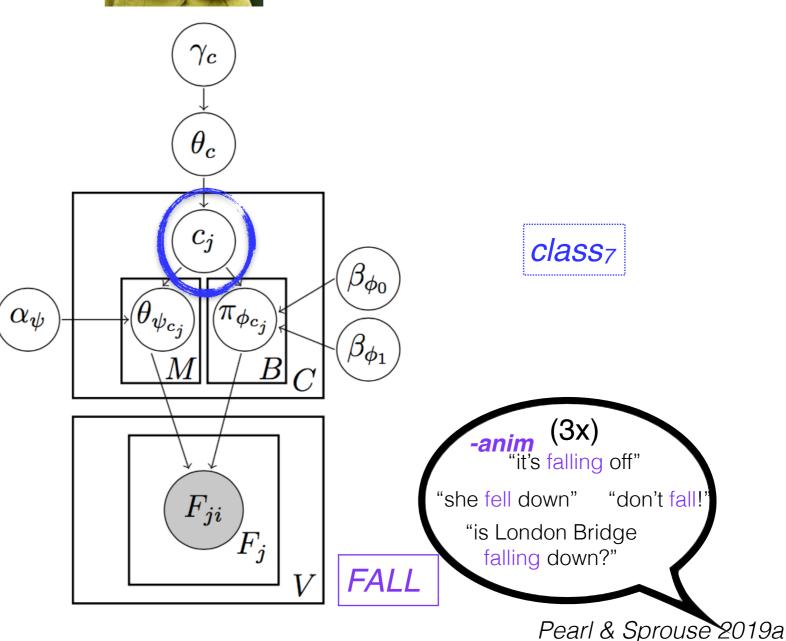
inference

Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?



target state initial state data intake

inference

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

 γ_c NP V PRT 0.3 NP V 0.25 θ_c NP V S c_{j} class₇ $lpha_{\psi}$ Subject -anim +anim 0.3 0.7 (3x)-anim (3X)
"it's falling off" "she fell down" "don't fall!" "is London Bridge falling down?"

Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class

initial state data intake target state

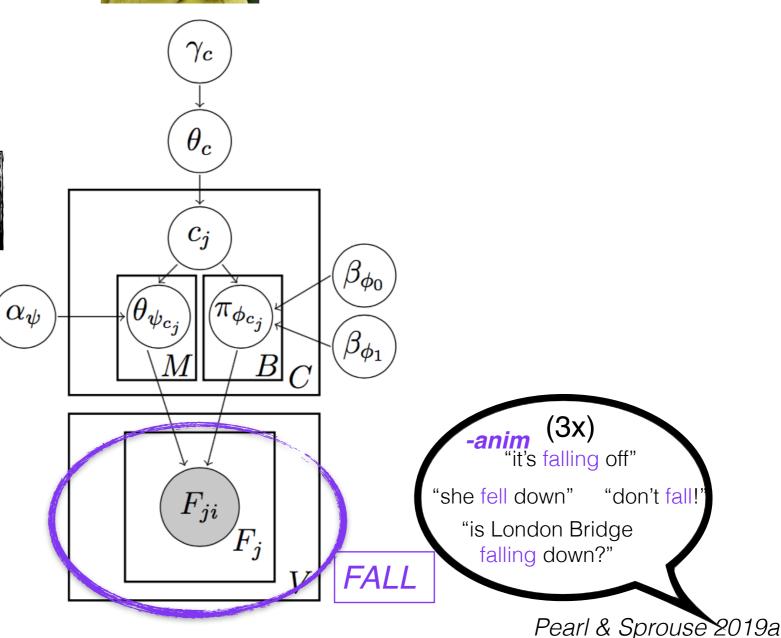
Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?



Best answer: maximizes the probability of the observed data.

Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class



initial state data intake target state



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?



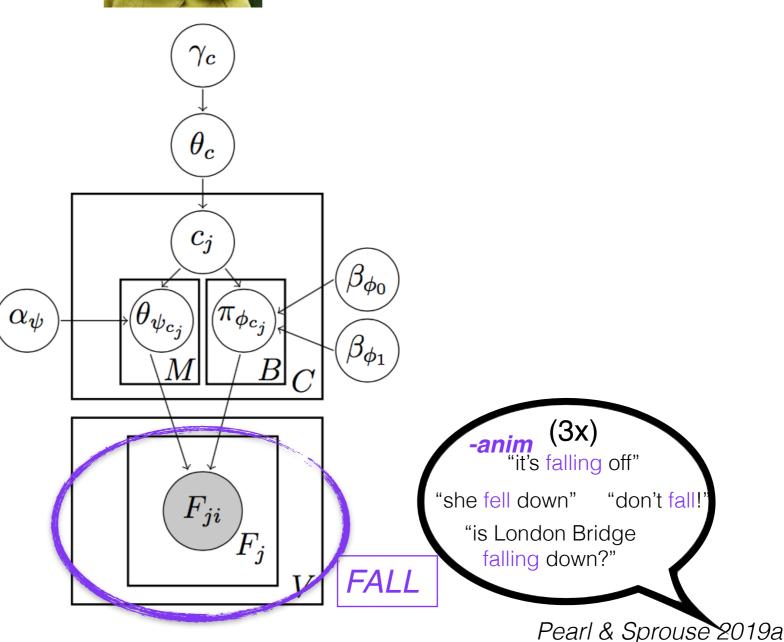
$$p_{c_j} = P(c_j | c_{-j}, \gamma_c, F_{-j}, \lambda) =$$

$$p_{cat_j} * p_{binary_{c_j}} * p_{multinomial_{c_j}}$$

+ Gibbs sampling

Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class



initial state data intake target state



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

$$p_{c_j} = P(c_j | c_{-j}, \gamma_c, F_{-j}, \lambda) =$$

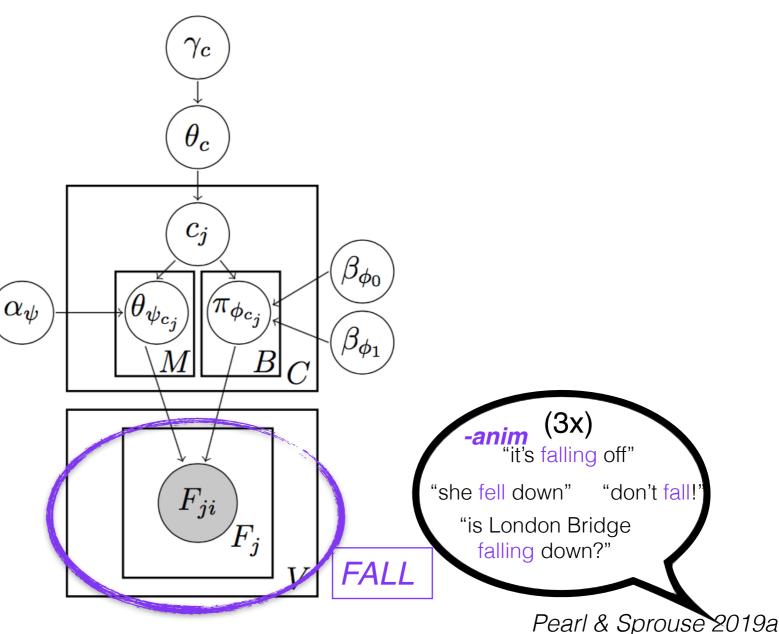
$$p_{cat_j} * p_{binary_{c_j}} * p_{multinomial_{c_j}}$$

+ Gibbs sampling

This is what makes this an ideal learner model—the inference computation is accomplished using something that's not incremental or constrained, and is guaranteed to converge on the optimal answer, given enough time to run.

Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class



initial state data intake target state



Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

inference

$$p_{c_j} = P(c_j | c_{-j}, \gamma_c, F_{-j}, \lambda) =$$

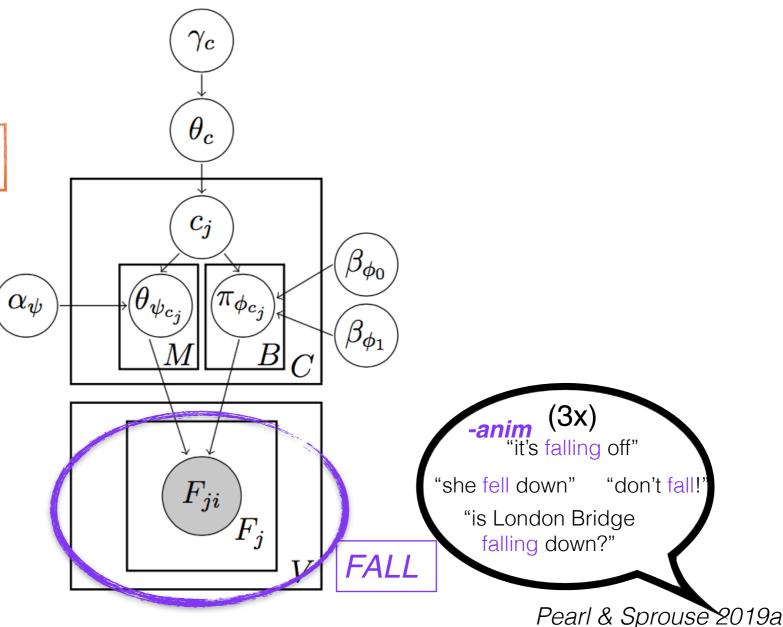
$$p_{cat_j} * p_{binary_{c_j}} * p_{multinomial_{c_j}}$$

+ Gibbs sampling

Goal: Determine what the best answer we can get is, given this characterization of the learning problem.

Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class

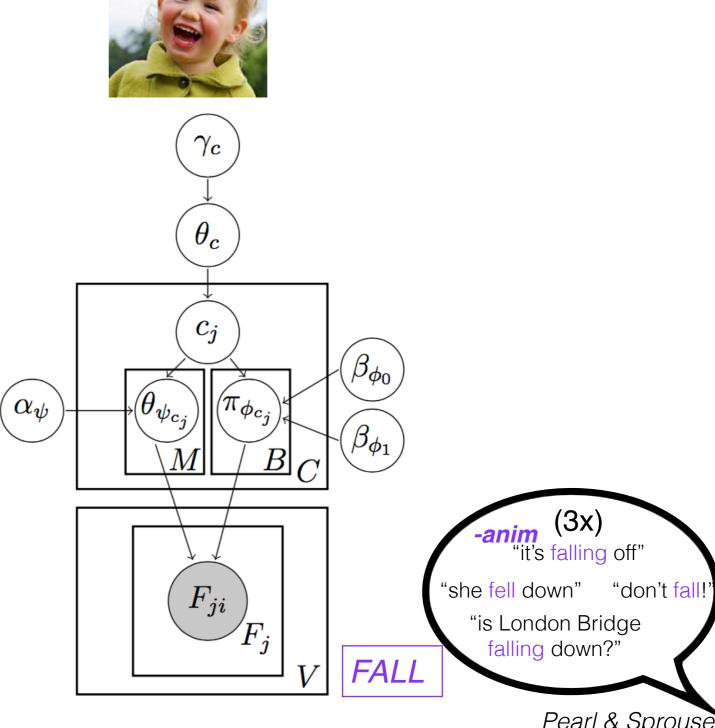


target state initial state data intake

inference

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?





Pearl & Sprouse 2019a

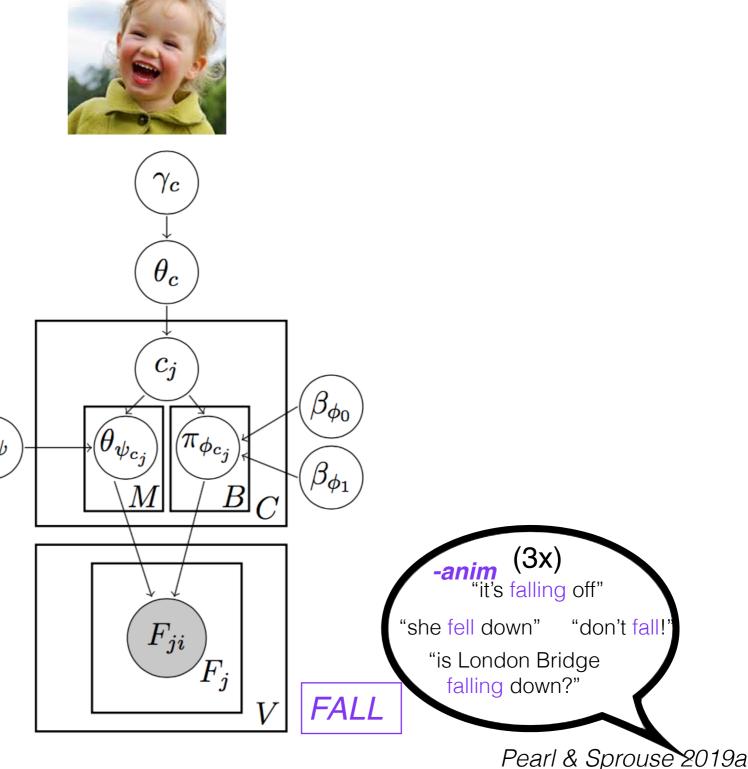
initial state data intake target state

inference

Basic question: Is it possible for the child to use the acquisitional intake to achieve the target knowledge/behavior?

Goal: Determine if the information provided in the modeled learner's acquisitional intake is sufficient to identify verb classes the way children do.





initial state data intake inference

target state



So what does the target knowledge/behavior look like?

initial state data intake inference

target state

Goal: Model the developmental trajectory of verb class knowledge from 3 to 4 to 5 years old in English





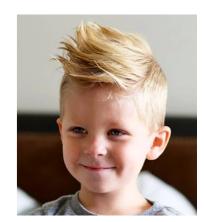


initial state data intake inference

target state







verb class knowledge

Survey of 38 experimental studies on children's production and comprehension of specific verbs



initial state data intake inference

target state







verb class knowledge

Survey of 38 experimental studies on children's production and comprehension of specific verbs

... yields 12 verb behaviors

+/-passive +unaccusative

+ditransitive +control-object

+raising-object

+raising-subject +control-subject

+that-comp

+whether/if-comp +subject-experiencer

+non-finite to-comp

+object-experiencer

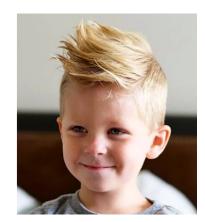


initial state data intake inference

target state







These verb behaviors yield a number of verb classes at each age

*Verbs only belong to one class



initial state data intake inference

mar state data make microne





target state

These verb behaviors yield a number of verb classes at each age

Example classes *Verbs only belong to one class

[+passive]: carry, chase, crash, drop, eat, hit, hold, hurt, jump, kick, kiss, knock, lick, punch, push, scratch, shake, turn, wash, watch

[-passive]: believe, remember

[+non-finite to]: ask, have, need, start, suppose, teach, try, use, want

[+that-comp]: bet, hope, think, wish

[+passive, +non-finite to]: like

[+passive, +that-comp]: see

<3yrs



initial state data intake inference





target state

These verb behaviors yield a number of verb classes at each age

Example classes *Verbs only belong to one class

[+passive]: bite, bump, carry, chase, crash, drop, find, hit, hold, hurt, jump, kick, kill, kiss, knock, lick, pull, punch, push, ride, scratch, shake, shoot, turn, wash, watch

[-passive]: believe, remember

[+that-comp]: bet, hope, think, wish

[+non-finite to, +raising-obj]: need

[+non-finite to, +raising-obj, +control-subj]: want

[+passive, +non-finite to, +psych-subj]: like

[+passive, +that-comp]: see

<4yrs



initial state data intake inference





target state

These verb behaviors yield a number of verb classes at each age

Example classes *Verbs only belong to one class

[+passive]: bite, bump, carry, chase, crash, drop, find, hit, hold, hurt, jump, kick, kill, kiss, knock, lick pull, push, ride, scratch, shake, shoot, turn, wash, watch [-passive]: believe, remember

[+that-comp]: bet, dream, guess, hope, lie, pretend, think, wish

[+non-finite to, +raising-obj]: need

[+non-finite to, +raising-obj, +control-subj]: want

[+passive, +non-finite to, +psych-subj]: like

[+passive, +that-comp, +whether/if-comp]: see

<5yrs



initial state data intake inference

target state

These verb behaviors yield a number of verb classes at each age

<3yrs



15 classes of 60 verbs total

<4yrs



23 classes of 76 verbs total

<5yrs



25 classes of 84 verbs total



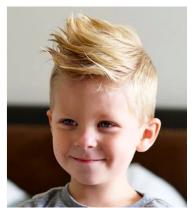


15 classes

<4yrs

23 classes

<5yrs



25 classes

Evaluation:

How well did the modeled learner do at finding these verb classes?





<3yrs



15 classes

23 classes

<4yrs

<5yrs



25 classes

Evaluation:

How well did the modeled learner do at finding these verb classes?

Implementation:



0.0 <= RI <= 1.0



<3yrs



15 classes

23 classes

<4yrs

<5yrs



25 classes

Evaluation:

How well did the modeled learner do at finding these verb classes?

Implementation:





Rand Index

0.0 <= RI <= 1.0



Evaluation:

How well did the modeled learner do at finding these verb classes?

<3yrs



15 classes

<4yrs



23 classes

<5yrs



25 classes





0.0 <= RI <= 1.0 Rand Index

For each pair of verbs in the inferred classes: verb_i verb_j

Inferred Class

Same class Different class

Child Class

Same class
Different class



Evaluation:

How well did the modeled learner do at finding these verb classes?

<3yrs



20 010

<5yrs



<4yrs

23 classes



25 classes



15 classes



0.0 <= RI <= 1.0 Rand Index

For each pair of verbs in the inferred classes:

verb_i verb_j

Inferred Class

Same class

Different class

Child Class

Same class
Different class

True Positive



Evaluation:

How well did the modeled learner do at finding these verb classes?





15 classes

<4yrs



23 classes

<5yrs



25 classes





0.0 <= RI <= 1.0 Rand Index

For each pair of verbs in the inferred classes:

verb_i verb_j

Inferred Class

Same class

Different class

Child Class

Same class
Different class

True Positive

True Negative



Evaluation:

How well did the modeled learner do at finding these verb classes?







<4yrs



<5yrs

25 classes



15 classes



0.0 <= RI <= 1.0 Rand Index

For each pair of verbs in the inferred classes: verbi

Inferred Class

verbi

Child Class Sa

Same class
Different class

Same class

True Positive

False Positive

Different class

False Negative

True Negative



Evaluation:

How well did the modeled learner do at finding these verb classes?

Same class

<3yrs



15 classes

<4yrs



23 classes

<5yrs



25 classes

True Positives + True Negatives

True Positives + True Negatives + False Positives + False Negatives

Rand Index

For each pair of verbs in the inferred classes: verb_i verb_j

Inferred Class

Same class

Different class

True Positive

False Negative

True Negative

Intuition: Get credit for putting things together that belong together and keeping things apart that should be apart.

Child Class

Different class False Positive



Evaluation:

How well did the modeled learner do at finding these verb classes?

<3yrs



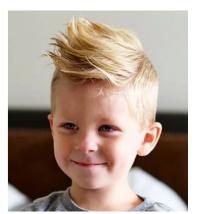
15 classes

<4yrs



23 classes

<5yrs



25 classes

True Positives + True Negatives

True Positives + True Negatives + False Positives + False Negatives

Rand Index

But how do we know we're doing better than chance?





Evaluation:

How well did the modeled learner do at finding these verb classes?

<3yrs



15 classes

<4yrs



23 classes

<5yrs



25 classes

True Positives + True Negatives

True Positives + True Negatives + False Positives + False Negatives

Rand Index

Bootstrapped confidence intervals for RI, with randomly generated classes of random size and random verb assignment





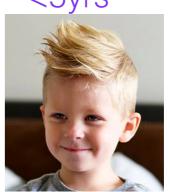
<3yrs



<4yrs



<5yrs



Thematic systems

<3yrs



<4yrs



<5yrs



Thematic systems

relative

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)

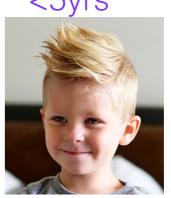
<3yrs



<4yrs



<5yrs



Thematic systems

relative

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)

fixed







<3yrs



<4yrs



<5yrs



Thematic systems

relative

Agent > Experiencer > Theme > Patient > (Source, Goal, Location)

fixed







Expected mapping

yes

no



Subject Highest-syn

Object

2nd-Highest-syn

Oblique Object

3rd-Highest-Syn

<3yrs



<4yrs



<5yrs



Thematic systems

relative

Agent > Experiencer > Theme > Patient > (Source, Goal, Location)

fixed







Expected mapping

yes



no

Subject Highest-syn Object 2nd-Highest-syn

Oblique Object

3rd-Highest-Syn

Surface morphology

yes

NP V_{past} PRT

no

NP V PRT

<3yrs



<4yrs



<5yrs



Thematic systems

relative

Agent > Experiencer > Theme > Patient > (Source, Goal, Location)

fixed







Expected mapping

yes

no



Object

Subject Highest-syn

2nd-Highest-syn

Oblique Object

3rd-Highest-Syn

Surface morphology

yes

NP V_{past} PRT

no

NP V PRT

A modeled learner implements one of each (thematic system, expected mapping, and surface morphology)





Good news!
There were some for each age that performed better than chance (RI > 99%).

<3yrs



<4yrs



<5yrs

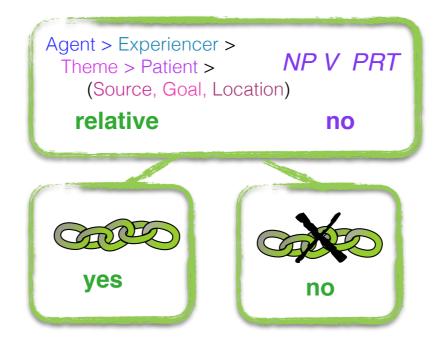


Pearl & Sprouse 2019a



RI > 99% = better than chance





<4yrs



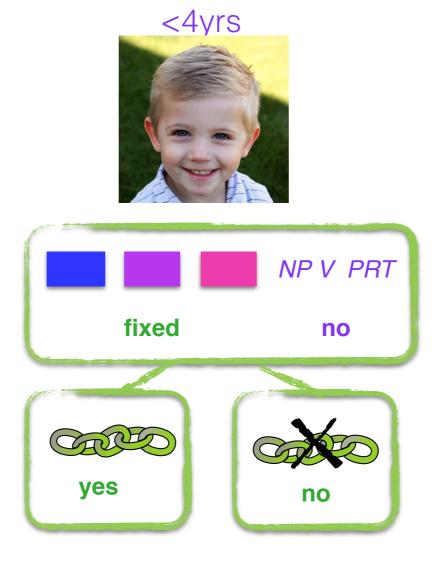
<5yrs

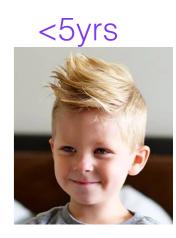


Pearl & Sprouse 2019a



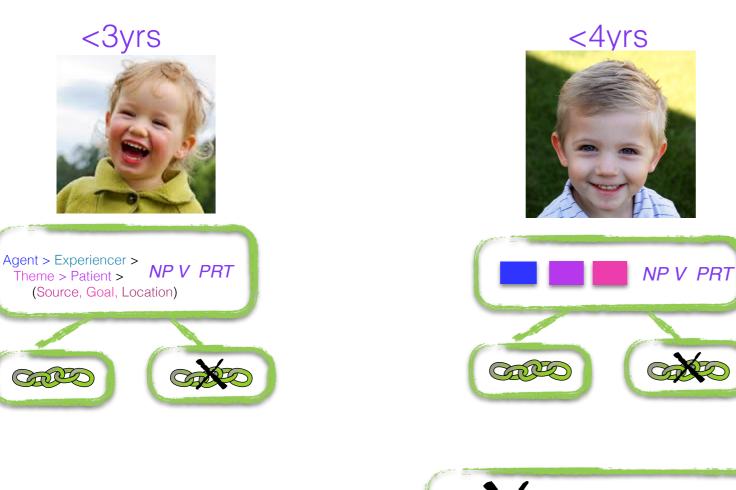


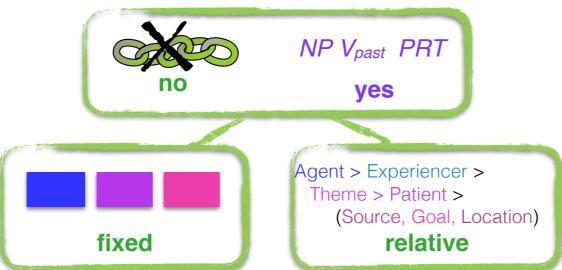




Pearl & Sprouse 2019a



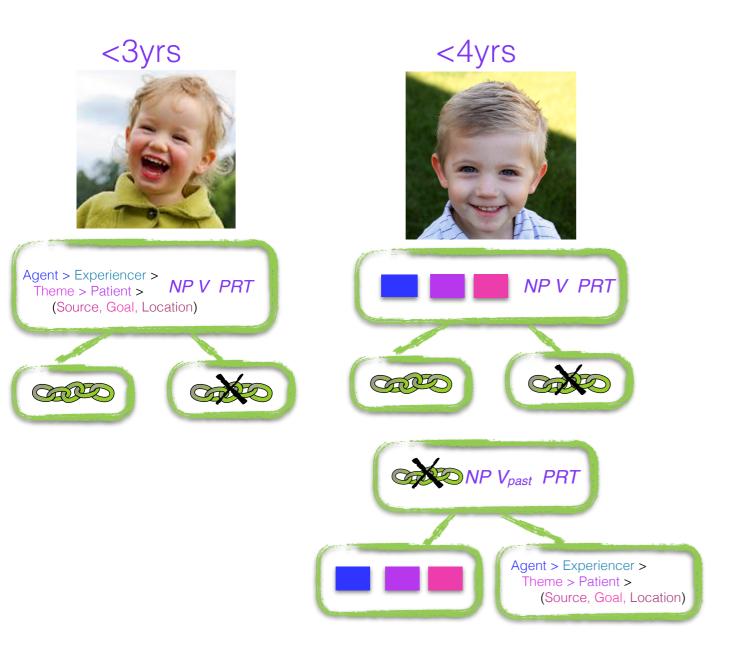


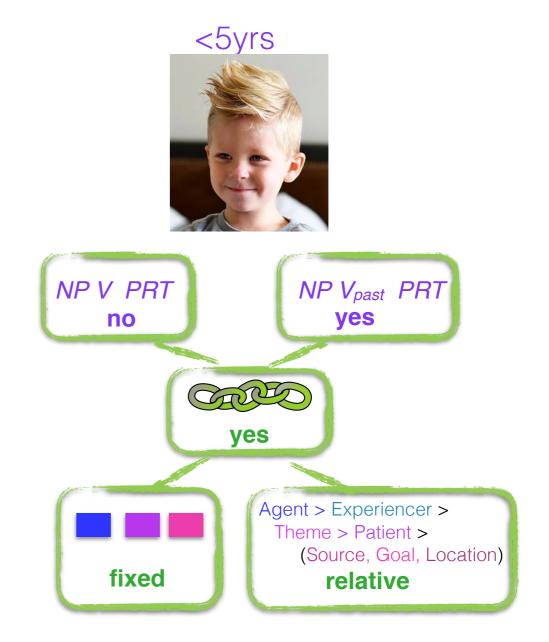




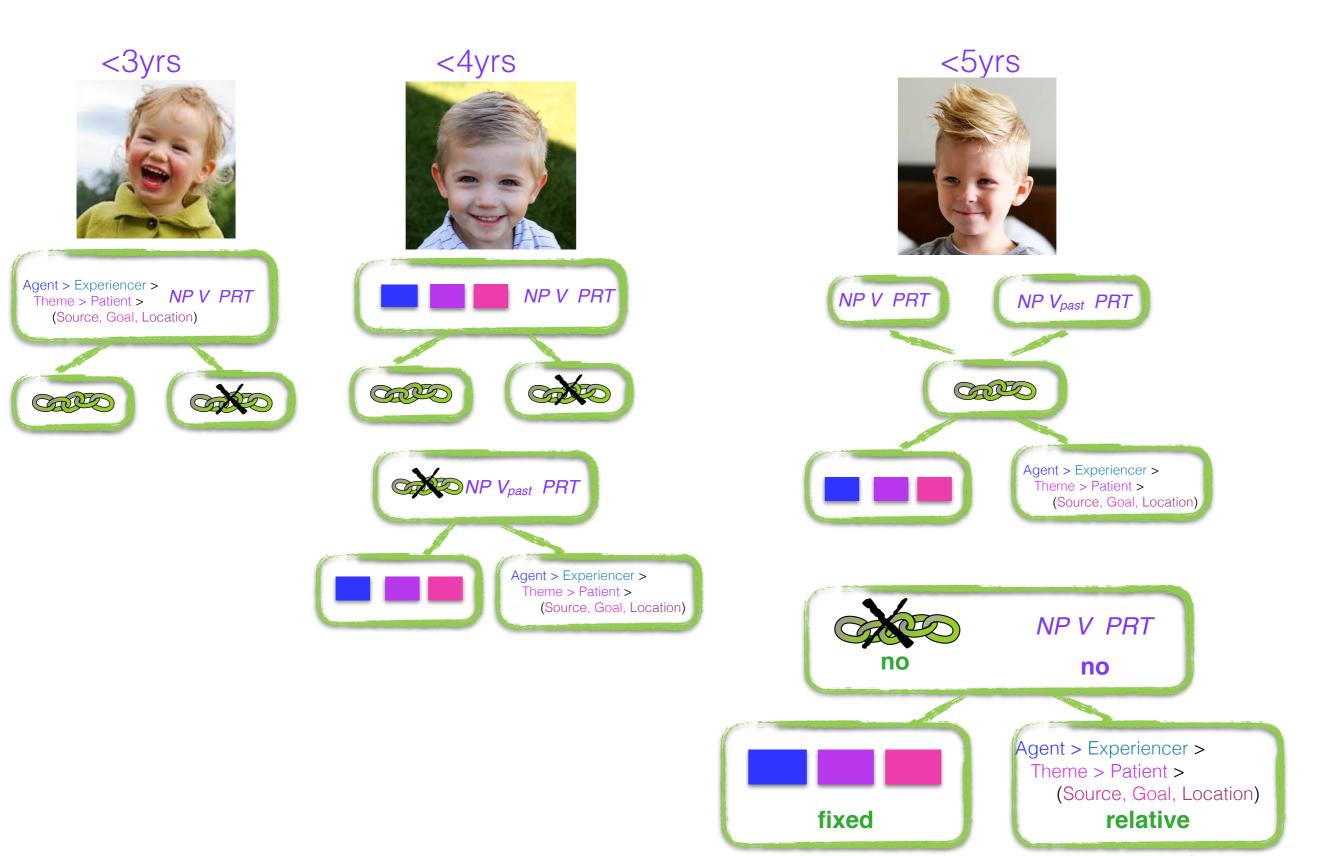
Pearl & Sprouse 2019a



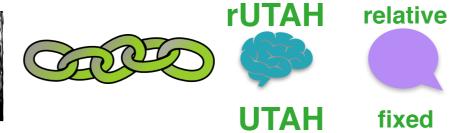


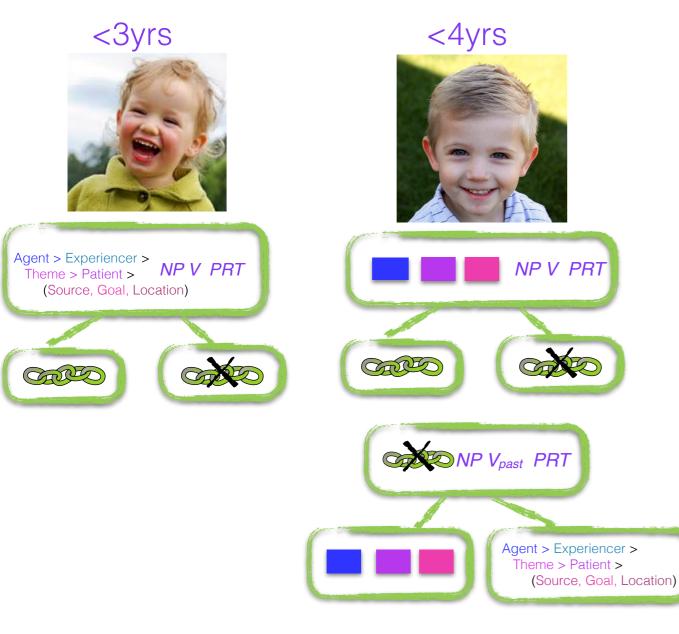


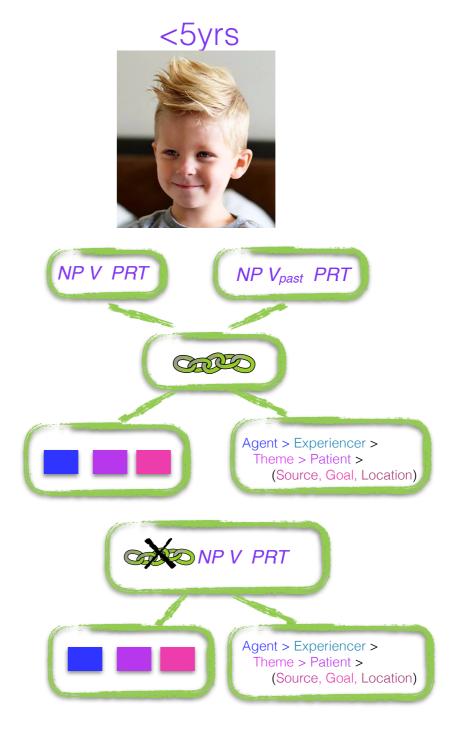




Pearl & Sprouse 2019a





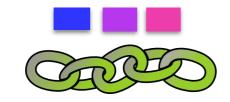






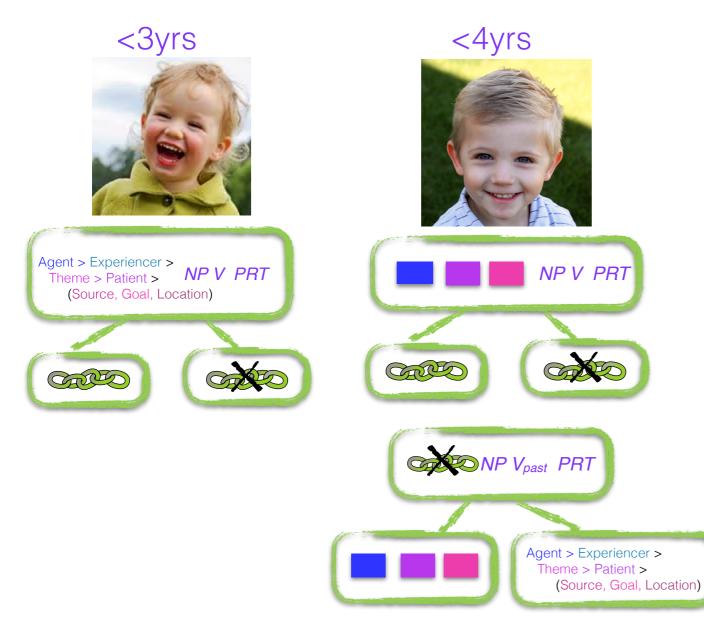


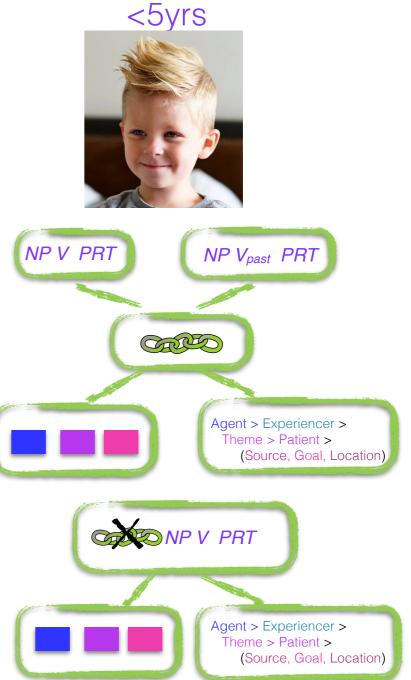
UTAH



These are innately specified. Early maturation would assume they're present at all ages.

rUTAH



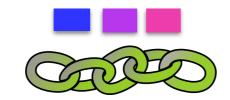






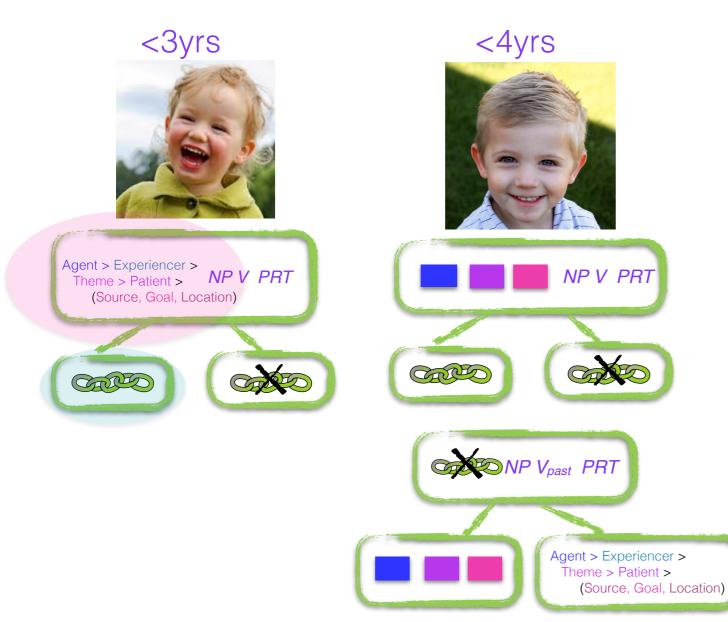


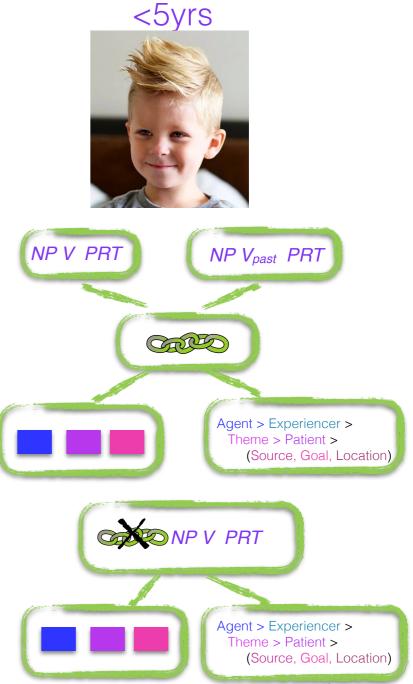




But the thematic representation isn't present at three, even though the link could be.

rUTAH



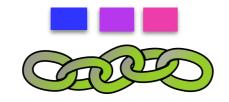










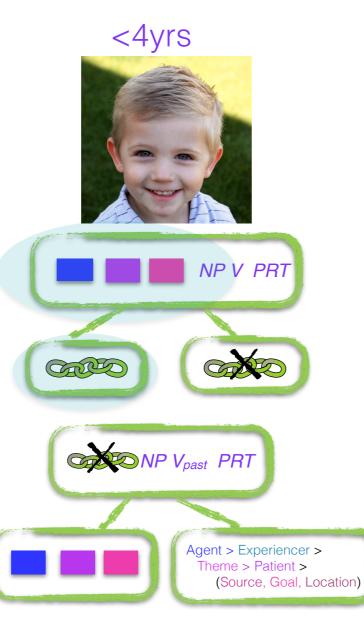


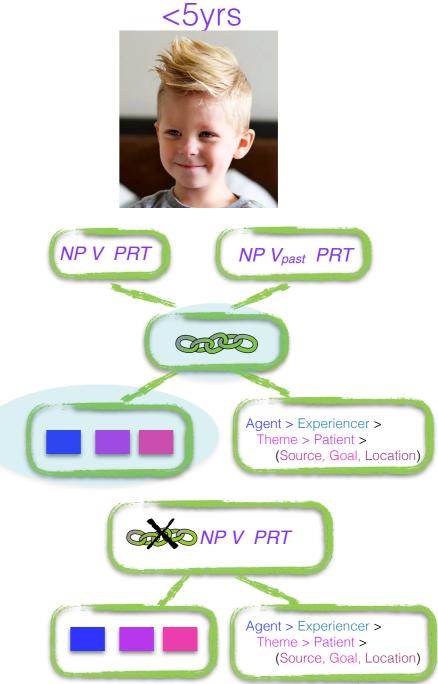
Both are present at four and five, though.

rUTAH



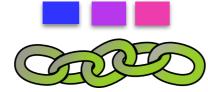




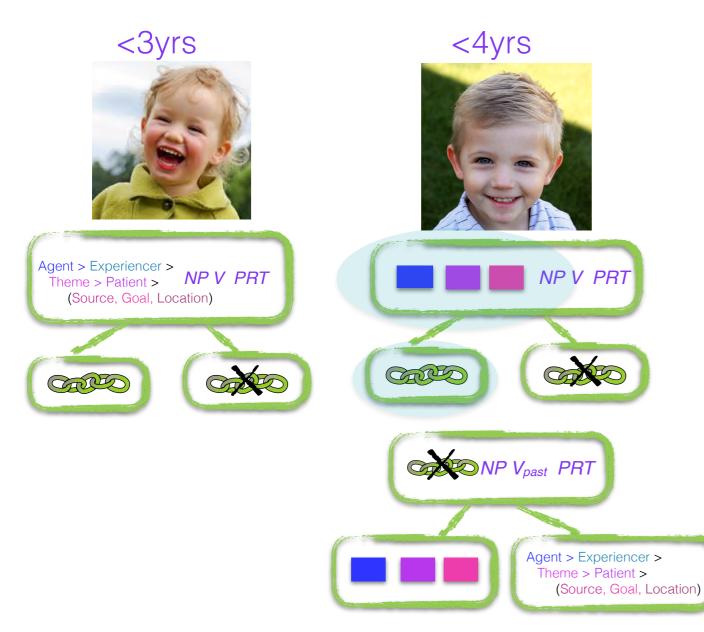


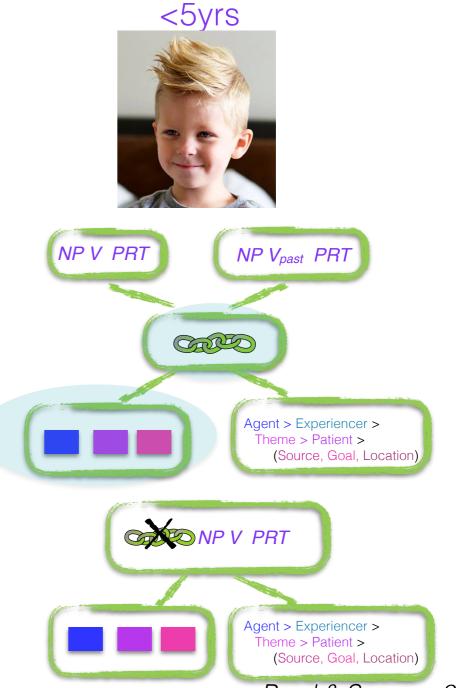






So UTAH is compatible with late maturation (at four or later).





rUTAH





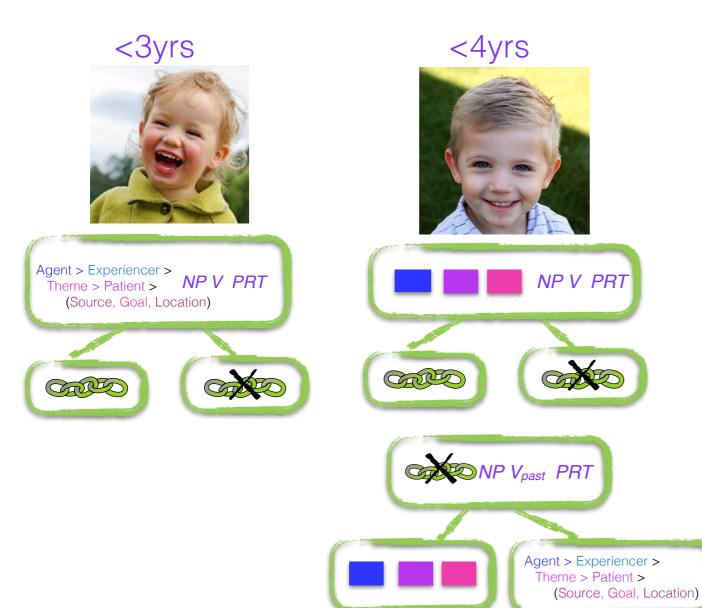


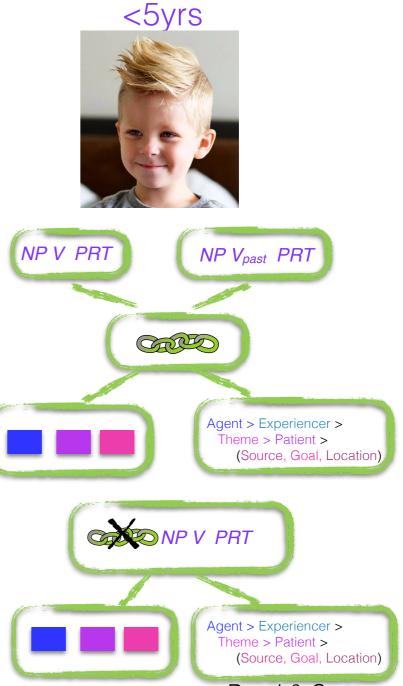
Agent > Experiencer > Theme > Patient > (Source, Goal, Location)





These are innately specified. Early maturation would assume they're present at all ages.





rUTAH



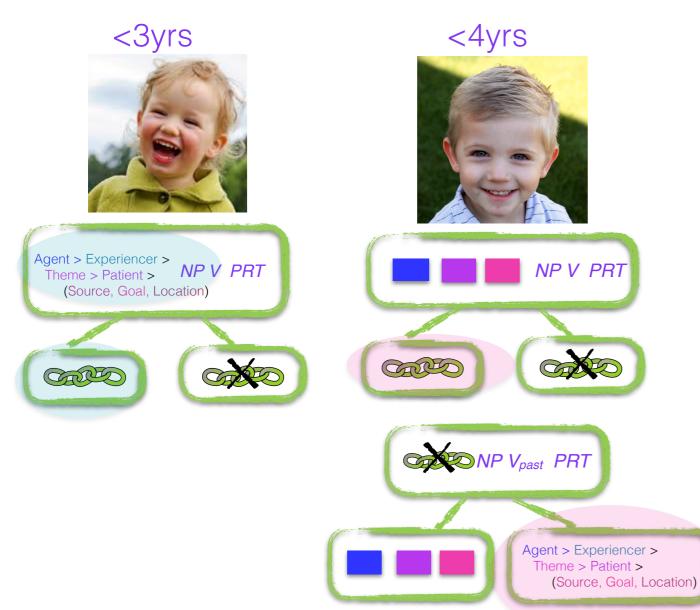


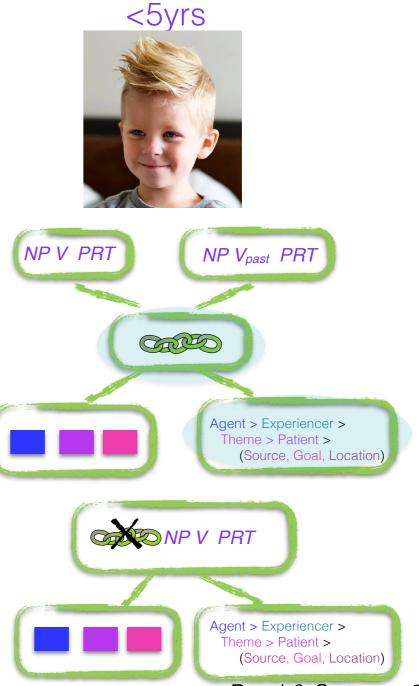


Agent > Experiencer > Theme > Patient > (Source, Goal, Location)









rUTAH



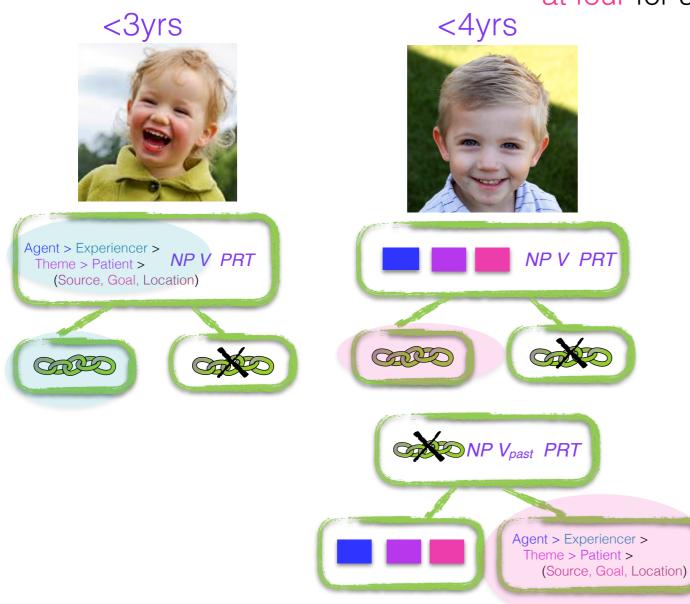


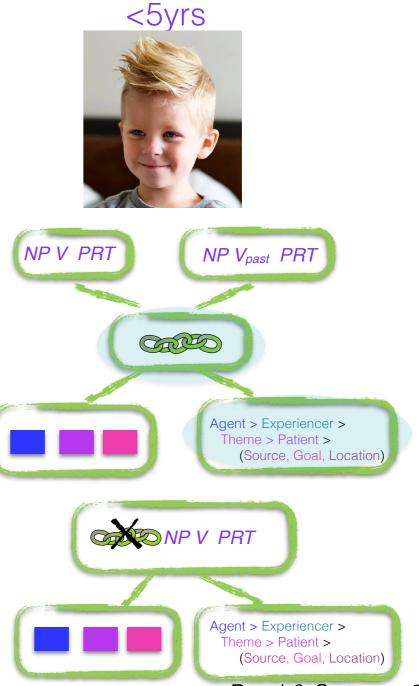


Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



This means development is complicated for early maturation — the knowledge has to be inaccessible at four for some reason.





rUTAH



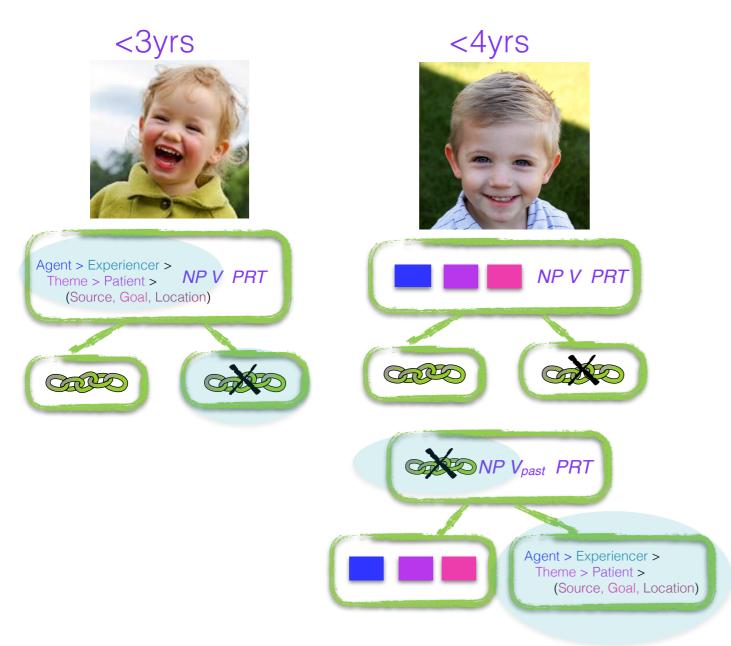


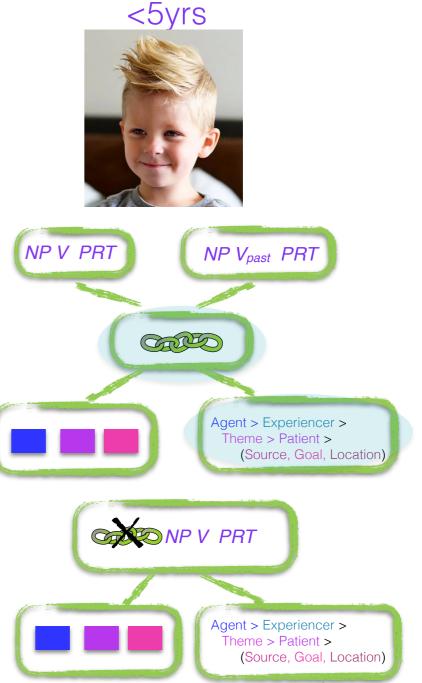


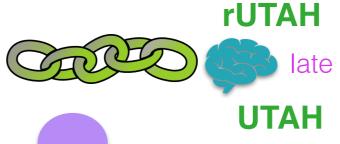
Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



Late maturation is compatible, and would predict that the linking knowledge doesn't emerge till five.







relative



The derived-mapping variant using the fixed system would look for this knowledge to be present after the child has had sufficient language experience.



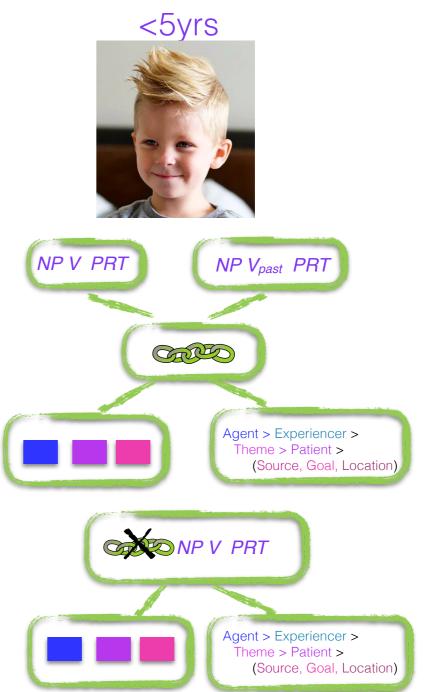


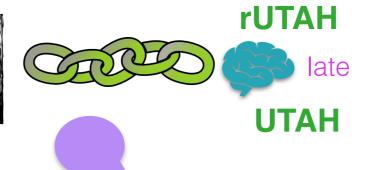












relative

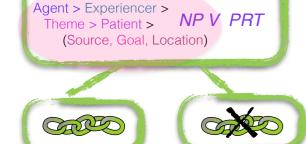




The child would need to derive the fixed system knowledge as well as the linking knowledge, since it's not present at age three.



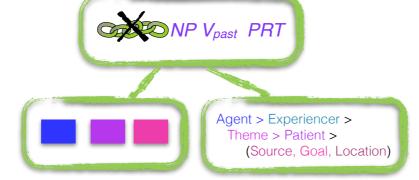




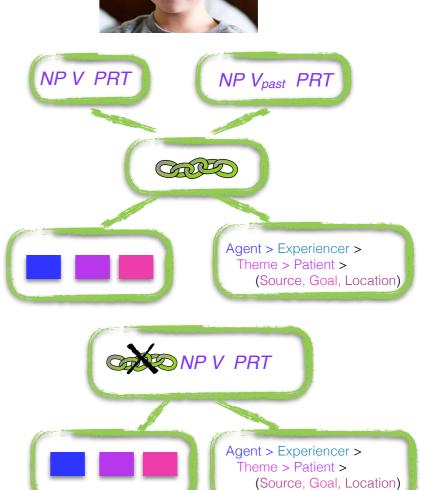


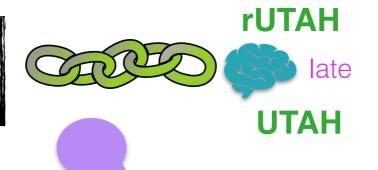








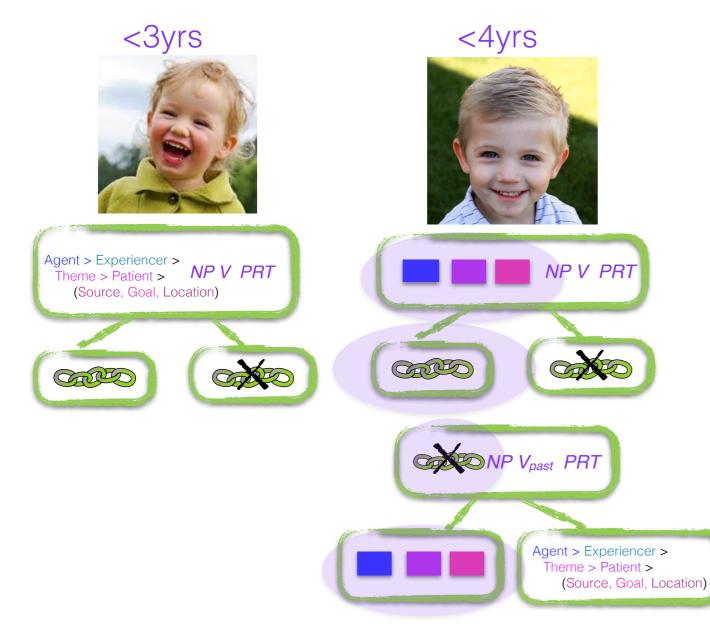


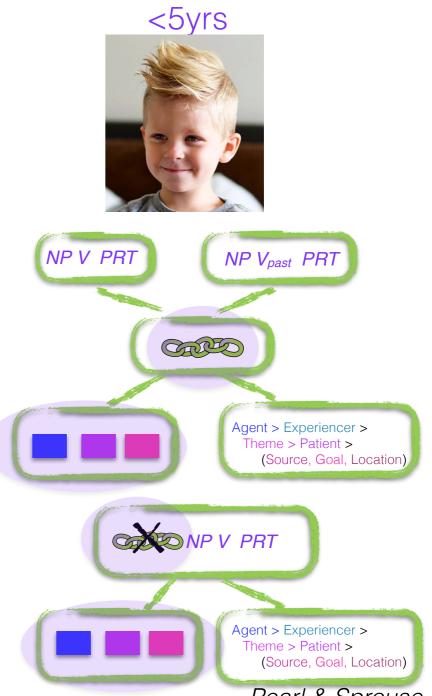


relative



The child would need to derive the fixed system knowledge as well as the linking knowledge, since it's not present at age three.







+derive fixed **fixed**

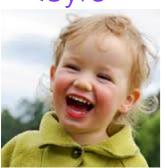


Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



The derived-mapping variant using the relative system would look for this knowledge to be present after the child has had sufficient language experience.





Agent > Experiencer >
Theme > Patient > NP V PRT
(Source, Goal, Location)







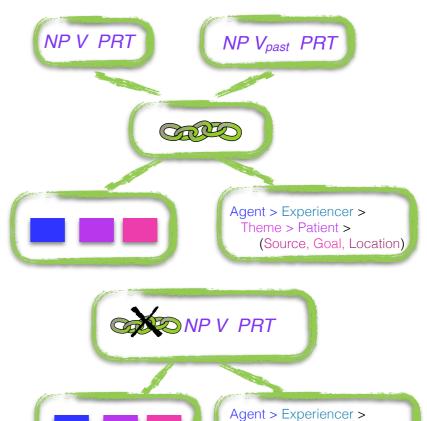












Pearl & Sprouse 2019a

Theme > Patient >

(Source, Goal, Location)



+derive fixed **fixed**

relative

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)

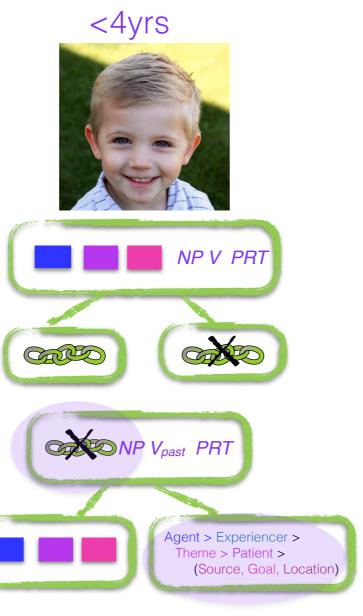


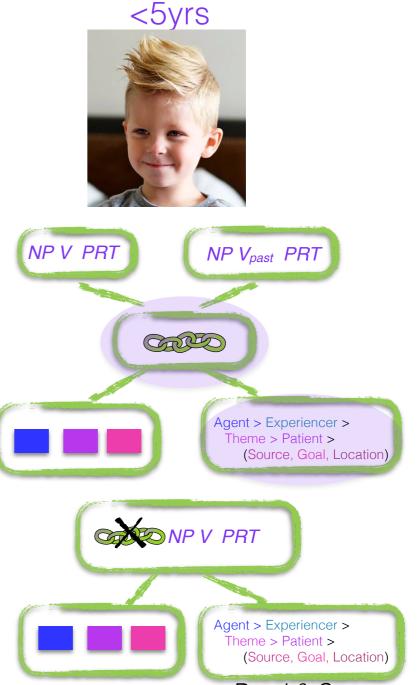
This seems compatible: for example, the linking knowledge could be absent at three and four, but derived by five.





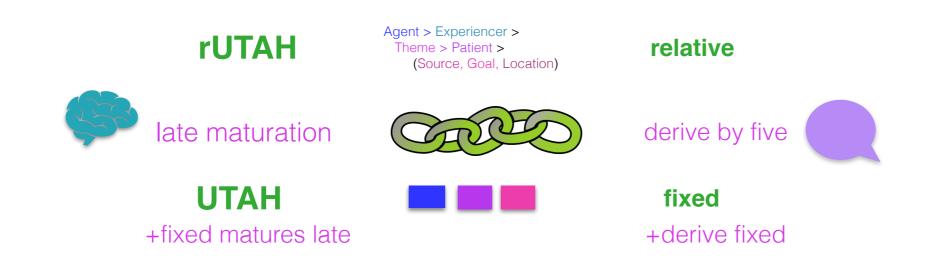






Pearl & Sprouse 2019a



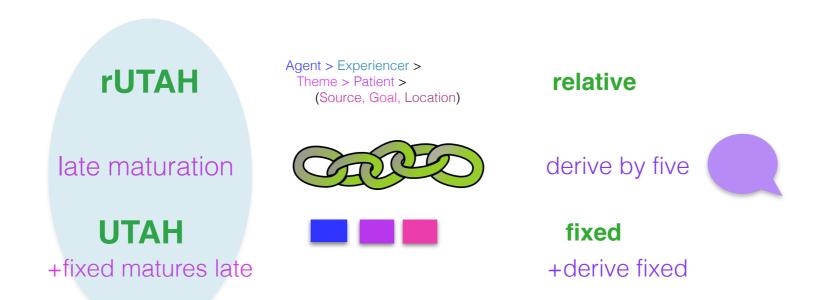








Takeaway 1: Innate-mapping approaches must involve late maturation.







Takeaway 2: Approaches with fixed thematic systems must involve late maturation or derivation from the input.



Question: If knowledge matures late, how does that work? We need evidence from developmental neurobiology.



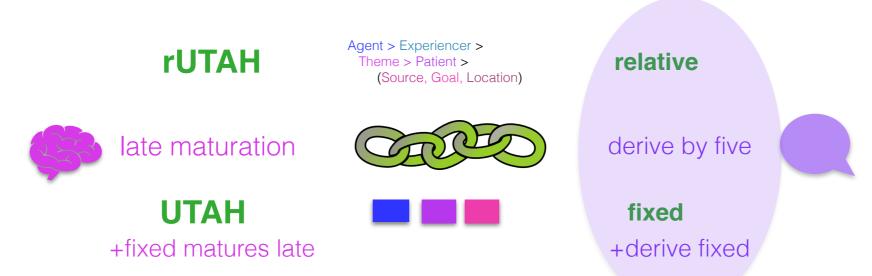


relative

fixed

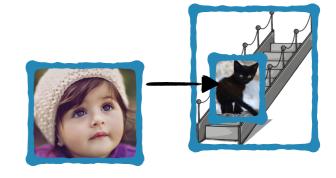
Question: If knowledge is derived from the input, how does that work? We need a concrete proposal for how children could do this.





The Plan

The little girl blicked the kitten on the stairs.



1. Evaluating different linking theory proposals using acquisition modeling



2. Exploring how a linking theory could be derived from children's input



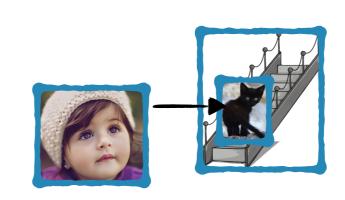
The little girl blicked the kitten on the stairs.





Let's remind ourselves what children are learning about links.





Subject

Object

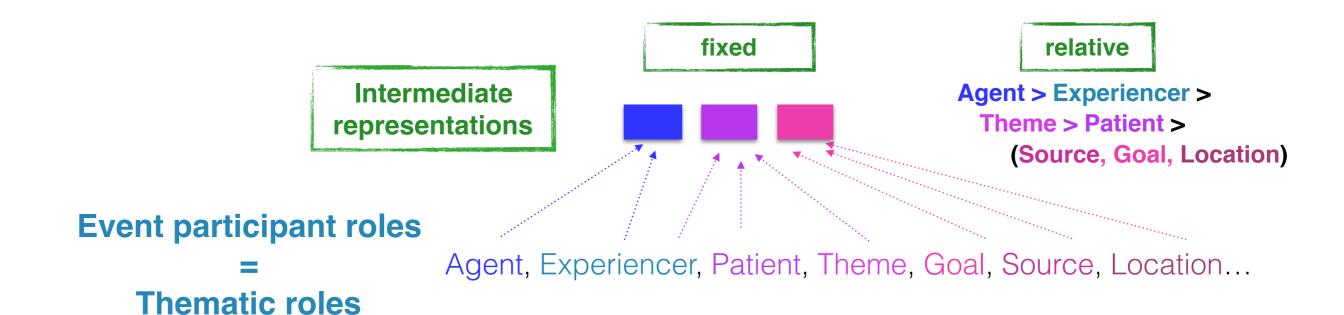
Oblique Object

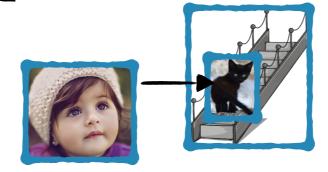
Syntax

The little girl blicked the kitten on the stairs.

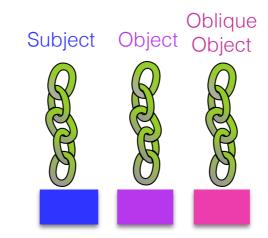


If children have a particular intermediate representation for thematic roles, then they need to link those representations to syntactic positions.





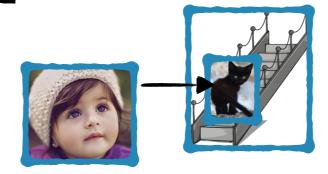
The little girl blicked the kitten on the stairs.



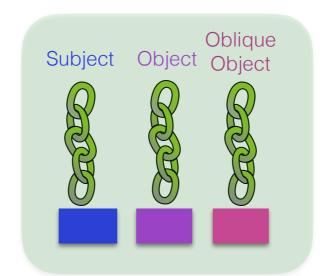
fixed

relative

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)



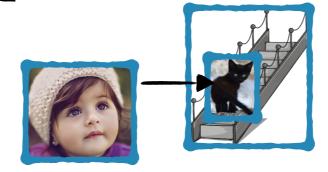
The little girl blicked the kitten on the stairs.



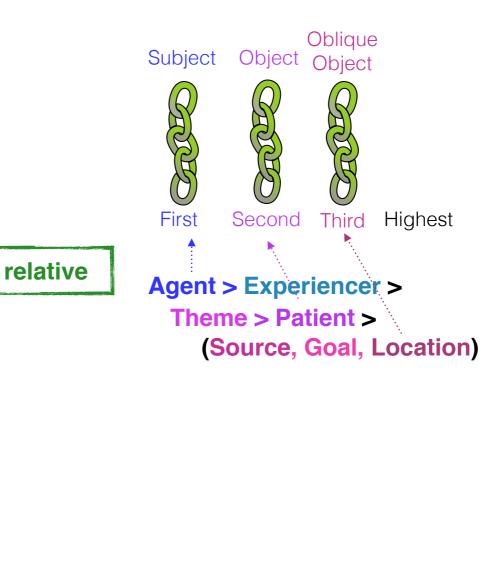
fixed

relative

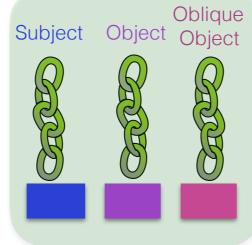
Agent > Experiencer >
Theme > Patient >
(Source, Goal, Location)

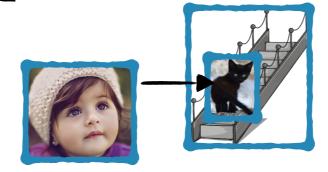


The little girl blicked the kitten on the stairs.

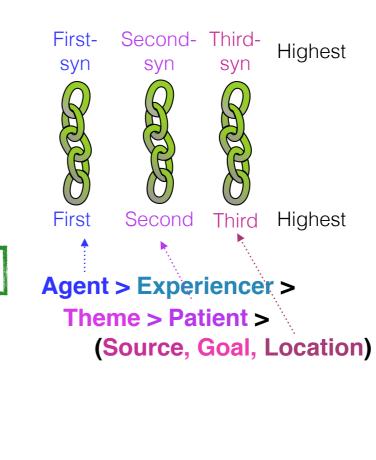


fixed





The little girl blicked the kitten on the stairs.

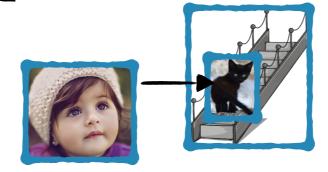


relative

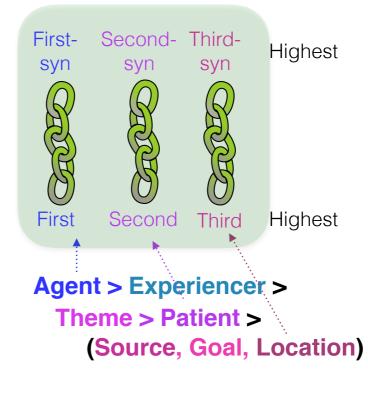
Subject Object Object

Object Object

fixed



The little girl blicked the kitten on the stairs.



relative

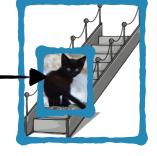
Subject Object Object

Oblique
Object

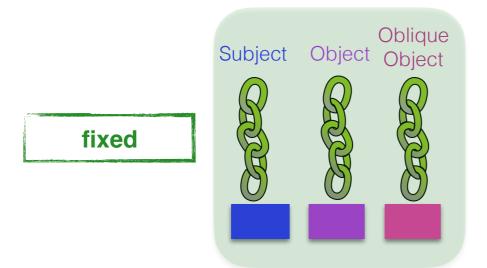
fixed

The little girl blicked the kitten on the stairs.

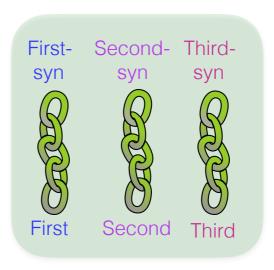




The linking theories we looked at before (UTAH and rUTAH, and their derived-mapping equivalents) treat these as atomic units (3-link theories).

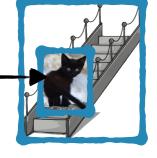


relative



The little girl blicked the kitten on the stairs.





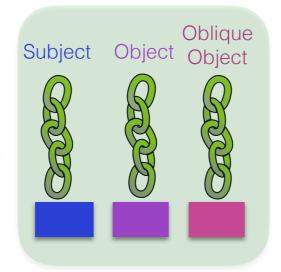
Acquisition task for one 3-link theory:

(1) Derive all three links from the input.

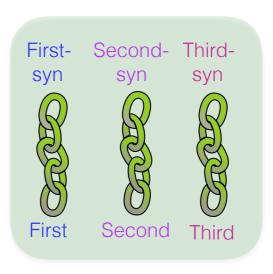
(2) Derive the 3-link linking theory from the input.



fixed



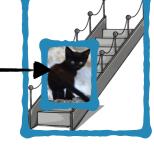
relative



fixed

The little girl blicked the kitten on the stairs.



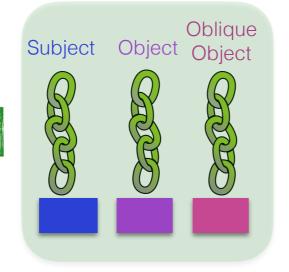


Acquisition task for one 3-link theory:

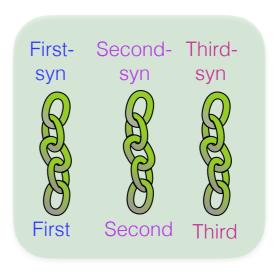
- (1) Derive all three links from the input.
- (2) Derive the 3-link linking theory from the input.



How would this work?



relative



The little girl blicked the kitten on the stairs.

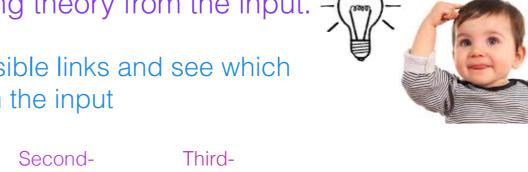


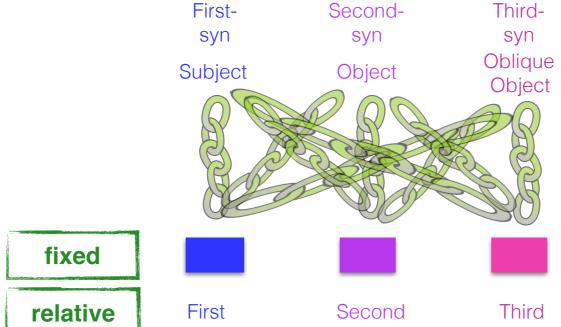


Acquisition task for one 3-link theory:

- (1) Derive all three links from the input.
- (2) Derive the 3-link linking theory from the input.

One way: Consider all possible links and see which ones are reliable enough in the input



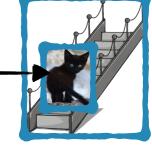


fixed

relative

The little girl blicked the kitten on the stairs.





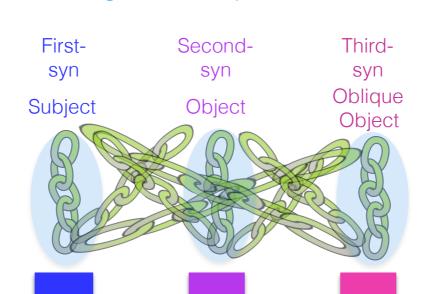
Acquisition task for one 3-link theory:

(1) Derive all three links from the input.

First

(2) Derive the 3-link linking theory from the input.

One way: Consider all possible links and see which ones are reliable enough in the input



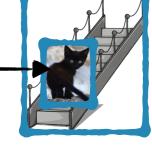
Second

Third



The little girl blicked the kitten on the stairs.

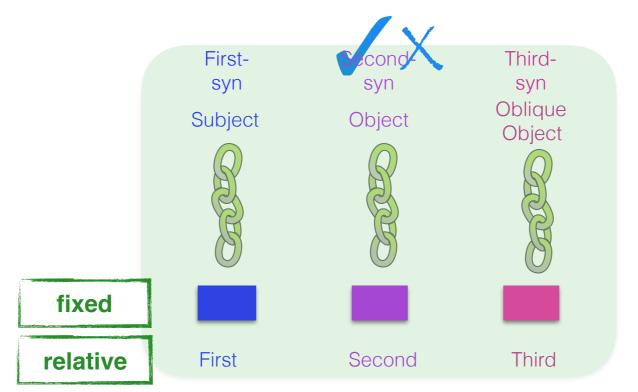




Acquisition task for one 3-link theory:

- (1) Derive all three links from the input.
- (2) Derive the 3-link linking theory from the input.

One way: Then construct the 3-link linking theory from the reliable links and see if the 3-link theory is reliable enough as a unit.



The little girl blicked the kitten on the stairs.

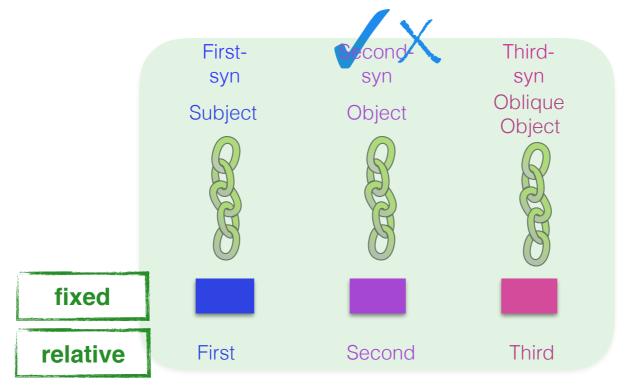




Acquisition task for one 3-link theory:

- (1) Derive all three links from the input.
- (2) Derive the 3-link linking theory from the input.

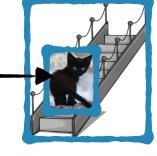






The little girl blicked the kitten on the stairs.



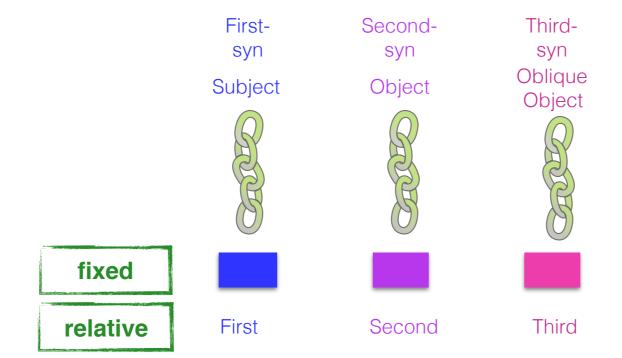


Acquisition task for one 3-link theory:

- (1) Derive all three links from the input.
- (2) Derive the 3-link linking theory from the input

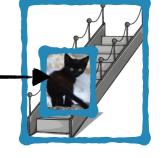


What if we just had three 1-link theories?



The little girl blicked the kitten on the stairs.



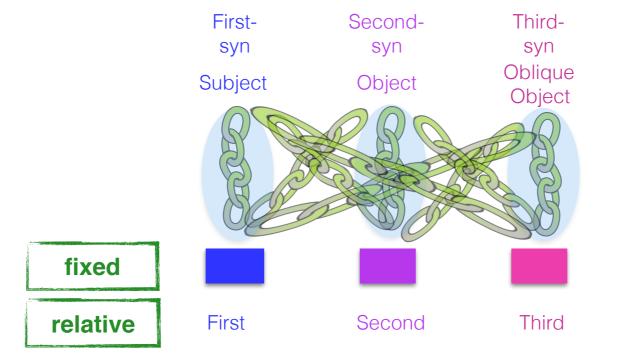


An alternative acquisition task for three 1-link theories:

Derive all three links from the input (and don't worry about

Derive all three links from the input (and don't worry about binding them together — just have three 1-link theories)

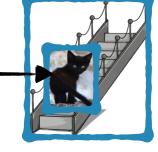




Exploring how a linking theory could be derived from children's input

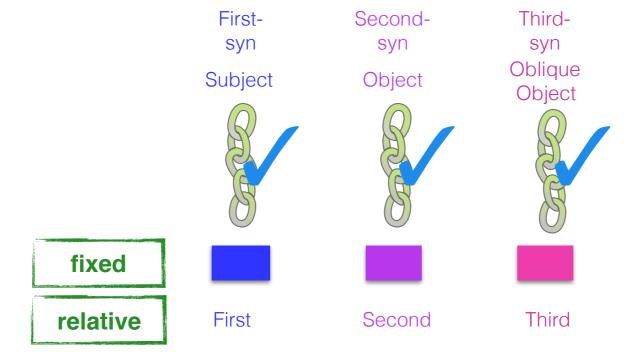
The little girl blicked the kitten on the stairs.





An alternative acquisition task for three 1-link theories: Derive all three links from the input (and don't worry about binding them together — just have three 1-link theories)





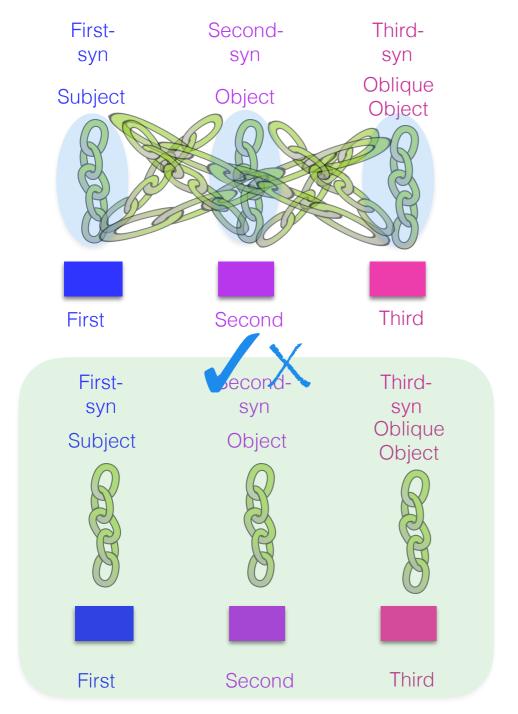
Exploring how a linking theory could be derived from children's input

The little girl blicked the kitten on the stairs.



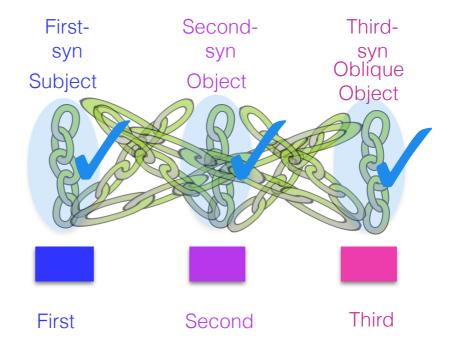








three 1-link theories



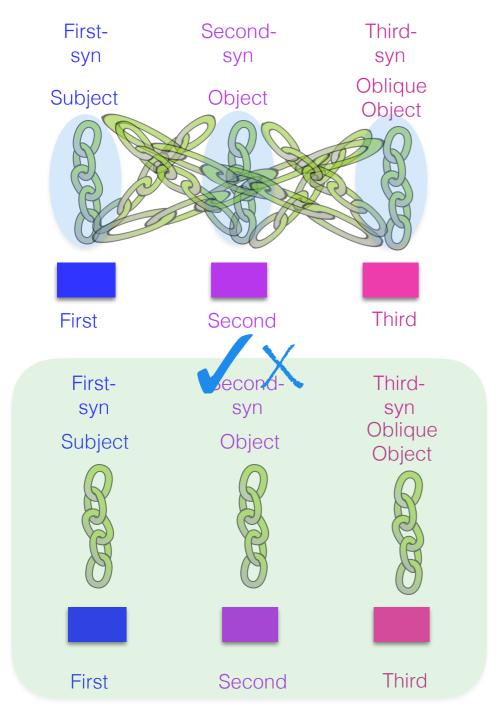
Exploring how a linking theory could be derived from children's input

The little girl blicked the kitten on the stairs.



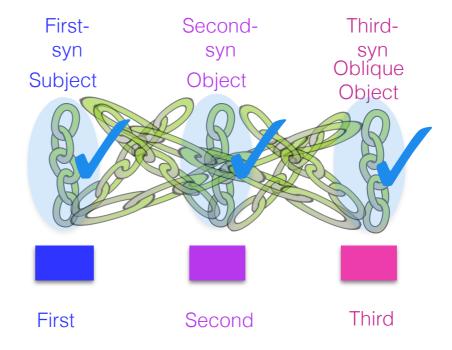


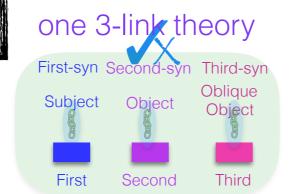




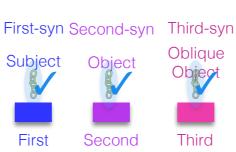
Is either of these possible, given the kind of input children get?

three 1-link theories











five main parts to defining an acquisition task concretely

initial state

data intake

inference

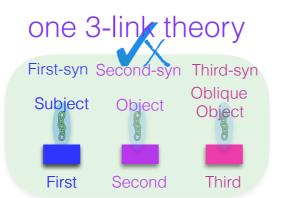


learning period

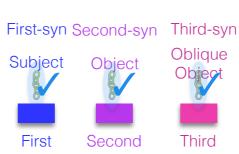
target state

data intake inference

learning period target state



three 1-link theories



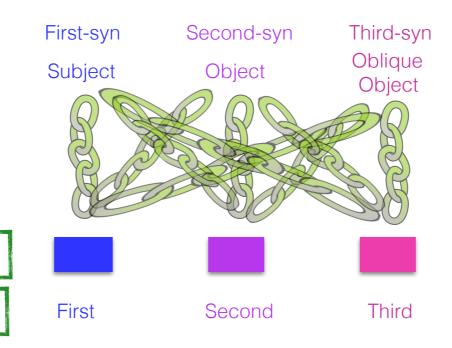


initial state



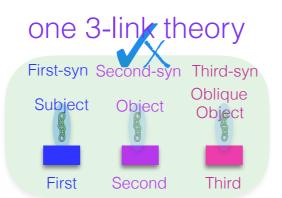
fixed

relative

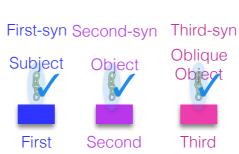


data intake inference

learning period target state



three 1-link theories



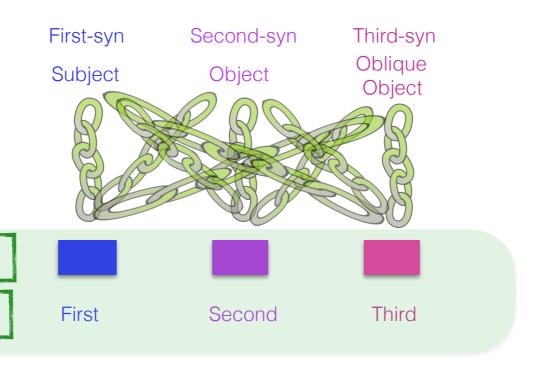


initial state



fixed

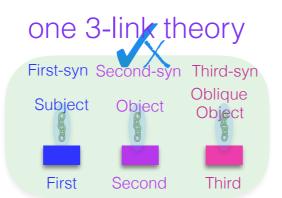
relative



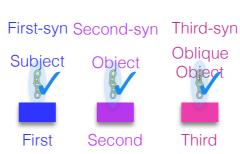
Knowledge of intermediate thematic representation

data intake inference

learning period target state



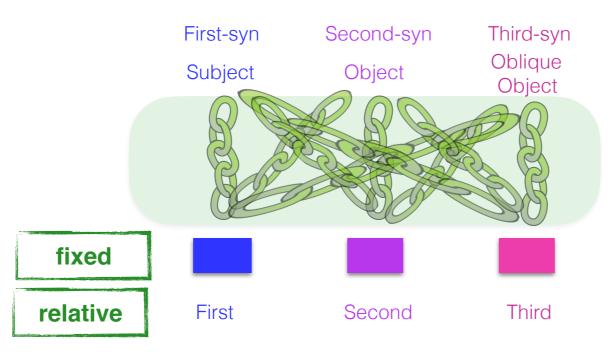
three 1-link theories





initial state

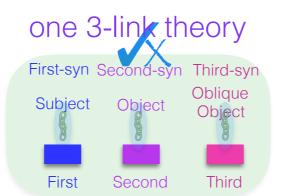




Constraints on possible links

data intake inference

learning period target state





Second

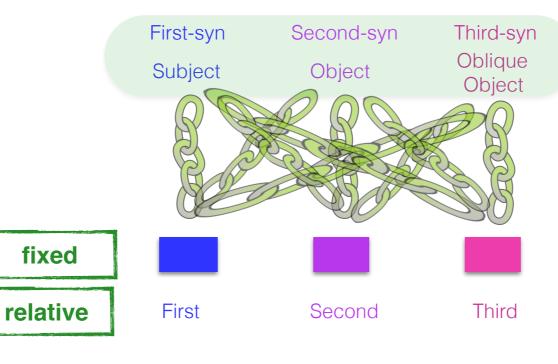
Third

First



initial state



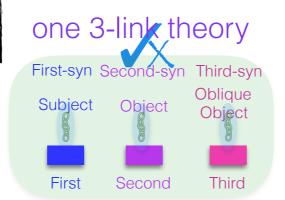


Constraints on possible links:

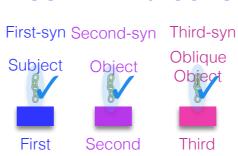
Knowing which syntactic positions are relevant

data intake inference

learning period target state



three 1-link theories





initial state



First-syn Subject Second-syn Object Third-syn Oblique Object Constraints on possible links:

- Knowing which syntactic positions are relevant
- A link can go from role to position...

fixed

relative



First

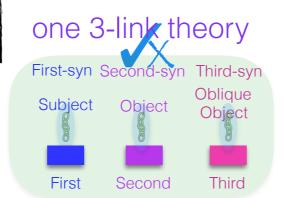


Second



data intake inference

learning period target state



three 1-link theories





initial state



First-syn Subject

Second-syn Object

Oblique Object

Third-syn

Constraints on possible links:

- Knowing which syntactic positions are relevant
- A link can go from role to position...

fixed

relative

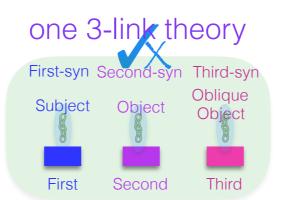
First



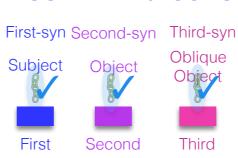
Second

data intake inference

learning period target state



three 1-link theories





initial state



First-syn Subject

Second-syn Object

Third-syn Oblique Object

Knowing which syntactic

Constraints on possible links:

positions are relevant

 A link can go from role to position or from position to role

fixed

relative

First

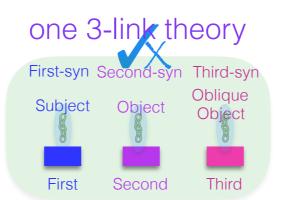


Second

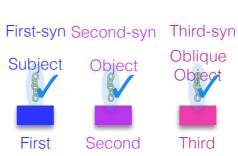


data intake inference

learning period target state



three 1-link theories





initial state



First-syn Subject Second-syn Object



Third-syn



Third

fixed relative

First

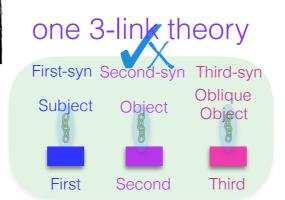
Second

Constraints on possible links:

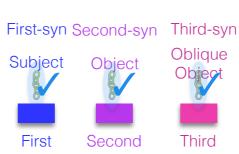
- Knowing which syntactic positions are relevant
- A link can go from role to position or from position to role

data intake inference

learning period target state



three 1-link theories



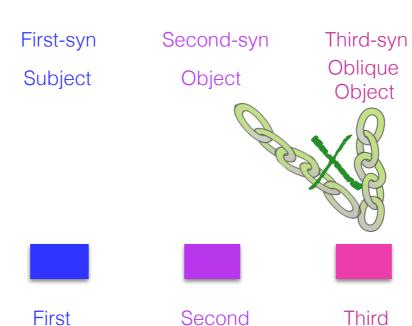


initial state



fixed

relative

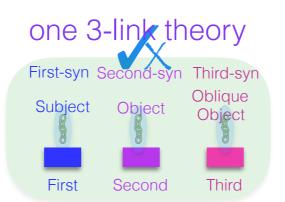


Constraints on possible links:

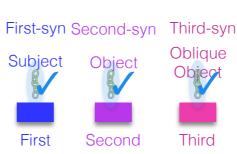
- Knowing which syntactic positions are relevant
- A link can go from role to position or from position to role
- A thematic role can only participate in one link at a time

data intake inference

learning period target state



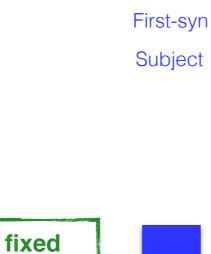
three 1-link theories





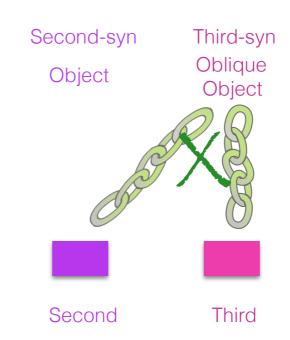
initial state





relative



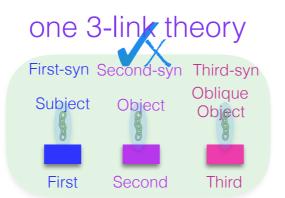


Constraints on possible links:

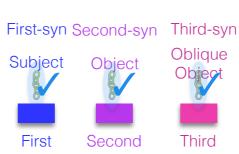
- Knowing which syntactic positions are relevant
- A link can go from role to position or from position to role
- A thematic role can only participate in one link at a time
- A syntactic position can only participate in one link at a time

data intake inference

learning period target state



three 1-link theories



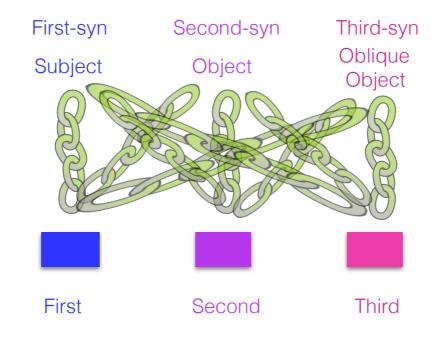






fixed

relative

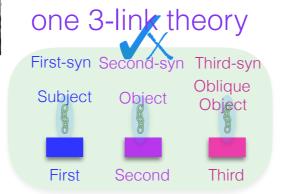




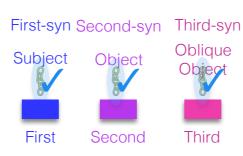
+ whatever abilities are required to do inference

initial state inference

learning period target state



three 1-link theories





Samples of child-directed speech

CHILDES Treebank

Pearl & Sprouse 2013









The little girl blicked the kitten on the stairs.



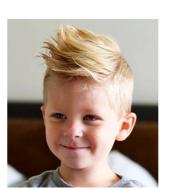
<3yrs

18 and 32 months ~40,000 utterances 239 verbs



<4yrs

18 and 48 months ~51,000 utterances 267 verbs

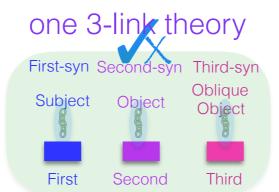


<5yrs

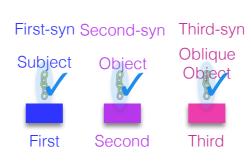
18 and 58 months ~56,500 utterances 284 verbs

initial state inference

learning period target state



three 1-link theories





input that yields data intake



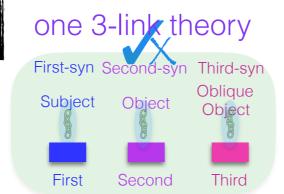




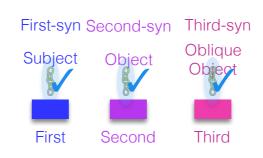
The little girl blicked the kitten on the stairs.



initial state data intake learning period target state



three 1-link theories





inference

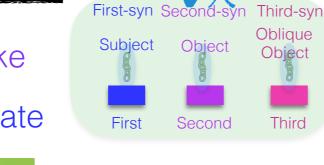


Remember that the acquisition process we imagined hinges on a child perceiving individual links and multilink theories as "**reliable enough**", given the input.



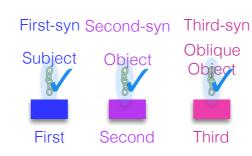


initial state data intake learning period target state



one 3-link theory







inference

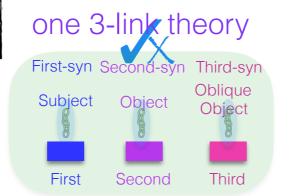


How can "reliable enough" be implemented?

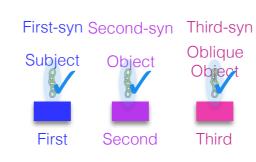




initial state data intake learning period target state



three 1-link theories





inference



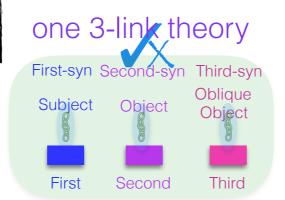
One answer: **The Tolerance Principle** (Yang 2005, 2016)

This principle is derived from considerations of knowledge storage and retrieval in real time, incorporating how frequently individual items occur, the absolute ranking of items by frequency, and serial memory access.

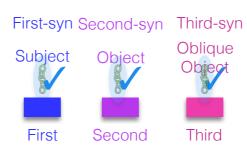




initial state data intake learning period target state



three 1-link theories



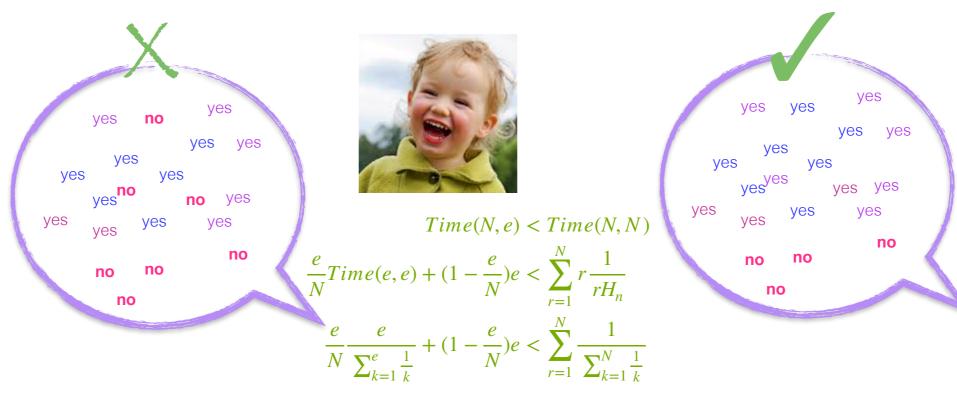


inference

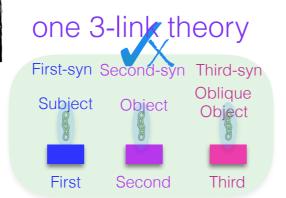


The Tolerance Principle (Yang 2005, 2016)

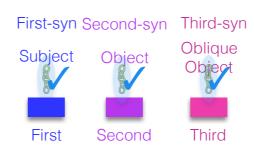
Designed for situations where there are exceptions to a potential rule — provides a **precise threshold** for how many exceptions a potential rule can tolerate before it's no longer worthwhile to have the rule in terms of average retrieval time.



initial state data intake learning period target state



three 1-link theories



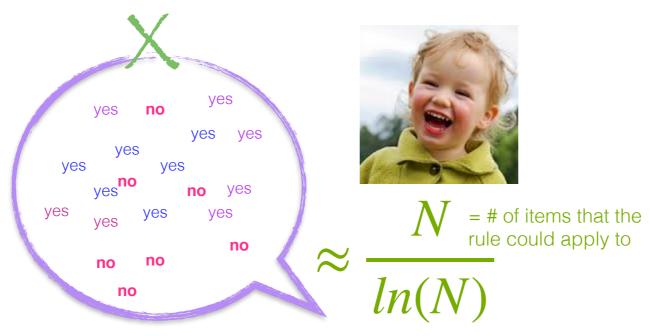


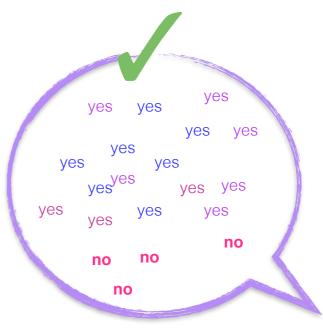
inference



The Tolerance Principle (Yang 2005, 2016)

Designed for situations where there are exceptions to a potential rule — provides a **precise threshold** for how many exceptions a potential rule can tolerate before it's no longer worthwhile to have the rule in terms of average retrieval time.

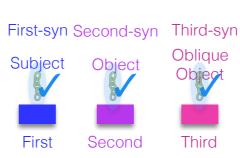




initial state data intake learning period target state









inference



 $\frac{N}{ln(N)}$

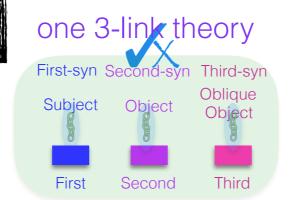
The Tolerance Principle (Yang 2005, 2016)

Here we can use it to evaluate both individual links and multi-link theories.

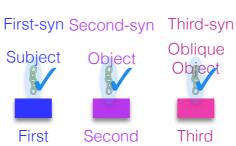
initial state

data intake

target state



three 1-link theories





inference



 $\frac{N}{ln(N)}$



The Tolerance Principle (Yang 2005, 2016)

Here we can use it to evaluate both individual links and multi-link theories.

learning period

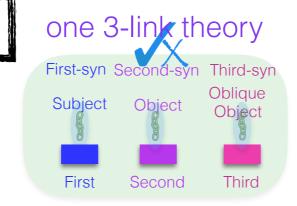
As before, we'll be using an ideal learner model, where the learner applies the Tolerance Principle to all the data available, rather than deploying it with the cognitive limitations and incremental learning restrictions real children have.

Goal: Is it possible to derive the linking theories from realistic child input?

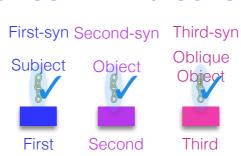


initial state data intake

target state



three 1-link theories





inference



 $\frac{N}{ln(N)}$



How do we evaluate an individual link?

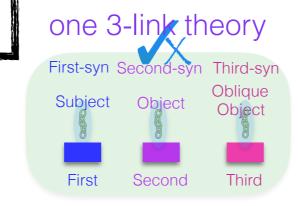
First-syn Subject



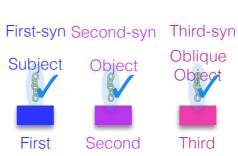
First

initial state data intake

target state









inference



 $\frac{N}{ln(N)}$



How do we evaluate an individual link?

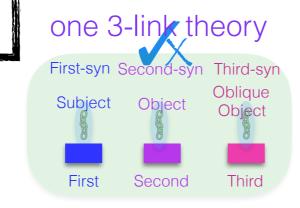
Subject
?

First-syn

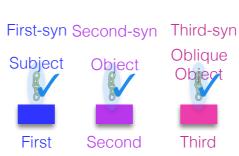
If it goes from role to position, we compare this link to the others that link from this role.

initial state data intake

target state









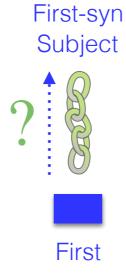
inference



 $\frac{N}{ln(N)}$



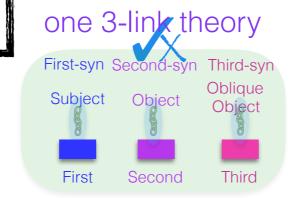
How do we evaluate an individual link?



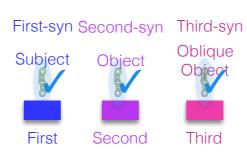
If it goes from role to position, we compare this link to the others that link from this role.

initial state data intake

target state



three 1-link theories





inference

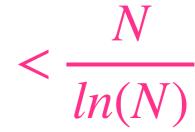




How do we evaluate an individual link?

First-syn Second-syn Third-syn
Subject Object Oblique
Object
First

If it goes from role to position, we compare this link to the others that link from this role (the exceptions to this link).

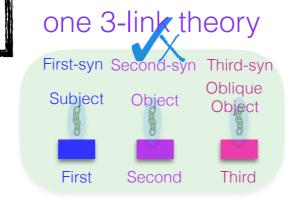


Does it have few enough exceptions according to the child's intake?

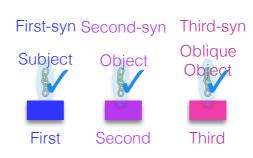


initial state data intake

target state



three 1-link theories





inference





How do we evaluate an individual link?





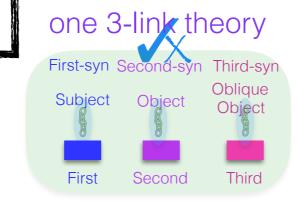


If it goes from position to role, we compare this link to the others that link from this position.

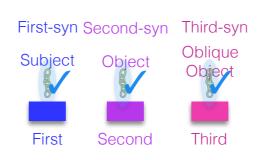


initial state data intake

target state



three 1-link theories



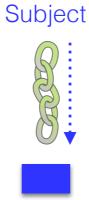


inference





How do we evaluate an individual link?



First

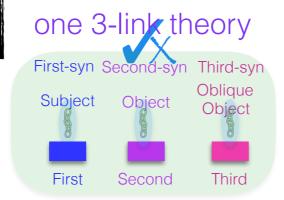
First-syn

If it goes from position to role, we compare this link to the others that link from this position.

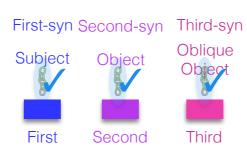


initial state data intake

target state



three 1-link theories



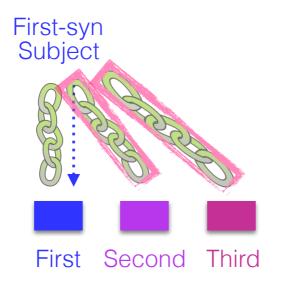




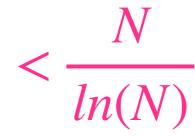




How do we evaluate an individual link?



If it goes from position to role, we compare this link to the others that link from this position (the exceptions to this link).

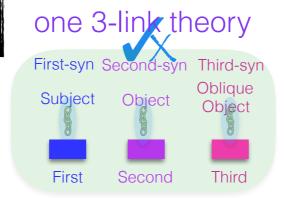


Does it have few enough exceptions according to the child's intake?

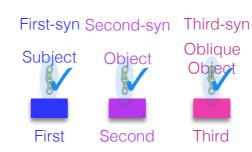


initial state data intake

target state



three 1-link theories

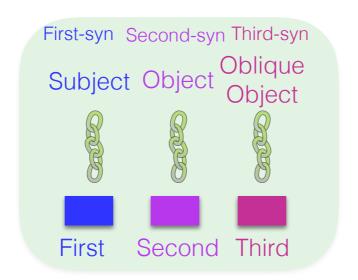




inference



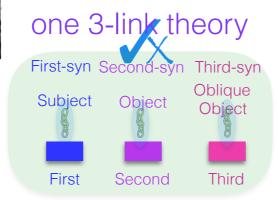
How do we evaluate multi-link theories?



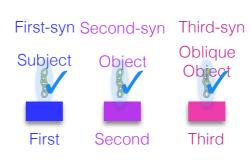


initial state data intake

target state



three 1-link theories

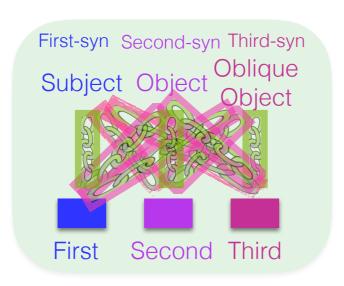




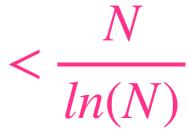
inference



How do we evaluate multi-link theories?



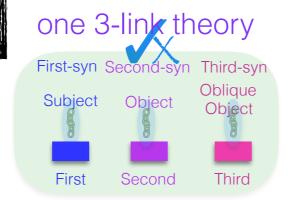
We compare the link instances that follow the multi-link theory against the link instances that don't (the exceptions to this multi-link theory).



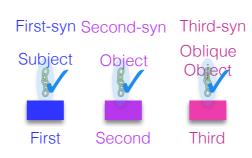
Note: This is a simple binary distinction between links that follow the multi-link theory and links that don't.

Does the 3-link theory have few enough exceptions according to the child's intake?

initial state data intake target state



three 1-link theories





inference



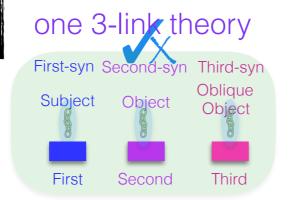


How do we evaluate theories (1-link or 3-link)?

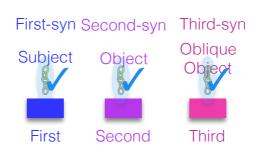


A linking theory should hold for the verb *lexical items* (types).

initial state data intake target state



three 1-link theories





inference



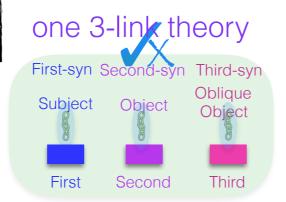


How do we evaluate theories (1-link or 3-link)?

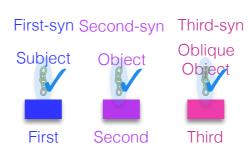
So, a linking theory is evaluated over the verb types — how many obey the linking theory and how many are exceptions?



initial state data intake target state



three 1-link theories





inference





How do we evaluate theories (1-link or 3-link)?

So, a linking theory is evaluated over the verb types — how many obey the linking theory and how many are exceptions?

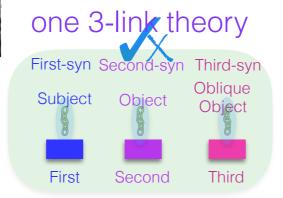


 $<\frac{N}{ln(N)}$ = verb types this theory could apply to

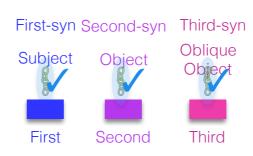
We want the number of verb types that disobey this linking theory to be less than the Tolerance Principle threshold.

initial state data intake

target state



three 1-link theories





inference



How do we evaluate theories (1-link or 3-link)?

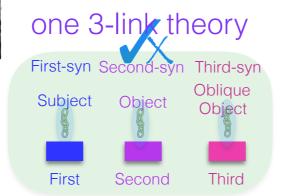


How do we tell if a verb type obeys the linking theory or is an exception?

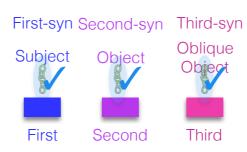


initial state data intake

target state



three 1-link theories





inference





How do we evaluate theories (1-link or 3-link)?

We evaluate that verb type's instances according to whether they follow the linking theory or not.

She's hugging the kitten on the stairs.

I hugged him.

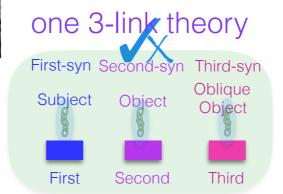
Penguins should be hugged.

Please hug me.

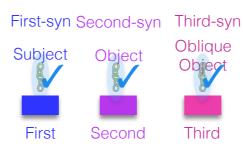
She'll hug the penguin.

Hug the kitten.

initial state data intake target state



three 1-link theories





inference





How do we evaluate theories (1-link or 3-link)?

So, a linking theory is evaluated over the verb type instances — how many obey the linking theory and how many are exceptions?

She's hugging the kitten on the stairs.

I hugged him.

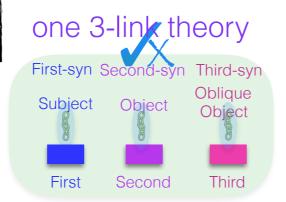
Penguins should be hugged.

Please hug me.

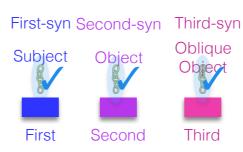
She'll hug the penguin.

Hug the kitten.

initial state data intake target state



three 1-link theories





inference





How do we evaluate theories (1-link or 3-link)?

So, a linking theory is evaluated over the verb type instances — how many obey the linking theory and how many are exceptions?

She's hugging the kitten on the stairs.

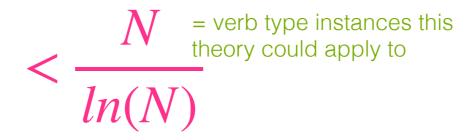
I hugged him.

Penguins should be hugged.

Please hug me.

She'll hug the penguin.

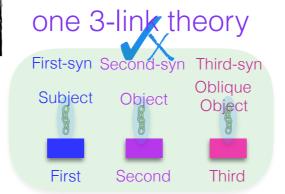
Hug the kitten.



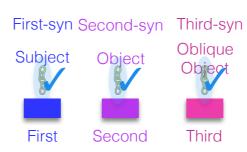
We want the number of verb type instances that disobey this linking theory to be less than the Tolerance Principle threshold.

initial state data intake

target state



three 1-link theories





inference





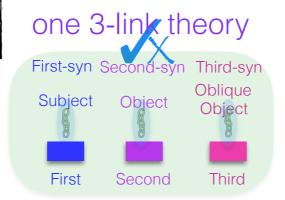
How do we evaluate theories (1-link or 3-link)?

We do this for each verb type, and then we know how many obey the linking theory and how many are exceptions.

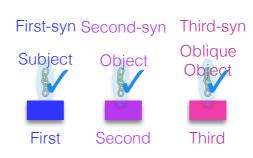


initial state data intake

target state



three 1-link theories





inference





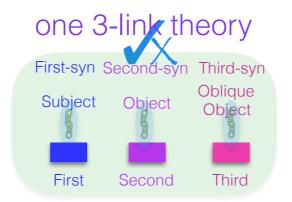
How do we evaluate theories (1-link or 3-link)?

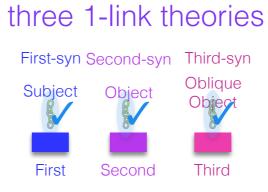
We do this for each verb type, and then we know how many obey the linking theory and how many are exceptions.



 $< \frac{N}{ln(N)}$

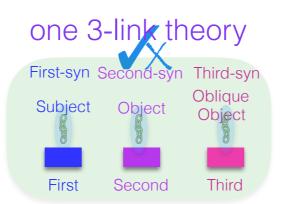
If the exceptions are less than the Tolerance Principle threshold, the linking theory is reliable enough for the verb types.



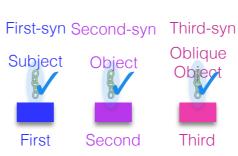








three 1-link theories













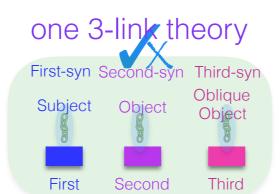
Same results for all three ages.

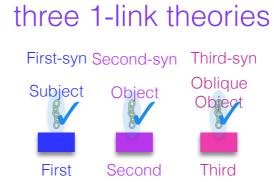












Oblique

Third



Let's look at individual links first.







<3vrs

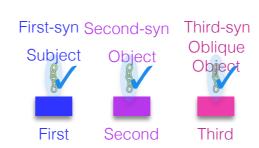
<4yrs

<5yrs

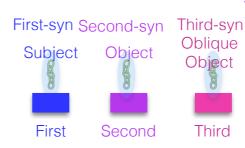


Individual links are the 1-link theories and the building blocks for the 3-link theories.

three 1-link theories



one 3-link theory

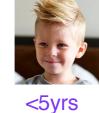




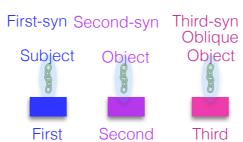


<4yrs

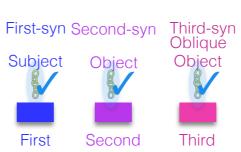




one 3-link theory

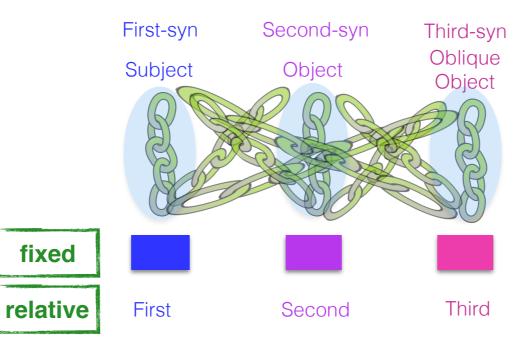


three 1-link theories





Are the individual links reliable enough?



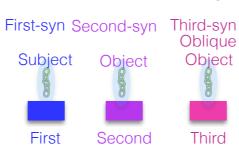




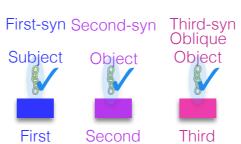


<5yrs

one 3-link theory

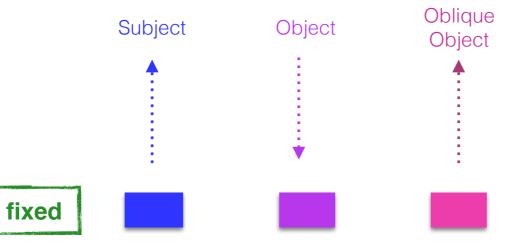


three 1-link theories





Here are the ones that are.







Good: At least one in one direction (role to position or position to role) for each of the three posited links.



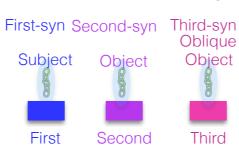




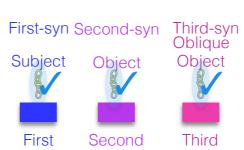


fixed

one 3-link theory

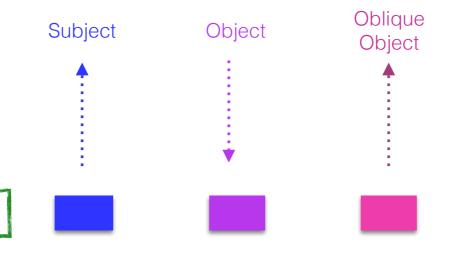


three 1-link theories





Here are the ones that are.







Good: At least one in one direction (role to position or position to role) for each of the three posited links.

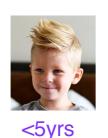
Good: No extraneous links are reliable enough.





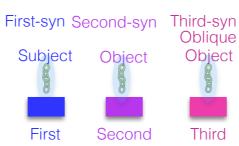




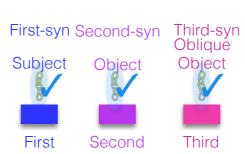


fixed

one 3-link theory

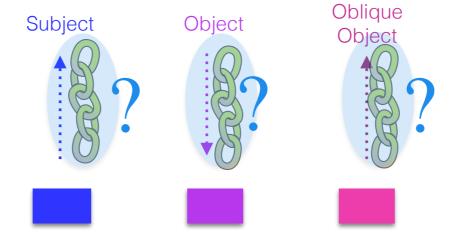


three 1-link theories





Here are the ones that are.







...but none have a reliable link in both directions, and it's not clear if both directions are needed to posit a link for the linking theory.



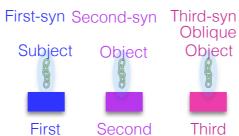






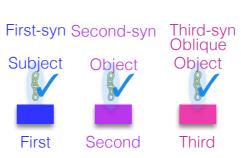
<5yrs

one 3-link theory



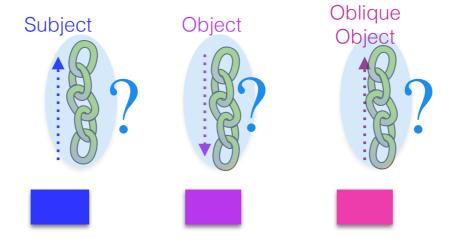


three 1-link theories





Here are the ones that are.







fixed

Only the most liberal approach to positing theories from links (one link in either direction is sufficient) would allow a child to posit the appropriate 1-link theories or the appropriate building blocks for the 3-link theory.

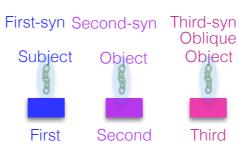




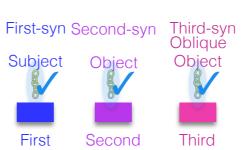




one 3-link theory



three 1-link theories







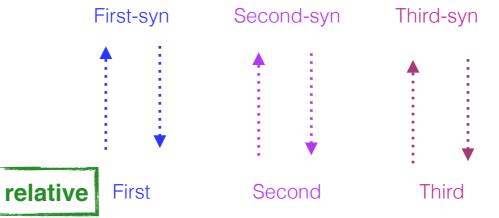






fixed



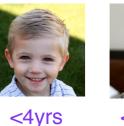


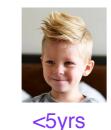


This contrasts with the relative thematic system, where links in both directions are reliable enough (and there are also no extraneous links).

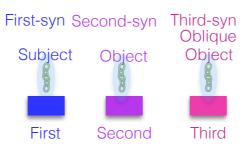




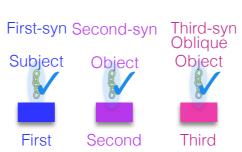




one 3-link theory











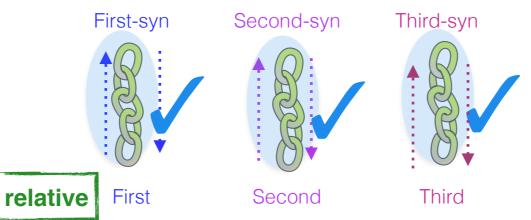








Here are the ones that are.

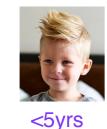




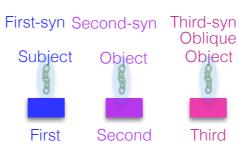
So more conservative strategies for positing theories from links (e.g., needing a link in both directions) would also posit the appropriate theories or building blocks.



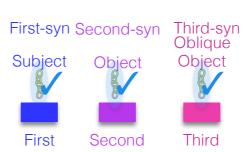




one 3-link theory



three 1-link theories







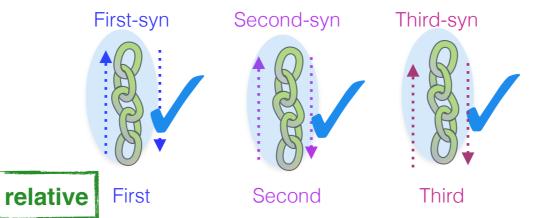






fixed

Here are the ones that are.





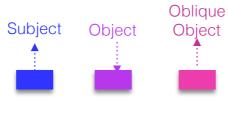
This means relying on relative thematic representations is more robust to different learning scenarios.





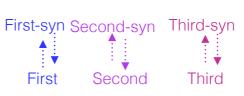












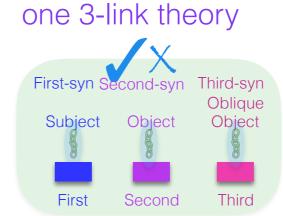






But what about the 3-link theories?

If in fact the appropriate building blocks are composed into the appropriate 3-link theories, are those theories reliable enough?



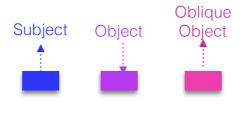






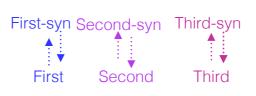










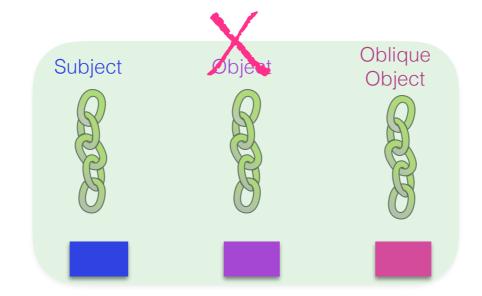








one 3-link theory



fixed



It turns out that the 3-link theory relying on a fixed thematic representation isn't reliable enough — not enough verb types obey it.

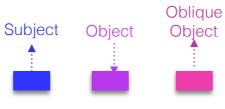


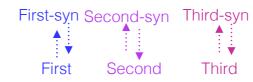














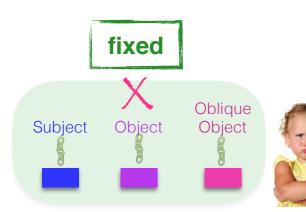


fixed

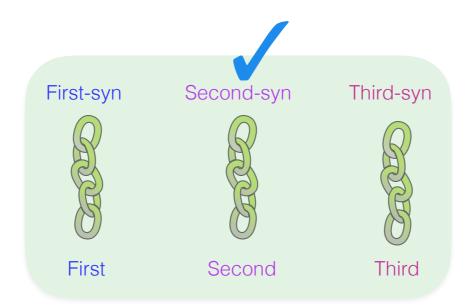




relative



one 3-link theory



relative



Meanwhile, the 3-link theory using the relative thematic representation is reliable enough as a unit.



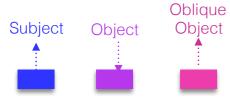




<3yrs

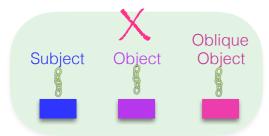
<4yrs

<5yrs



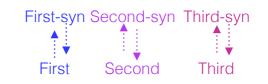






Takeaway 1: Relying on a relative thematic representation makes it **easier** to derive three 1-link theories of the kind compatible with those that linguists have theorized (rUTAH).









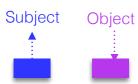






<3yrs



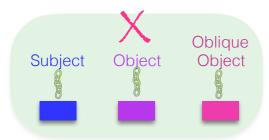




harder

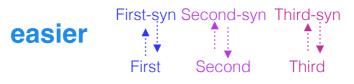






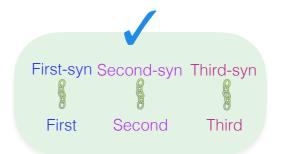
Takeaway 2: Relying on a relative thematic representation is the **only** way to derive a 3-link theory of the kind linguists have theorized (rUTAH).

















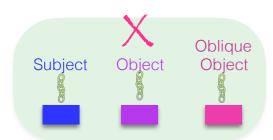
<3yrs

<4yrs

<5yrs

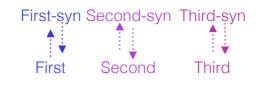
Subject Object Object



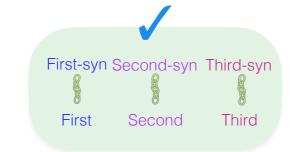


Bigger takeaway: Acquisition support for relative over fixed.

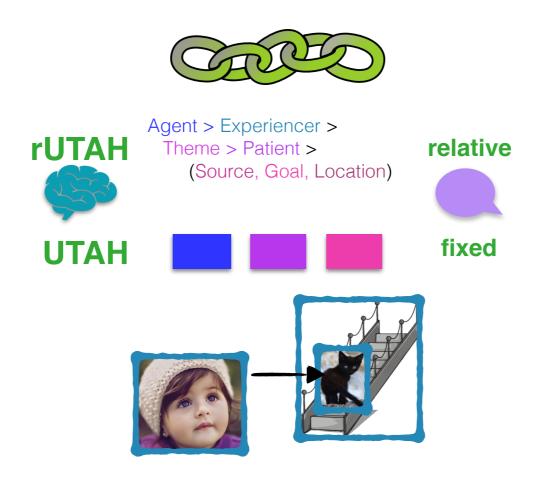
Whether we think the linking theories that humans use are multi-link theories or multiple 1-link theories, it seems that English children would need to rely on a relative thematic representation if they're going to derive these linking theories from their input.







The little girl blicked the kitten on the stairs.



The little girl blicked the kitten on the stairs.

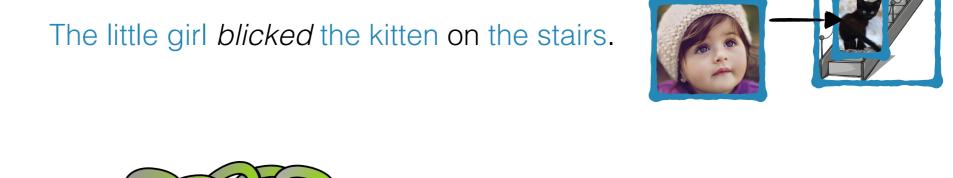


Linking theory proposals relying on innate knowledge require late maturation if they're going to be compatible with what we know about English children's developing verb knowledge.











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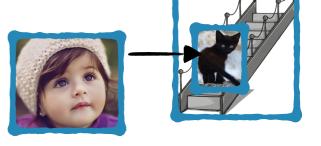
Linking theory proposals relying on derived knowledge are also compatible with what we know about English children's developing verb knowledge.

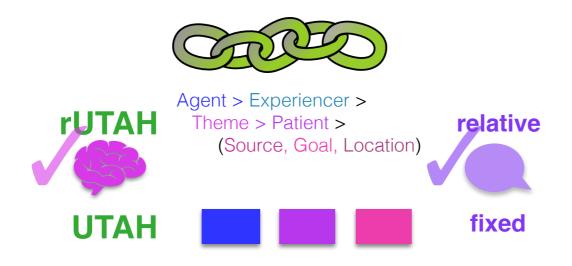






The little girl blicked the kitten on the stairs.





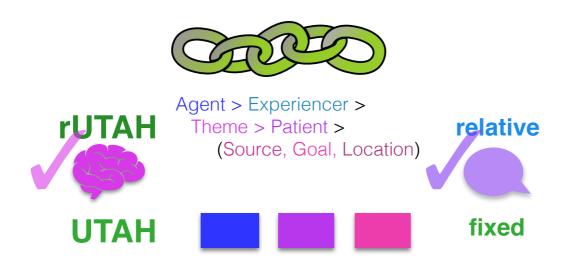
Linking theory proposals relying on derived knowledge are also compatible with what we know about English children's developing verb knowledge.





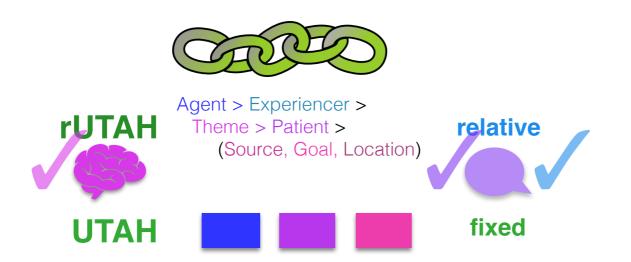


The little girl blicked the kitten on the stairs.



We provided an existence proof for how linking knowledge could be derived from realistic English child input. It only works for learners relying on relative thematic representations.

The little girl blicked the kitten on the stairs.

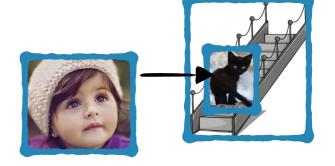


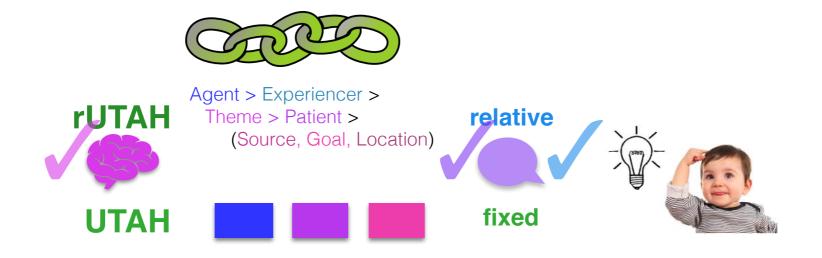
We provided an existence proof for how linking knowledge could be derived from realistic English child input. It only works for learners relying on relative thematic representations.

This can be interpreted as an argument from acquisition for theories of relative thematic representations over theories of fixed thematic representations.



The little girl blicked the kitten on the stairs.

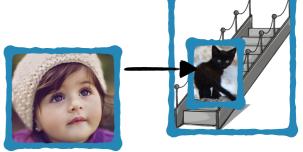


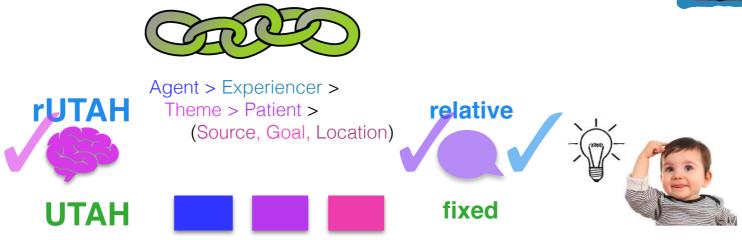


So now what?



The little girl blicked the kitten on the stairs.

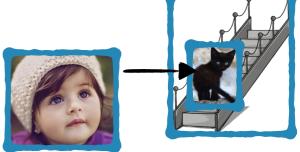


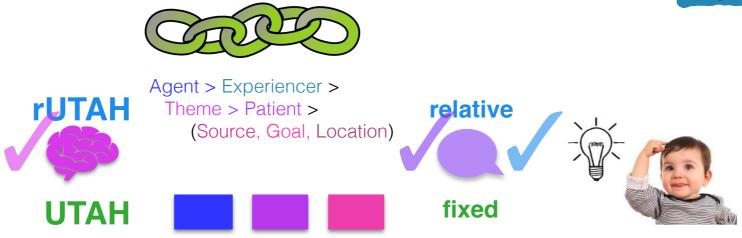


(1) A broader assessment of children's verb class knowledge



The little girl blicked the kitten on the stairs.





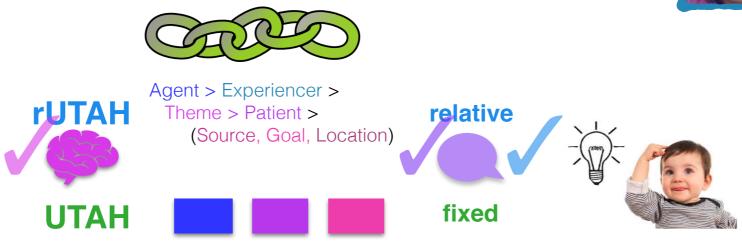
(1) A broader assessment of children's verb class knowledge



This will allow us to further validate our acquisition modeling results for these theoretical proposals.

The little girl blicked the kitten on the stairs.





(1) A broader assessment of children's verb class knowledge



Children's input

Children's known behavior



239 verbs

15 classes of 60 verbs <4yrs

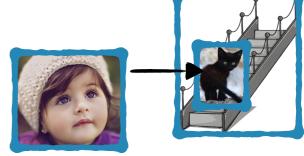
267 verbs

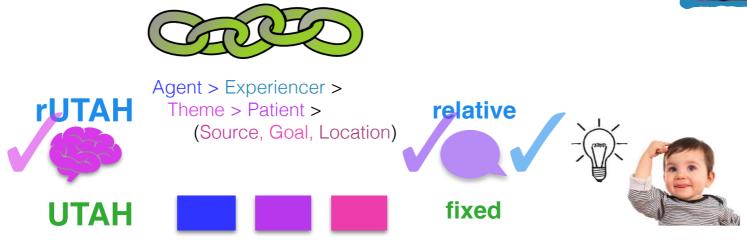
23 classes of 76 verbs <5yrs

284 verbs

24 classes of 82 verbs

The little girl blicked the kitten on the stairs.





(1) A broader assessment of children's verb class knowledge

<3yrs

Children's input

Children's known behavior

239 verbs

15 classes of 60 verbs



267 verbs

23 classes of 76 verbs

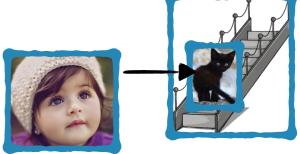


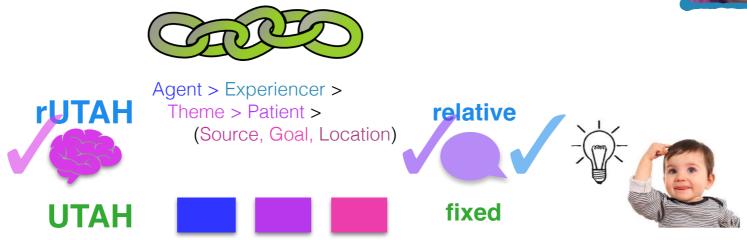
284 verbs

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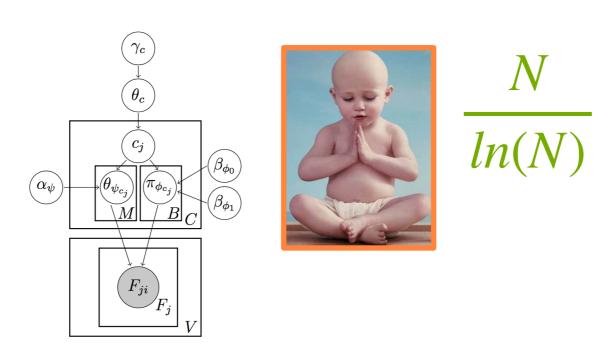
There are nearly 200 verbs in each age that we have acquisition model predictions for based on children's input but no behavioral data for.

The little girl blicked the kitten on the stairs.

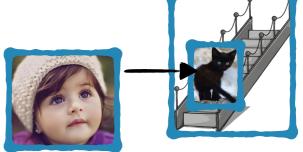


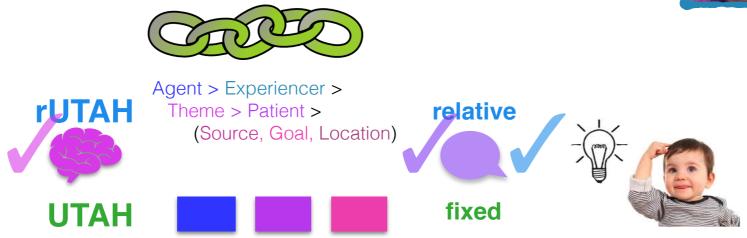


(2) Models incorporating more cognitively plausible assumptions

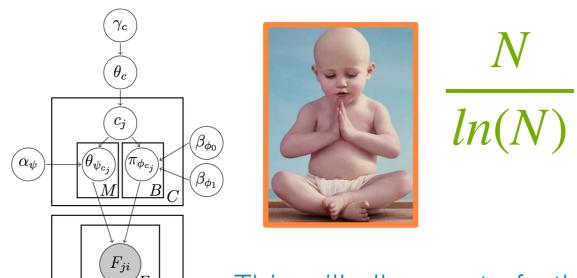


The little girl blicked the kitten on the stairs.



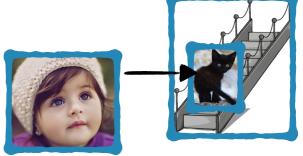


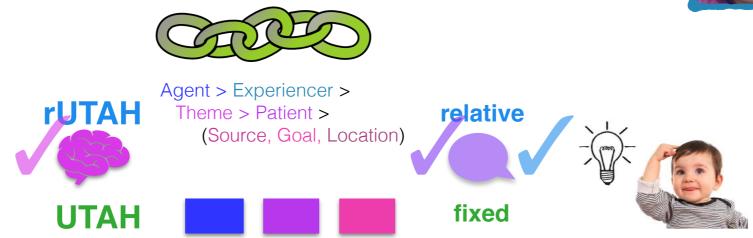
(2) Models incorporating more cognitively plausible assumptions



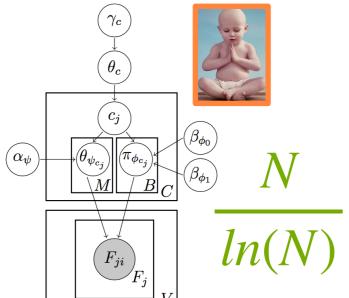
This will allow us to further validate our acquisition modeling results for these theoretical proposals.

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(2) Models incorporating more cognitively plausible assumptions



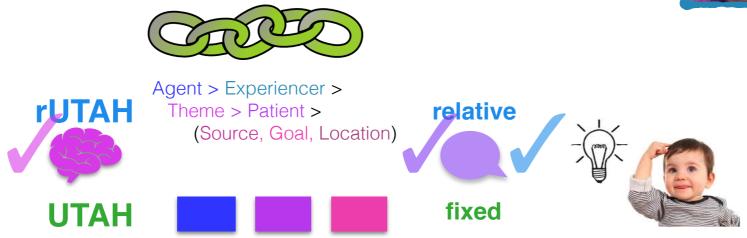
about intake & inference: +memory & processing limitations



Is what's useful actually useable by children?

The little girl blicked the kitten on the stairs.





(2) Models incorporating more cognitively plausible assumptions



about developing grammar: +incorporating additional age-appropriate information

"It seemed to be right"

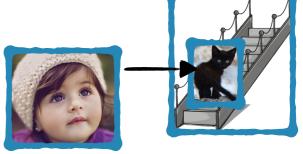
NP __ IP-finite ---> NPraised __ [IP-finite ___NP]

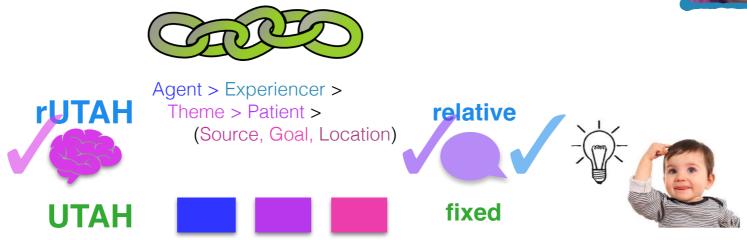






The little girl blicked the kitten on the stairs.





(2) Models incorporating more cognitively plausible assumptions



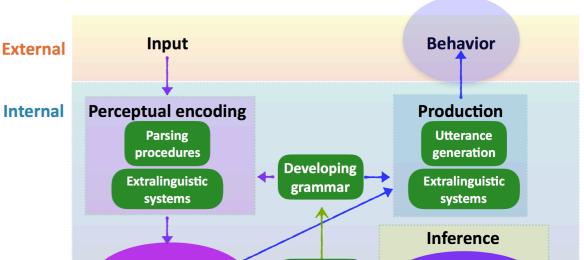






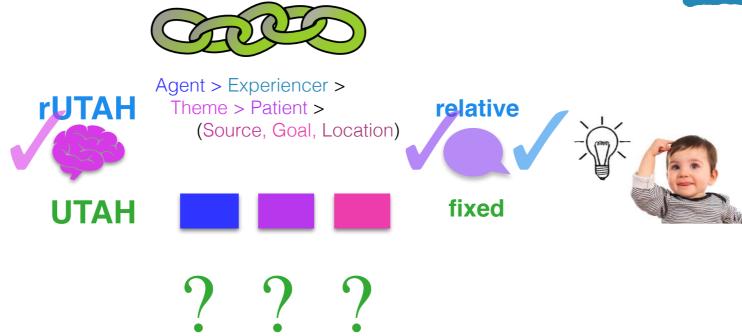
about target state:
+predicting behavioral data
available from experiments





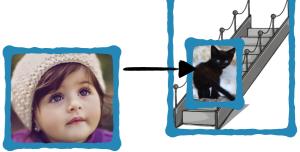
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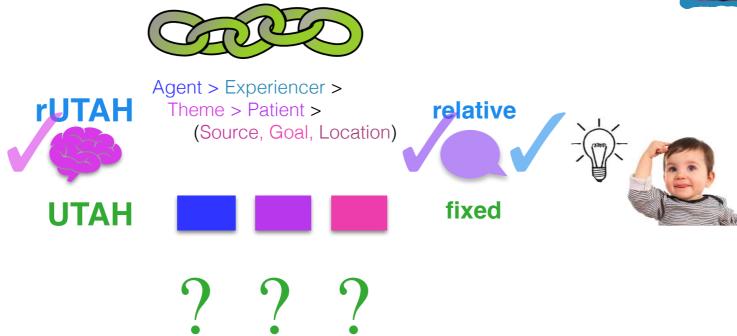




(3) Are there other theoretical options for linking thematic role information to syntactic structure that are compatible with what we know about development?

The little girl blicked the kitten on the stairs.



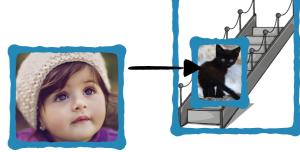


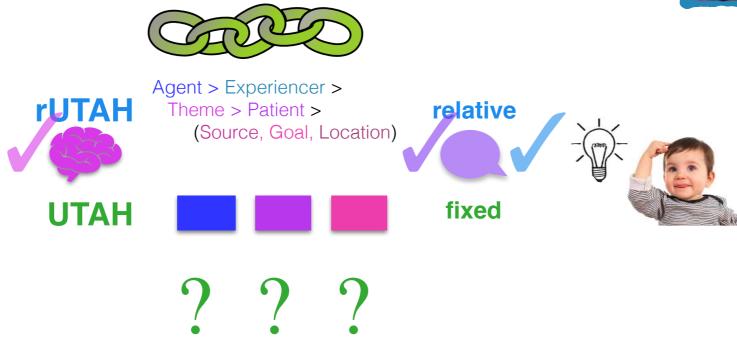
(3) Are there other theoretical options for linking thematic role information to syntactic structure that are compatible with what we know about development?

We can use these acquisition modeling approaches to investigate them.



The little girl blicked the kitten on the stairs.





These acquisition modeling approaches allow us to connect theories of linguistic representation with theories of language development and so understand more about both.

Jon Sprouse



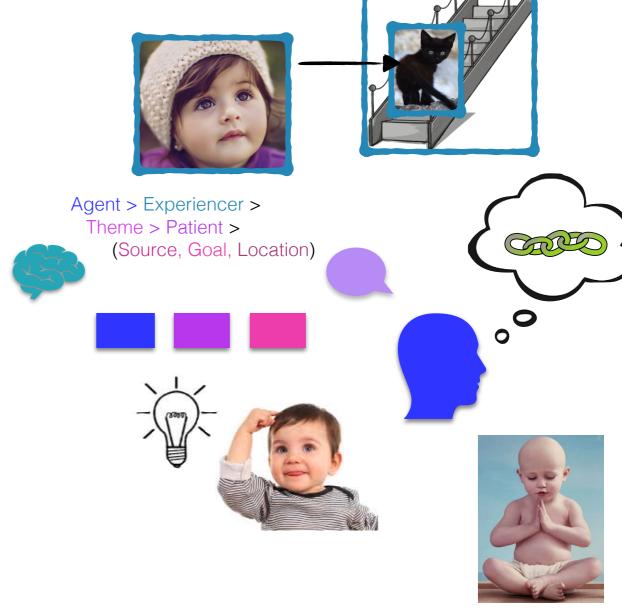
Thank you!

IMBS @ UCI 2018

MathPsych 2017
UCI Linguistics 2017
SynLinks workshop 2016
McGill Linguistics 2016







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